



INSTITUTE OF AERONAUTICAL ENGINEERING

(Autonomous)

Dundigal, Hyderabad -500 043

ELECTRICAL AND ELECTRONICS ENGINEERING

COURSE DESCRIPTOR

Course Title	AC MACHINES				
Course Code	AEE007				
Programme	B.Tech				
Semester	IV	EEE			
Course Type	Core				
Regulation	IARE - R16				
Course Structure	Theory			Practical	
	Lectures	Tutorials	Credits	Laboratory	Credits
	3	1	4	3	2
Chief Coordinator	Mr. K Devender Reddy, Assistant Professor				
Course Faculty	Mr. K Devender Reddy, Assistant Professor Mr. P Mabu Hussain, Assistant Professor				

I. COURSE OVERVIEW:

This course deals with the construction, principle, classification, starting methods and different types of testing methods on AC machines including single phase, three phase induction motors and synchronous motors, this course also enlightens the students with the construction, principle, classification and different testing methods of synchronous generator.

II. COURSE PRE-REQUISITES:

Level	Course Code	Semester	Prerequisites
UG	AEE004	III	DC Machines and transformers

III. MARKS DISTRIBUTION:

Subject	SEE Examination	CIA	Total Marks
AC Machines	70 Marks	30 Marks	100

IV. DELIVERY / INSTRUCTIONAL METHODOLOGIES:

✓	Chalk & Talk	✓	Quiz	✓	Assignments	✗	MOOCs
✓	LCD / PPT	✓	Seminars	✗	Mini Project	✗	Videos
✗	Open Ended Experiments						

V. EVALUATION METHODOLOGY:

The course will be evaluated for a total of 100 marks, with 30 marks for Continuous Internal Assessment (CIA) and 70 marks for Semester End Examination (SEE). Out of 30 marks allotted for CIA during the semester, marks are awarded by taking average of two CIA examinations or the marks scored in the make-up examination.

Semester End Examination (SEE): The SEE is conducted for 70 marks of 3 hours duration. The syllabus for the theory courses is divided into five units and each unit carries equal weightage in terms of marks distribution. The question paper pattern is as follows. Two full questions with “either” or “choice” will be drawn from each unit. Each question carries 14 marks. There could be a maximum of two sub divisions in a question.

The emphasis on the questions is broadly based on the following criteria:

50 %	To test the objectiveness of the concept.
50 %	To test the analytical skill of the concept OR to test the application skill of the concept.

Continuous Internal Assessment (CIA):

CIA is conducted for a total of 30 marks (Table 1), with 25 marks for Continuous Internal Examination (CIE), 05 marks for Quiz/ Alternative Assessment Tool (AAT).

Table 1: Assessment pattern for CIA

Component	Theory		Total marks
	CIE Exam	Quiz / AAT	
CIA marks	25	05	30

Continuous Internal Examination (CIE):

Two CIE exams shall be conducted at the end of the 8th and 16th week of the semester respectively. The CIE exam is conducted for 25 marks of 2 hours duration consisting of two parts. Part–A shall have five compulsory questions of one mark each. In part–B, four out of five questions have to be answered where, each question carries 5 marks. Marks are awarded by taking average of marks scored in two CIE exams.

Quiz / Alternative Assessment Tool (AAT):

Two Quiz exams shall be online examination consisting of 25 multiple choice questions and are to be answered by choosing the correct answer from a given set of choices (commonly four). Marks shall be awarded considering the average of two quizzes for every course. The AAT may include seminars, assignments, term paper, open ended experiments, five minutes video and MOOCs.

VI. HOW PROGRAM OUTCOMES ARE ASSESSED:

Program Outcomes (POs)		Strength	Proficiency assessed by
PO 1	Engineering knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.	3	Seminars
PO 2	Problem analysis: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences	2	Term paper
PO 4	Conduct investigations of complex problems: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.	2	Laboratory experiments

3 = High; 2 = Medium; 1 = Low

VII. HOW PROGRAM SPECIFIC OUTCOMES ARE ASSESSED:

Program Specific Outcomes (PSOs)		Strength	Proficiency assessed by
PSO 1	Problem-Solving Skills: Exploit the knowledge of high voltage engineering in collaboration with power systems in innovative, dynamic and challenging environment, for the research based team work.	-	-
PSO 2	Professional Skills: Identify the scientific theories, ideas, methodologies and the new cutting edge technologies in renewable energy engineering, and use this erudition in their professional development and gain sufficient competence to solve the current and future energy problems universally.	2	Seminars
PSO 3	Modern Tools in Electrical Engineering: Comprehend the technologies like PLC, PMC, process controllers, transducers and HMI one can analyze, design electrical and electronics principles to install, test, and maintain power system and industrial applications.	-	-

3 = High; 2 = Medium; 1 = Low

VIII. COURSE OBJECTIVES (COs):

The course should enable the students to:	
I	Discuss the construction, working and characteristics of three phase induction motor and synchronous motor.
II	Illustrate the equivalent circuit and speed control methods of three phase induction motors.
III	Outline the working and parallel operation of alternators.
IV	Evaluate synchronous impedance and voltage regulation of synchronous machine.

IX. COURSE LEARNING OUTCOMES (CLOs):

CLO Code	CLO's	At the end of the course, the student will have the ability to:	PO's mapped	Strength of mapping
CAEE007.01	CLO 1	Understand the principle of operation and constructional features of three phase induction motor	PO1	3
CAEE007.02	CLO 2	Understand production of torque and modes of three phase induction motor operation	PO2	2
CAEE007.03	CLO 3	Understand the different types of torques, various losses, efficiency and torque- slip characteristics of three phase induction motor operation	PO2	2
CAEE007.04	CLO 4	Describe no-load and blocked rotor test of three phase induction motor for calculating the equivalent circuit parameters.	PO1,PO2, PO4	3
CAEE007.05	CLO 5	Describe circle diagram of three phase induction motor and concept of induction generator	PO1,PO2, PO4	3
CAEE007.06	CLO 6	Understand the starting and speed control methods of three phase induction motor	PO2,PO4	2
CAEE007.07	CLO 7	Understand the principle of operation and constructional features and different types of armature windings of synchronous alternator	PO1	3
CAEE007.08	CLO 8	Understand the phasor diagrams of alternator on no-load, load and analyze the harmonics and its suppression methods.	PO2	2
CAEE007.09	CLO 9	Describe the different methods for calculating the voltage regulation	PO2	2

CLO Code	CLO's	At the end of the course, the student will have the ability to:	PO's mapped	Strength of mapping
CAEE007.10	CLO 10	Understand the concept of parallel operation and slip test	PO1, PO2	2
CAEE007.11	CLO 11	Understand the principle of operation, constructional features and starting methods of synchronous motor	PO1	3
CAEE007.12	CLO 12	Describe the importance of power, excitation circles and effect of varying different parameters on synchronous motor performance	PO2	3
CAEE007.13	CLO 13	Understand the concept of constructing V, inverted V curves and synchronous condenser	PO2,PO4, PSO2	2
CAEE007.14	CLO 14	Understand the principle of operation and constructional features of single phase induction motor and starting methods for single phase induction motor	PO1, PO2	2
CAEE007.15	CLO 15	Describe the torque-speed characteristics of single phase induction motor and equivalent circuit.	PO2	2
CAEE007.16	CLO 16	Apply the concept of electromagnetic and electrostatic fields to solve real time world applications.	PO1,PO2	3
CAEE007.17	CLO 17	Explore the knowledge and skills of employability to succeed in national and international level competitive examinations.	PO1	3

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X. MAPPING COURSE LEARNING OUTCOMES LEADING TO THE ACHIEVEMENT OF PROGRAM OUTCOMES AND PROGRAM SPECIFIC OUTCOMES:

CLOs	Program Outcomes (POs)												Program Specific Outcomes (PSOs)		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CLO 1	3														
CLO 2		3													
CLO 3		2													
CLO 4	3	2		3											
CLO 5		2		3											
CLO 6	3	2		3										2	
CLO 7	3														
CLO 8		2													
CLO 9		2		3											
CLO 10	3	2		3										2	
CLO 11	2														
CLO 12		3												2	
CLO 13	2			3										2	
CLO 14	2			3											
CLO 15		2													
CLO 16	2	2													
CLO 17						2									

3 = High; 2 = Medium; 1 = Low

XI. ASSESSMENT METHODOLOGIES – DIRECT

CIE Exams	PO1, PO2, PO4	SEE Exams	PO1, PO2, PO4	Assignments	PO1, PO2, PO4	Seminars	PO1
Laboratory Practices	PO4	Student Viva	PO1, PO2, PO4	Mini Project	-	Certification	-
Term Paper	PO2						

XII. ASSESSMENT METHODOLOGIES - INDIRECT

✓	Early Semester Feedback	✓	End Semester OBE Feedback
✗	Assessment of Mini Projects by Experts		

XIII. SYLLABUS

UNIT - I	THREE PHASE INDUCTION MOTORS
Three phase induction motors: Introduction, construction, types of induction motors, slip and frequency of rotor currents, rotor MMF and production of torque, equivalent circuit, power across air gap, torque and power output, torque slip characteristics, generating and braking modes, maximum (breakdown) torque, starting torque, maximum power output, problems.	
UNIT - II	TESTING AND SPEED CONTROL OF INDUCTION MOTORS
Equivalent circuit model: No load test and blocked rotor test, circuit model, starting methods, speed control of induction motors, induction generator, principle of operation, isolated induction generator, circle diagram, determination of induction motor parameters from circle diagram, problems.	
UNIT - III	ALTERNATORS
Synchronous generators: Introduction, principle of operation, constructional features, armature windings, integral slot and fractional slot windings, distributed and concentrated windings, winding factors, basic synchronous machine model, circuit model of a synchronous machine, phasor diagrams, determination of synchronous impedance, short circuit ratio, armature reaction ampere turns and leakage reactance. Voltage regulation: Calculation of regulation by synchronous impedance method, MMF, ZPF and ASA methods, slip test, parallel operation of alternators, synchronization of alternators, problems.	
UNIT - IV	SYNCHRONOUS MOTORS
Synchronous motors: Principle of operation, power developed, synchronous motor with different excitations, effect of increased load with constant excitation, effect of change in excitation with constant load, effect of excitation on armature current and power factor, construction of “V” and inverted “V” curves, power and excitation circles, starting methods, salient pole synchronous motor, phasor diagrams and analysis, synchronous condenser.	
UNIT - V	SINGLE PHASE INDUCTION MOTOR
Single phase induction motor: Principle of operation, two reaction theory, equivalent circuit analysis, split phase motor, construction, principle of operation, capacitor start motor, shaded pole motor, torque speed characteristics.	
Text books	
1. P S Bimbra, “Electrical Machines”, Khanna Publishers, 2nd Edition, 2008. 2. Kothari, “Electrical Machines”, TMH publication, 3rd Edition, 2010. 3. B. L Thereja, A.K Thereja Charles Kingsley JR., Stephen D U mans, “Electric Machinery”, McGraw-Hill, 6th Edition, 1985.	
References	
1. J B Gupta, “Theory and Performance of Electrical Machines”, S K Kataria & Sons Publication, 14th Edition, 2010 2. M G Say, “Alternating Current Machines”, Pitman Publishing Ltd, 4th Edition, 1976. 3. S K Bhattacharya, “Electrical Machines”, TMH publication, 2nd Edition, 2006.	

XIV. COURSE PLAN:

The course plan is meant as a guideline. Probably there may be changes.

Lecture No	Topics to be covered	CLOs	Reference
1	Understand the principle of operation and constructional features of three phase induction motor	CLO 1	T1: 6.2 R1:7.1-7.2
2	Discuss the types of induction motor based on rotor structure like caged and wound rotor type and concept of slip	CLO 1	T1: 6.3 R1:7.35
3-4	Describe the frequency of rotor currents, rotor MMF, power and numerical problems on rotor EMF, current and power	CLO 1	T1: 6.4-6.5 R1:7.4-7.9
5	Discuss the types of torques under different slip conditions and derive torque derivation, starting torque and condition for maximum torque	CLO 2	T1: 6.6 R1:7.1- 7.9
6-7	Understand the relation between rotor input, losses and power developed and numerical problems on rotor losses and power developed	CLO 3	T1: 6.9 R1:7.22
8	Describe equivalent circuit of three phase induction motor	CLO 4	T1: 6.8 R1:7.28
9-10	Understand the torque slip characteristics and numerical problems on equivalent circuit and torque – slip	CLO 3	T1: 6.9.1 R1:7.11
11-12	Understand no load and blocked rotor test of three phase induction motor and numerical problems on no load and blocked rotor test	CLO 4	T1:6.11 R1:7.31
13-15	Explain the procedure for drawing circle diagram and numerical problems on circle diagram	CLO 5	T1:6.12 R1:8.1-8.3
16-17	Understand starting methods of three phase induction motor and numerical problems on starting methods of three phase induction motor	CLO 6	T1:6.14 R19.1
18-19	Explain speed control methods of three phase induction motor and numerical problems on speed control methods of three phase induction motor	CLO 6	T1:6.15 R1:3.1-3.2
20	Discuss the induction generator principle of operation, isolated induction generator	CLO 6	T1:6.16.1 R1:6.16
21	Explain the working principle of synchronous generators	CLO 7	T1: 5.2 R1:3.5
22	Understand constructional details like stator, rotor and types of synchronous generators	CLO 7	T1: 5.1 R1:3.5
23	Discuss the types of armature windings like single layer, double layer, short pitch, full pitch windings	CLO 8	T1: 5.1 R13.6-3.7
24	Derive the equation for distribution, pitch, winding factors and EMF equation	CLO 8	T1: 7.7 R1:3.12
25-26	Describe armature reaction, leakage reactance, synchronous impedance and numerical problems on windings and EMF equation	CLO 8	T1: 5.2 R1:3.13-3.15
27	Discuss the experimental determination of synchronous reactance and impedance	CLO 8	T1: 5.2.1 R1:3.14
28-29	Explain load characteristics of synchronous generator and numerical problems on efficiency	CLO 8	T1: 5.7 R1:3.17
30	Describe harmonics in generated EMF and suppression methods	CLO 8	T1: 5.3.1 R1:3.17
31	Explain the procedure of calculating the voltage regulation by synchronous impedance method	CLO 9	T1: 5.4.1 R1:3.17
32	Use EMF method for solving numerical problems on voltage regulation	CLO 9	T1: 5.4.1 R1:3.18
33	Explain the procedure for calculating the regulation by MMF method	CLO 9	T1: 5.4.2 R1:3.18
34-35	Use MMF method for solving numerical problems on voltage regulation	CLO 9	T1: 5.4.2 R1:3.19-3.20
36	Explain the procedure for calculating the regulation by Zero power factor method	CLO 9	T1: 5.4.3 R1:3.21
37-38	Use Zero power factor method for solving numerical problems on voltage regulation	CLO 9	T1: 5.4.3 R1:6.1-6.2

Lecture No	Topics to be covered	CLOs	Reference
39	Explain the procedure for calculating the regulation by American standard association method	CLO 9	T1: 5.4.4 R1:6.4-6.6
40	Use American standard association method for solving numerical problems on voltage regulation	CLO 9	T1: 5.4.4 R1:6.13
41	Discuss two reaction analysis and experimental determination of X_d and X_q (slip test), phasor diagram	CLO 10	T1: 5.16 R1:6.7
42	Explain the regulation of salient pole alternators	CLO 10	T1: 5.12 R1:6.13
43	Discuss the parallel operation and necessary conditions for parallel operation	CLO 10	R1:3.22
44	Explain different types of parallel operation methods like dark lamp and bright lamp methods and numerical problems on	CLO 10	R1:6.13
45-46	Understand load shearing of alternators and numerical problems on load shearing	CLO 10	R1:5.3 R1:5.8
47	Explain synchronous motor principle of operation and constructional features	CLO 11	T1: 5.12 R1:5.5
48	Discuss the starting methods of synchronous motor and hunting effect	CLO 11	T1: 5.20 R1:5.5
49	Describe the effect of increased load with constant excitation on armature current, power factor and voltage	CLO 12	T1: 5.14 R1:5.8-5.9
50	Understand excitation and power circles	CLO 12	T1: 5.14.1 R1:5.14-5.15
51-53	Derive formula for power developed by synchronous motor and numerical problems on power developed	CLO 12	T1: 5.116 R1:5.10
54	Discuss the operation of synchronous condenser and numerical problems	CLO 13	T1: 5.419 R1:5.10
55	Explain constructional features and principle of operation of single phase induction motor	CLO 14	T3:36.2 R1:5.11
56	Discuss double revolving and cross field theory	CLO 14	T3:36.3 R1:10.2
57-58	Explain single phase induction motor starting methods like split phase, capacitor start, capacitor run, shaded pole induction motor and numerical problems on starting methods of single phase induction motor	CLO 14	T3:36.8 R1:10.3- 10.5
59-60	Understand the equivalent circuit and its parameters and numerical problems on equivalent circuit of single phase induction motor.	CLO 15	T3:36.2 R1:10.6-10.10

XV. GAPS IN THE SYLLABUS - TO MEET INDUSTRY / PROFESSION REQUIREMENTS:

S. No	Description	Proposed actions	Relevance with POs	Relevance with PSOs
1	Cascaded connection of induction motor	Guest lecture	PO1, PO2	-
2	Stepper motor	Seminars	PO1, PO2	-
3	Encourage students to solve real time applications and prepare towards competitive examinations.	NPTEL	PO 1	-

Prepared by:

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HOD, EEE