

DYNAMICS OF MACHINERY

V Semester: ME								
Course Code	Category	Hours / Week			Credits	Maximum Marks		
AMEB17	Core	L	T	P	C	CIA	SEE	Total
		2	1	-	3	30	70	100
Contact Classes: 45		Tutorial Classes: 15		Practical Classes: Nil		Total Classes: 60		
<p>OBJECTIVES: Students will try to learn:</p> <ol style="list-style-type: none"> The concepts of precision, static and dynamic forces of planer mechanisms by neglecting friction of aero planes, sea vessels, auto mobiles and various force members. The knowledge of engineering mechanics for identifying the coefficient of friction and engine speed of the various contact bodies (Clutches and Brakes) and speed controlled devices, variations of torques and fluctuation of speeds of IC engines. The magnitude and direction of balanced mass for unbalanced rotary and reciprocating engines with the fundamentals of applied physics. Mathematical modeling of various degree of freedom systems to interpret the various vibration parameters. The affluence of real world engineering problems and examples towards gaining the experience for how dynamics of machinery is applied in engineering practice. <p>COURSE OUTCOMES: After the successful completion of the course, students will be able to:</p> <ol style="list-style-type: none"> Discuss the Gyroscopes, effect of precession motion on the stability of moving vehicles such as motor car, motor cycle, aero-planes and ships. Determine the angle of heel to avoid upside down of a two wheeler vehicle while taking in left and right turns. Illustrate the static and dynamic force analysis of two and three force members by graphical super position method. Apply the laws of friction on clutches, brakes and dynamometers to reduce the power losses for the effective torque transmission. Justify the importance of torque and fluctuation of speeds for single and multi cylindered engines to increase the mechanical efficiency. Estimate the height of a governor to regulate the speed of a prime mover at various load conditions. Determine the balanced mass for unbalanced rotary and reciprocating engines by analytical and graphical methods. Develop a mathematical modelling of free and forced vibration systems under damped and un-damped conditions to avoid the vibratory damages of aero-mechanical-civil structures and electrical and electronic components at various operated frequencies. Use the resonance phenomenon to predict the critical or whirling or whipping speeds of various structures under vibrations to avoid catastrophic failures. Apply the principles of dynamics of machinery to a real world problems for obtaining optimum solutions. 								

Module-I	PRECESION, STATIC AND DYNAMIC FORCE ANALYSIS OF PLANAR MECHANISMS	Classes: 09
Precession: Gyroscopes, effect of processional motion on the stability of moving vehicles such as motor car, motor cycle, aero-planes and ships, static and dynamic force analysis of planar mechanisms: (Neglecting friction), Introduction to free body diagrams, conditions of equilibrium, two and three force members, inertia forces and D'Alembert's principle, planar rotation about a fixed centre.		
Module -II	CLUTCHES, BRAKES AND DYNAMOMETERS	Classes: 09
Clutches: Friction clutches, Single disc or plate clutch, multiple disc clutches, cone clutch and centrifugal clutch; Brakes and dynamometers: Simple block brakes, internal expanding brake, band brake of vehicle; Dynamometers absorption and transmission types, general description and method of operation.		
Module -III	TURNING MOMENT AND GOVERNORS	Classes: 09
Turning moment diagrams and flywheels: turning moment: Inertia torque, angular velocity and acceleration of connecting rod, crank effort and torque diagrams, fluctuation of energy; Design of flywheels. Governors: Watt, Porter and Proell governors, spring loaded governors, Hartnell and Hartung with auxiliary springs, sensitiveness, isochronism and hunting		
Module -IV	BALANCING OF ROTATORY AND RECIPROCATING MASSES	Classes: 09
Balancing: Balancing of rotating masses, single and multiple-single and different planes-balancing of reciprocating masses, primary and secondary balancing-analytical and graphical methods; unbalanced forces and couples: Balancing of V-engines, multi cylinder, inline and radial engines for primary, secondary balancing and locomotive balancing.		
Module -V	MECHANICAL VIBRATIONS	Classes: 09
Vibrations: Free vibration of mass attached to a vertical spring, simple problems on forced damped vibration; Vibration isolation and transmissibility, whirling of shafts, critical speeds, torsional vibrations, two and three rotor systems.		
Text Books:		
<ol style="list-style-type: none"> 1. Thomas Bevan, "Theory of Machines", Pearson Education, 3rd Edition, 2009. 2. S.S Ratan, "Theory of Machines", Tata McGraw-Hill, 4th Edition, 2014. 3. R. L. Norton, "Kinematics and Dynamics of Machinery", McGraw-Hill, 1st Edition, 2009. 4. P.L. Balleny, "Theory of Machines and Mechanisms", Khanna publishers, 2013. 		
Reference Books:		
<ol style="list-style-type: none"> 1. J. S. Rao, R.V. Dukkupati, "Mechanism and Machine Theory", New Age Publication, 1st Edition, 2013. 2. Uiker, Penock, Shigley, "Theory of Machines and Mechanisms", Oxford University Press, 4th Edition, 2013. 3. R.S. Khurmi, Gupta, "Theory of Machines", S.Chand & Co, New Delhi, 14th Edition, 2013 		
Web References:		
<ol style="list-style-type: none"> 1. http://www.uobabylon.edu.iq/uobcolleges/ad_downloads/4_1293_515.pdf 2. http://ebooks.library.cornell.edu/k/kmoddl/toc_hartenberg1.html 		
E-Text Books:		
<ol style="list-style-type: none"> 1. https://drive.google.com/file/d/ob7raaoEF40D7eEJIR1voODJodFE/edit 2. http://royalmechanicalbuzz.blogspot.in/2015/04/theory-of-machines-by-rs-khurmi-ebook-pdf.html 		