ANALOG COMMUNICATIONS

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Overview

Communication is the transfer of information from one place to another.

This should be done

- as efficiently as possible
- with as much *fidelity/reliability* as possible
- as securely as possible

Communication System: Components/subsystems act together to accomplish information transfer/exchange.

Elements of a Communication System





Input Transducer: The message produced by a source must be converted by a transducer to a form suitable for the particular type of communication system.

Example: In electrical communications, speech waves are **converted** by a microphone to voltage variation.

Transmitter: The transmitter processes the input signal to produce a signal suits to the characteristics of the transmission channel.

Signal **processing** for transmission almost always involves **modulation** and may also include **coding**. In addition to modulation, other functions performed by the transmitter are **amplification**, **filtering** and coupling the modulated signal to the channel. **Channel:** The channel can have different forms: The atmosphere (or free space), coaxial cable, fiber optic, waveguide, etc.

The signal undergoes some amount of degradation from noise, interference and distortion

Receiver: The receiver's function is to extract the desired signal from the received signal at the channel output and to convert it to a form suitable for the output transducer.

Other functions performed by the receiver: amplification (the received signal may be extremely weak), demodulation and filtering.

Output Transducer: Converts the electric signal at its input into the form desired by the system user.

Example: Loudspeaker, personal computer (PC), tape recorders.

WHAT IS MODULATION

MODULATION is the basic requirement for transmitting the message signal through free space

It is the process of transmission of information signal (low frequency audio signal) using a high frequency carrier signal



Fig. Process of Modulation

 Once this information is received, the <u>low frequency information</u> <u>must be removed from the high frequency</u> carrier. This process is known as "<u>Demodulation</u>".



WHY MODULATION?

- Carrying one signal to another : uses carrier (having high frequency, smaller wavelength)
- > Modulated signal is transmitted
- Problems with transmitting baseband signal/ Need of modulation
 - Height of transmitting and receiving antenna
 - Noise and interference from other sources at low frequencies: Multiplexing
 - *Narrow banding

PRACTICABILITY OF ANTENNAS

 $h=\lambda/4$, for efficient transmission. For f=30 Hz => h= 2500 km f=3kHz => h= 25 km f=3MHz => h= 25 m

Thus as

Frequency increases height of the antenna decreases

What are the reasons for modulation?

1. Frequency division multiplexing (To support multiple transmissions via a single channel) *To avoid* <u>interference</u>



TYPES OF MODULATION

- Sine wave (carrier) described by 3 parameters: amplitude, frequency and phase.
- Let carrier signal be:

 $v(t) = A \sin (\omega t + \varphi)$

So can have

- Amplitude modulation (AM)
- Frequency modulation (FM)
- Phase modulation (PM)

Frequency and phase combined are known as Angle Modulation

AMPLITUDE MODULATION

- The amplitude of the carrier is changed in accordance with the instantaneous value of modulating signal
- Carrier : c(t) = $V_c \cos (2\pi f_c t + \varphi)$ modulating signal v(t) = $V_m \cos (2\pi f_m t)$

Information is contained in the envelop

What are the different Forms of Amplitude Modulation ?

- 1. Conventional Amplitude Modulation (DSB-LC) (Alternatively known as <u>Full AM</u> or Double Sideband with Large carrier (DSB-LC) modulation
- 2. Double Side Band Suppressed Carrier (DSB-SC) modulation
- 3. Single Sideband (SSB) modulation
- 4. Vestigial Sideband (VSB) modulation

AMPLITUDE MODULATION

> Modulated signal:

 $v(t) = V_c \cos (2\pi f_c t) \{1 + m \cos (2\pi f_m t)\}$ $V_c = unmodulated peak carrier amplitude$ $f_c = carrier frequency$ $f_m = modulation frequency$ m = modulation index ("degree" of modulation) m must be between 0 and 1If m > 1 get overmodulation (bad ...distortion)

Figure Amplitude modulation



AM Signal Waveform



(a) Sinusoidal Modulating Wave



(b) Resulting AM Signal

$$A_{max} = 1.5A_{c}$$

 $A_{min} = 0.5 A_{c}$

% Positive modulation= 50%% Negative modulation = 50%Overall Modulation = 50%

VARYRING MODULATION INDEX



modulating signal unmodulated carrier (m = 0)

modulated carrier (m = 0.5)

modulated carrier (m = 1.0)

modulated carrier (m > 1, overmodulated)

m =Vmax – Vmin / Vmax + Vmin

AM – Percentage Modulation



Therefore The full AM signal may be written as

$$s(t) = A_c(1 + m\cos(\omega_m t))\cos(\omega_c t)$$

 $\cos A \cos B = 1/2[\cos(A+B) + \cos(A-B)]$

$$s(t) = A_c(\cos\omega_c t) + \frac{mA_c}{2}\cos(\omega_c + \omega_m)t + \frac{mA_c}{2}\cos(\omega_c - \omega_m)t$$

Draw the Frequency Spectrum of the above AM signal and calculate the Bandwidth



8. Draw Frequency Spectrum for a complex input signal with AM



Frequency Spectrum of an AM signal

The frequency spectrum of AM waveform contains three parts:

- **1.** A component at the <u>carrier</u> frequency f_c
- 2. An <u>upper side band</u> (USB), whose highest frequency component is at f_c+f_m
- **3.** A lower side band (LSB), whose highest frequency component is at $f_c f_m$

The bandwidth of the modulated waveform is twice the information signal bandwidth.

• Because of the two side bands in the frequency spectrum its often called <u>Double Sideband with Large Carrier</u>.(DSB-LC)

 The information in the base band (information) signal is <u>duplicated in the LSB and USB</u> and the carrier conveys no information.



- **m** is merely defined as a parameter, which determines the amount of modulation.
- What is the degree of modulation required to establish a desirable AM communication link?

Answer is to maintain m < 1.0 (m < 100%).

• This is important <u>for successful retrieval</u> of the original transmitted information at the receiver end.

AM – Normalized Average Power

The normalized average power of the AM signal is

$$\langle s^{2}(t) \rangle = \frac{1}{2} \langle |g(t)|^{2} \rangle = \frac{1}{2} A_{c}^{2} \langle [1 + m(t)]^{2} \rangle$$

$$= \frac{1}{2} A_{c}^{2} \langle [1 + 2m(t) + m^{2}(t)] \rangle$$

$$= \frac{1}{2} A_{c}^{2} \langle m(t) \rangle + \frac{1}{2} A_{c}^{2} \langle m^{2}(t) \rangle$$

If the modulation contains no dc level, then $\langle m(t) \rangle = 0$

The **normalized power** of the AM signal is

$$\left\langle s^{2}\left(t\right)\right\rangle = \frac{1}{2}A_{c}^{2} + \frac{1}{2}A_{c}^{2}\left\langle m^{2}\left(t\right)\right\rangle$$

Discrete Carrier Power Sideband power

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AM - Modulation Efficiency

Definition : The Modulation Efficiency is the percentage of the total power of the modulated signal that conveys information.

Only "Sideband Components" – Convey information

Modulation Efficiency:
$$E = \frac{\langle m^2(t) \rangle}{1 + \langle m^2(t) \rangle} \times 100$$

Highest efficiency for a 100% AM signal : 50% - square wave modulation

Normalized Peak Envelope Power (PEP) of the AM signal: $= \frac{A^2}{l_1} \{ 1 + \max[m(t)] \}^2$ Prep 2 Voltage Spectrum of the AM signal:

$$S(f) = \frac{A_c}{2} \left[\delta(f - f_c) + M(f - f_c) + \delta(f + f_c) + M(f + f_c) \right]$$

Unmodulated Carrier
Spectral Component

Power of an AM signal

Suppose that a **5000-W** AM transmitter is connected to a **50 ohm** load;

Then the constant
$$\mathbf{A}_{\mathbf{c}}$$
 is given by $\frac{1}{2} \frac{A_c^2}{50} = 5,000 \Rightarrow A_c = 707 \text{ V}$ Without Modulation

If the transmitter is then **100% modulated** by a **1000-Hz** test tone , the **total** (carrier + sideband) **average power** will be

$$1.5 \begin{bmatrix} 1 \\ -c \\ 2 \\ 50 \end{bmatrix} = (1.5) \times (5000) = 7,500W \qquad \qquad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulation} \quad \begin{bmatrix} m^2(t) \\ -c \\ 2 \end{bmatrix} = \frac{1}{2} \quad \text{for 100\% modulatio$$

The **peak voltage** (100% modulation) is (2)(707) = 1414 V across the 50 ohm load.

The **peak envelope power** (PEP) is

$$4\begin{bmatrix}1 & A^{2} \\ - & c\end{bmatrix} = (4) \times (5000) = 20,000W$$
$$\begin{bmatrix}2 & 50\end{bmatrix}$$

The **modulation efficiency** would be 33% since $< m^2(t) > = 1/2$

Demodulation of Amplitude Modulated Signals

There are 2 main methods of AM Demodulation:

- Envelope or non-coherent Detection/Demodulation.
- Synchronised or coherent Demodulation.

Envelope or Non-Coherent Detection

An envelope detector for AM is shown below:



This is obviously simple, low cost. But the AM input <u>must be</u> DSBAM with *m* << 1, *i.e.* it does not demodulate DSBDimC, DSBSC or SSBxx.

Large Signal Operation

For large signal inputs, (\approx Volts) the diode is switched *i.e.* forward biased \equiv ON, reverse biased \equiv OFF, and acts as a half wave rectifier. The 'RC' combination acts as a 'smoothing circuit' and the output is m(t) plus 'distortion'.



If the modulation depth is > 1, the distortion below occurs



Small Signal Operation – Square Law Detector

For small AM signals (~ millivolts) demodulation depends on the diode square law characteristic.



The diode characteristic is of the form i(t) = av + bv2 + cv3 + ..., where

$$v = (V_{DC} + m(t))\cos(\omega_c t)$$
 i.e. DSBAM signal.

Small Signal Operation – Square Law Detector

i.e. $a(V_{DC} + m(t))\cos(\omega_c t) + b((V_{DC} + m(t))\cos(\omega_c t))^2 + ...$

 $= aV_{DC} + am(t)\cos(\omega_{c}t) + b(V_{DC}^{2} + 2V_{DC}m(t) + m(t)^{2})\cos^{2}(\omega_{c}t) + \dots$

$$= aV_{DC} + am(t)\cos(\omega_{c}t) + (bV_{DC}^{2} + 2bV_{DC}m(t) + bm(t)^{2})\left(\frac{1}{2} + \frac{1}{2}\cos(2\omega_{c}t)\right)$$
$$= aV_{DC} + am(t)\cos(\omega_{c}t) + \frac{bV_{DC}^{2}}{2} + \frac{2bV_{DC}m(t)}{2} + \frac{bm(t)^{2}}{2} + b\frac{V_{DC}^{2}}{2}\cos(2\omega_{c}t) + \dots$$

'LPF' removes components.

Signal out = $aV_{DC} + \frac{bV_{DC}^2}{2} + bV_{DC}m(t)$ *i.e.* the output contains m(t)

Synchronous or Coherent Demodulation

A synchronous demodulator is shown below



This is relatively more complex and more expensive. The Local Oscillator (LO) must be synchronised or coherent, *i.e.* at the same frequency and in phase with the carrier in the AM input signal. This additional requirement adds to the complexity and the cost.

However, the AM input may be <u>any</u> form of AM, *i.e.* DSBAM, DSBDimC, DSBSC or SSBAM, SSBDimC, SSBSC. (Note – this is a 'universal' AM demodulator and the process is similar to correlation – the LPF is similar to an integrator).
Double Side Band Suppressed Carrier (DSB-SC) Modulation

- The carrier component in full AM or DSB-LC does not convey any information. Hence it may be removed or suppressed during the modulation process to attain higher power efficiency.
- The <u>trade off</u> of achieving a higher power efficiency using DSB-SC is at the expense of requiring a <u>complex and expensive</u> receiver due to the absence of carrier in order to maintain <u>transmitter/receiver synchronization</u>.

Derive the Frequency Spectrum for Double Sideband Suppressed Carrier Modulation (DSB-SC)

1 Consider the carrier

 $s_c(t) = A_c \cos(\omega_c t)$ where $\omega_c = 2\pi f_c$

2 modulated by a single sinusoidal signal

$$s_m(t) = A_m \cos \omega_m t$$
 where $\omega_m = 2\pi f_m$

LSB

3 The modulated signal is simply the product of these two $s(t) = A_c \cos(\omega_c t) A_m \cos(\omega_m t)$ $= A_c A_m \cos(\omega_c t) \cos(\omega_m t)$ since $\cos A \cos B = \frac{1}{2} \left(\cos(A + B) + \cos(A - B) \right)$ $= \frac{A_m A_c}{2} \cos(\omega_c + \omega_m) t + \frac{A_m A_c}{2} \cos(\omega_c - \omega_m) t$

$$s_{c}(t) = A_{c} \cos \omega_{c} t$$

$$s_{m}(t) = A_{m} \cos \omega_{m} t$$

$$s(t) = A_{c} \cos (\omega_{c} t) A_{m} \cos (\omega_{m} t)$$

Frequency Spectrum of a DSB-SC AM Signal



- All the transmitted power is contained in the two sidebands (no carrier present).
- The bandwidth is twice the modulating signal bandwidth.
- USB displays the positive components of $s_m(t)$ and LSB displays the negative components of $s_m(t)$.

Generation and Detection of DSB-SC

- The simplest method of generating a DSB-SC signal is merely to <u>filter out the carrier portion</u> of a full AM (or DSB-LC) waveform.
- Given carrier reference, modulation and demodulation (detection) can be implemented using product devices or balanced modulators.

BALANCED MODULATOR



• The two modulators are identical except for the sign reversal of the input to one of them. Thus,

$$s_{1}(t) = A_{c}(1 + m\cos(\omega_{m}t))\cos(\omega_{c}t)$$

$$s_{2}(t) = A_{c}(1 - m\cos(\omega_{m}t))\cos(\omega_{c}t)$$

$$s(t) = s_{1}(t) - s_{2}(t)$$

$$= 2mA_{c}\cos(\omega_{m}t)\cos(\omega_{c}t)$$

COHERENT (SYNCHRONOUS) DETECTOR OR

DSB-SC (PRODUCT DETECTOR)



 Since the carrier is suppressed the envelope no longer represents the modulating signal and hence <u>envelope</u> <u>detector which is of the non-coherent type cannot be</u> used.

$$v(t) = s(t)\cos(\omega_{c}t) = \left[2mA_{c}\cos(\omega_{m}t)\cos(\omega_{c}t)\right]\cos(\omega_{c}t)$$

$$= 2\frac{A_{m}}{A_{c}}A_{c}\cos(\omega_{m}t)\cos^{2}(\omega_{c}t)$$

$$= 2A\cos(\omega)\left(1+\cos 2\omega_{c}t\right)$$

$$m^{m}t\left(\frac{1}{2}\right)$$

$$= A_{m}\cos(\omega_{m}t) + A_{m}\cos(\omega_{m}t)\cos(2\omega_{c}t)$$
since $s_{m}(t) = A_{m}\cos(\omega_{m}t)$

$$= s_{m}(t) + \underbrace{s_{m}(t)\cos(2\omega_{c}t)}_{Unwanted term(removed by LPF)}$$

 It is necessary to have <u>synchronization</u> in both <u>frequency</u> and <u>phase</u> between the <u>transmitter</u> (modulator) & <u>receiver</u> (demodulator), when DSB-SC modulation ,which is of the coherent type, is used.
 Both phase and frequency must be known to demodulate DSB-SC waveforms.

LACK OF PHASE SYNCHRONISATION

Let the received DSB-SC signal be

$$s_{DSB-SC}(t) = s_m(t)\cos(\omega_c t + \theta)A_c$$

if θ is unknown,

$$v(t) = s_{DSB-SC}(t)\cos\omega_{c}t$$

= $A_{c}s_{m}(t)\cos(\omega_{c}t + \theta)\cos\omega_{c}t$
= $\frac{A_{c}s_{m}(t)[\cos\theta + \cos(2\omega_{c}t + \theta)]$

Output of LPF

$$v_o(t) = \frac{A_c}{2} \int_{m}^{m} (t) \cos\theta$$

But we want just

$$v_o(t) = \frac{A_c}{2} s_m(t)$$

Due to lack of phase synchronization, we will see that the wanted signal at the output of LPF will be attenuated by an amount of $cos\theta$. In other words, phase error causes an attenuation of the output signal proportional to the cosine of the phase error.

The worst scenario is when $\theta = \pi/2$, which will give rise to zero or no output at the output of the LPF.

LACK OF FREQUENCY SYNCHRONISATION

Suppose that the local oscillator is not stable at f_c but at $\mathbf{f_c} + \Delta \mathbf{f}$, then $v(t) = s_{DSB-SC}(t) \cos(\omega_c + \Delta \omega)t$ $= A_c s_m(t) \cos \omega_c t \cos(\omega_c + \Delta \omega)t$ $= \frac{A_c}{2} s_m(t) [\cos \Delta \omega t + \cos(2\omega_c t + \Delta \omega)]$

Output of LPF

$$v_o(t) = \frac{A_e}{S_m}(t) \cos \Delta \omega t$$

Thus, the recovered baseband information signal will vary sinusoidal according to $\cos \Delta \omega t$

This problem can be overcome by adding an extra synchronization circuitry which is required to detect θ and $\Delta \omega t$ and by providing the carrier signal to the receiver. **A** synchronizer is introduced to curb the synchronization

problem exhibited in a coherent system.

Let the baseband signal be

$$s_m(t) = A_m \cos \omega_m t$$

Received DSB-SC signal

$$s(t) = A_c s_m(t) \cos \omega_c t$$

SYNCHRONISER



Mathematical analysis of the synchronizer is shown below: $s^{2}(t) = A_{c}^{2}A_{m}^{2}\cos^{2}\omega_{m}t\cos^{2}\omega_{t}t$ $= \frac{A^2 A^2}{4} \left[1 + \cos 2\omega_m t \right] \left[1 + \cos 2\omega_c t \right]$

Output of BPF

$$\frac{A_c^2 A_m^2}{\cos 2\omega_c t}$$

Output of frequency divider

 $k \cos \omega_c t$

where k is a constant of proportionality.

DISADVANTAGE OF USING COHERENT SYSTEMS

 The <u>frequency and phase</u> of the local oscillator signal must be <u>very precise</u> which is very difficult to achieve.

It requires additional circuitry such as <u>synchronizer circuit</u> and hence the <u>cost is higher</u>.

Single Side Band Modulation (SSB)

How to generate SSB signal?

- Generate DSB-SC signal
- Band-pass filter to pass only one of the sideband and suppress the other.

For the generation of an SSB modulated signal to be possible, the message spectrum must have an *energy gap* centered at the origin.

Double Side Band Suppressed Carrier (DSBSC)

• Power in a AM signal is given by

$$\langle s^{2}(t) \rangle = \frac{1}{2}A_{c}^{2} + \frac{1}{2}A_{c}^{2}\langle m^{2}(t) \rangle$$

Carrier Power Sideband power

DSBSC is obtained by eliminating carrier component If *m(t)* is assumed to have a zero DC level, then

$$s(t) = A_c m(t) \cos \omega_c t$$

Spectrum
$$\Rightarrow$$
 $S(f) = \frac{A_c}{2} [M(f - f_c) + M(f + f_c)]$
Power \Rightarrow $\langle s^2(t) \rangle = \frac{1}{2} A_c^2 \langle m^2(t) \rangle$
Modulation Efficiency \Rightarrow $E = \frac{\langle m^2(t) \rangle}{\langle m^2(t) \rangle} \times 100 = 100\%$

Disadvantages of DSBSC:

- Less information about the carrier will be delivered to the receiver.
- Needs a coherent carrier detector at receiver

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EFFICIENCY

- For a fully modulated carrier (m=1), 2/3 of the power is in the carrier, the rest in the sidebands (33.33% efficient)
- > Total power $Pt = Pc (1 + m^2/2)$

Carrier Power (Pc) = V_c² / 2

Side band Power =Plsb=Pusb= m² Pc / 4

- Information in side band : Power gets wasted in carrier
- AM is bandwidth inefficient (2 fm)
- Gets effected due to noise

DSBSC Modulation



Energy spectrum of the DSBSC modulated message signal.

Carrier Recovery for DSBSC Demodulation

> Coherent reference for product detection of DSBSC can not be obtained by the use of ordinary PLL because there are no spectral line components at f_c .



(a) Costas Phase-Locked Loop

Carrier Recovery for DSBSC Demodulation

> A squaring loop can also be used to obtain coherent reference carrier for product detection of DSBSC. A frequency divider is needed to bring the double carrier frequency to f_c .



(b) Squaring Loop

Single Sideband (SSB) Modulation

- 2 An upper single sideband (USSB) signal has a zero-valued spectrum for
- A lower single sideband (LSSB) signal has a zero-valued spectrum for
- SSB-AM popular method ~ BW is same as that of the modulating signal.
 Note: Normally SSB refers to SSB-AM type of signal





 $|f| < f_c$

 $|f| > f_c$

Single Sideband Signal

Theorem : A SSB signal has **Complex Envelope** and bandpass form as:

$$g(t) = A_c [m(t) \pm j\hat{m}(t)]$$

$$s(t) = A_c [m(t) \cos \omega_c t \mp \hat{m}(t) \sin \omega_c t] \qquad \text{Upper sign (-) } \rightarrow \text{ USSB} \\ \text{Lower sign (+) } \rightarrow \text{ LSSB} \qquad \text{Iower sign (+) } \rightarrow \text{ LSSB}$$

$$\hat{m}(t) - \text{Hilbert transform of } m(t) \Rightarrow \hat{m}(t) \equiv m(t) * h(t) \qquad \text{Where} \quad h(t) = \frac{1}{\pi t}$$

$$H(f) = \Im[h(t)] \quad \text{and} \qquad H(f) = \begin{cases} -j, & f > 0 \\ j, & f < 0 \end{cases}$$

Hilbert Transform corresponds to a -90⁰ phase shift



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Chapter 3

FREQUENCY MODULATION



3 properties of an analog signal can be modulated by information signal:

oAmplitude - - -> produce AM
oFrequency - - - > produce FM
oPhase ---> produce PM

FM & PM are forms of <u>angle modulation</u> and often referred as frequency modulation.

FM VS AM

FM is considered to be superior to AM. Transmission efficiency:

>AM use linear amplifier to produced the final RF signal.

>FM has constant carrier amplitude so it is not necessary to use linear amplifier.

Fidelity (capture effect):

> The stronger signal will be capture and eliminate the weaker.

> In AM, the weaker signal can be heard in the background.

Noise immunity (noise reduction):

Constant carrier amplitude.

FM receiver have limiter circuit

Disadvantages of FM

Use too much spectrum space. Requiring a wider bandwidth

> ✓ Reduce modulation index to minimize BW but in FM although we reduced the modulation index, BW is still larger.

- typically used at high frequencies (VHF,UHF)
- & microwave frequencies

More complex circuitry

ANGLE MODULATION

Amplitude of the modulated carrier is held constant and either the phase or the time derivative of the phase of the carrier is varied linearly with the message signal m(t).

General angle-modulated signal is given by

$$m(t) = V_c \cos[\omega_c t + \theta(t)]$$

In angle modulation, $\theta(t)$ is prescribed as being a function of the modulating signal $\theta(t) = F[v_m(t)]$

If $v_m(t)$ is the modulating signal, angle modulation is expressed as

$$v_m(t) = V_m \sin(\omega_m t)$$

 $\omega_m = 2\pi f_m$

where

FM OR PM ?

FM	PM
<i>Instantaneous frequency</i> of the carrier	<i>Phase angle</i> of the camiler is wanied
is varied from its reference value by	from its reference value by an
an amount proportional to the	amount proportional to the
modulating signal amplitude	modulating signal amplitude
Freq. carrier > directly varied	Phase carrier > directly varied
Phase carrier> indirectly varied	Freq. carrier> indirectly varied

Both must occur whenever either form of angle modulation is performed



MATHEMATICAL ANALYSIS

- Instantaneous frequency deviation
 - Instantaneous change in the frequency of the carrier and is defined as the first time derivative of the instantaneous phase deviation

instantaneous frequency deviation = $\theta'(t)$ rad/s

or
$$-\frac{\theta'(t) \text{ rad/s}}{2\pi \text{ rad/cycle}} - \frac{\text{cycle}}{\text{s}} - \text{Hz}$$

- Instantaneous frequency
 - the precise frequency of the carrier at any given instant of time and is defined as the first time derivative of the instantaneous

instantaneous frequency =
$$\omega(t) = \frac{d}{dt}\omega t_c + \theta(t)$$
]
= $\omega_c + \theta'(t)$ rad/s



• Substituting $2\pi f_{\rm c}$ for $\omega_{\rm c}$ gives

instantaneous frequency = $f_i(t)$ and $\omega_i(t) = \left(2\pi \frac{\text{rad}}{\text{cycle}}\right) \left(f_c \frac{\text{cycles}}{\text{s}}\right) + \theta'(t) = 2\pi f_c + \theta'(t) \text{ rad/s}$

 Frequency modulation is angle modulation in which the instantaneous frequency deviation, θ'(t), is proportional to the amplitude of the modulating signal, and the instantaneous phase deviation is proportional to the integral of the modulating signal voltage.

DEVIATION SENSITIVITY

• For modulating signal $v_m(t)$, the frequency modulation are frequency modulation = $\theta'(t) = k_f v_m(t)$ rad/s

where k_f are constant and are the deviation sensitivities of the frequency modulator.

- Deviation sensitivities are the output-versus-input transfer function for the modulators, which gave the relationship between what output parameter changes in respect to specified changes in the input signal.
- frequency modulator,

$$k_f = \frac{\mathrm{rad/s}}{\mathrm{V}} \left(\frac{\Delta \omega}{\Lambda V} \right)$$

FREQUENCY MODULATION (FM)

- Variation of dθ/dt produces Frequency Modulation
- Frequency modulation implies that *dθ/dt* is proportional to the modulating signal.
- This yields

$$v_{FM}(t) = V_c \sin \left[\omega_c t + \theta(t) \right]$$

= $V_c \sin \left[\omega_c t + \int \theta'(t) dt \right]$
= $V_c \sin \left[\omega_c t + \int k_f v_m(t) dt \right]$
= $V_c \sin \left[\omega_c t + k_f V_m \int \sin \omega_m(t) dt \right]$
= $V_c \sin \left[\omega_c t - \frac{k_f V_m}{\omega_m} \cos \omega_m(t) \right]$
Derive the FM signal using both cosine wave signal.

 $v(t) = V_c \cos(\omega_c t + \theta(t))$ $v_m(t) = V_m \cos(\omega_m t)$ for PM $v_{PM}(t) = V_c \cos(\omega_c t + k_p v_m(t))$ $= V_c \cos(\omega_c t + k_p V_m \cos(\omega_m t))$

for FM

$$\begin{aligned}
\nu_{FM}(t) &= V_c \cos\left(\omega_c t + \int k_f v_m(t) dt\right) \\
&= V_c \cos\left(\omega_c t + \int k_f V_m \cos(\omega_m t) dt\right) \\
&= V_c \cos\left(\omega_c t + k_f V_m \int \cos(\omega_m t) dt\right) \\
&= V_c \cos\left(\omega_c t + \frac{k_f V_m}{\omega_m} \sin(\omega_m t)\right)
\end{aligned}$$

FM WAVEFORM



Phase and Frequency modulation ; (a) carrier signal (b) modulating signal (c) frequency modulated wave (d) phase modulated wave

- Carrier amplitude remains constant
- Carrier frequency is changed by the modulating signal.
 - amplitude of the information signal varies, the carrier frequency shift proportionately.
 - Modulating signal amplitude increases, the carrier frequency increases.
 - Production of the signal amplitude varies, the carrier frequency varies below and above it normal center or resting, frequency with no modulation.
- The amount of the change in carrier frequency produced by the modulating signal known as frequency deviation f_d.
- Maximum frequency deviation occurs at the maximum amplitude of the modulating signal.
- The frequency of the modulating signal determines the frequency deviation rate

MODULATION INDEX

- Directly proportional to the amplitude of the modulating signal and inversely proportional to the frequency of the modulating signal
- Ratio of the frequency deviation and the modulating frequency
- FM equation : $v_{FM}(t) = V_c \sin[\omega_c t \beta \cos \omega_m(t)]$
- β as modulation index :

$$\boldsymbol{\rho} = \frac{k_f V_m}{\omega_m} = \frac{\Delta f_c}{f_m}$$

- **Example:**
 - Determine the modulation index for FM signal with modulating frequency is 10KHz deviated by ±10kHz.

 \checkmark Answer : (20KHz/10KHz) = 2.0 (unitless)

The total frequency change, 10kHz x 2 is called the carrier swing

Example:

- a simple transmitter with an assigned rest frequency of 100MHz deviated by a ±25kHz, the carrier changes frequency with modulation between the limits of 99.975MHz and 100.025MHz
- The total frequency change, 25kHz x 2 is called the carrier swing
- Table 1 display the transmission band that use FM and the legal frequency deviation limit for each category
- Deviation limits are based on the quality of the intended transmissions, wider deviation results in higher fidelity
- The frequency deviation is a useful parameter for determining the bandwidth of the FM-signals

Display the transmission band that use FM and the legal

frequency deviation limit for each category

Service Type	Frequency Assignment	Channel Bandwidth	Maximum Deviation	Highest Audio				
Commercial FM radio broadcast	88.0 to 108.0 MHz	200 kHz	±75 kHz	15 kHz				
Television sound	4.5 MHz above the picture carrier frequency	100 kHz	±25 kHz monaural; ± 50 kHz stereo	15 kHz				
Public safety: police, fire, ambulance, taxi, forestry, utilities, transportation, government, etc.	50 MHz and 122 to 174 MHz	20 kHz	±5 kHz	3 kHz				
Amateur and CE class A and business band radio	216 to 470 MHz	15 kHz ±3 kHz		3 kHz				
Wireless mics., wireless telephones	The same as commercial FM broadcast, but limited in power to less than 1 W							
Videotape recorders	All functions are within a closed system and are not restricted, except to radiation into the air. System specs may vary with each manufacturer. Typically: the carrier is at 3.4 MHz, sync tips cause a frequency change to 3.0 MHz, the white level to 4.0 MHz, with a typical bandwidth of 4.0 MHz.							
Satellites	See FSK and data communications (special)							
Military	Intermingled with public safety, and extending to microwave frequencies							

Specifications for transmission of FM signal

PERCENT MODULATION

 Simply the ratio of the frequency deviation actually produced to the maximum frequency deviation allowed by law stated in percent form



• For example if a given modulating signal produces ±50kHz frequency deviation, and the law stated that maximum frequency deviation allowed is ±75kHz, then

% modulation =
$$\frac{50kHz}{75kHz} \times 100 = 67\%$$

A 1 MHz carrier freq with a measured sensitivity of 3 kHz/V is modulated with a 2 V, 4 kHz sinusoid. Determine

- 1. the max freq deviation of the carrier
- 2. the modulation index
- 3. the modulation index if the modulation voltage is doubled
- 4. the modulation index for $v_m(t)=2cos[2\pi(8kHz)t)]V$
- express the FM signal mathematically for a cosine carrier & the cosine-modulating signal of part 4. Carrier amplitude is 10V

1.50					
	FM	РМ			
Modulated wave	$m(t) = V_c \cos \left[\omega_c t + \frac{K_1 V_m}{f_m} \sin(\omega_m t) \right]$	$m(t) = V_c \cos[\omega_c t + K V_m]$			
$\cos(\omega_m t)]$					
or	$m(t) = V_c \cos[\omega_c t + m \sin(\omega_m t)]$	$m(t) = V_c \cos[\omega_c t + m \cos(\omega_m t)]$			
or	$m(t) = V_c \cos \left[\omega_c t + \frac{\Delta f}{f_m} \sin(\omega_m t) \right]$	$m(t) = V_c \cos[\omega_c t + \Delta \theta]$			
$\cos(\omega_m t)$]					
Deviation sensitivity	K_1 (Hz/V)	K (rad/V)			
Deviation	$\Delta f = K_1 V_m (\mathrm{Hz})$	$\Delta \theta = K V_m \text{ (rad)}$			
Modulation index	$m = \frac{K_1 V_m}{f_m} \text{ (unitless)}$	$m = KV_m$ (rad)			
or	$m = \frac{\Delta f}{f_m}$ (unitless)	$m = \Delta \Theta$ (rad)			
Modulating signal	$v_m(t) = V_m \sin(\omega_m t)$	$v_m(t) = V_m \cos(\omega_m t)$			
Modulating frequency	$\omega_m = 2\pi f_m \text{ rad/s}$	$\omega_m = 2\pi f_m \text{ rad/s}$			
or	$\omega_m/2\pi = f_m$ (Hz)	$\omega_m/2\pi = f_m$ (Hz)			
Carrier signal	$V_c \cos(\omega_c t)$	$V_c \cos(\omega_c t)$			

FM RADIO FREQUENCY

- Commercial radio FM band, 88MHz 108MHz
- Each station allotted to a frequency deviation of ±75kHz (150 carrier swing) and 25kHz of guard band added above and below the carrier frequency swing
- Total bandwidth is 200kHz
- Therefore, maximum of 100 stations can be made available

FREQUENCY ANALYSIS OF FM WAVES

BESSEL TABLE

Modulation , index	Carrier J _o	Sidebands									
		J ₁	J ₂	J ₃	J ₄	J ₅	J ₆	J ₇	J ₈	J ₉	J ₁₀
0.0	1.00	<u></u>	7.0 <u></u>	1 <u></u> 1			800 84 <u></u>	<u></u>			
0.25	0.98	0.12	—				13 <u></u> 13		12-11		
0.5	0.94	0.24	0.03								
1.0	0.77	0.44	0.11	0.02			83 				
1.5	0.51	0.56	0.23	0.06	0.01		8. 	an ca d		100-00	1
2.0	0.22	0.58	0.35	0.13	0.03	10 - 1 - 11				3 	3 5
2.5	-0.05	0.50	0.45	0.22	0.07	0.02					
3.0	-0.26	0.34	0.49	0.31	0.13	0.04	0.01			_	-
4.0	-0.40	-0.07	0.36	0.43	0.28	0.13	0.05	0.02	_	—	-
5.0	-0.18	-0.33	0.05	0.36	0.39	0.26	0.13	0.06	0.02		1 <u>11-0</u> 1
6.0	0.15	-0.28	-0.24	0.11	0.36	0.36	0.25	0.13	0.06	0.02	
7.0	0.30	0.00	-0.30	-0.17	0.16	0.35	0.34	0.23	0.13	0.06	0.02
8.0	0.17	0.23	-0.11	-0.29	0.10	0.19	0.34	0.32	0.22	0.13	0.06

Tabulated value for Bessel Function for the first kind of the nth order

- The first column gives the modulation , while the first row gives the Bessel function.
- The remaining columns indicate the amplitudes of the carrier and the various pairs of sidebands.
- Sidebands with relative magnitude of less than 0.001 have been eliminated.
- Some of the carrier and sideband amplitudes have negative signs. This means that the signal represented by that amplitude is simply shifted in phase 180° (phase inversion).
- The spectrum of a FM signal varies considerably in bandwidth depending upon the value of the modulation index. The higher the modulation index, the wider the bandwidth of the FM signal.
- With the increase in the modulation index, the carrier amplitude decreases while the amplitude of the various sidebands increases. With some values of modulation index, the carrier can disappear completely.



Bessel Function, $J_n(m)$ vs m

PROPERTIES OF BESSEL FUNCTION

• Property - 1:

For n even,

we have $J_n(\beta) = J_{-n}(\beta)$ For *n* odd,

we have $J_n(\beta) = (-1) J_{-n}(\beta)$ Thus,

 $J_n(\beta) = (-1)^n J_{-n}(\beta)$

• Property - 2:

For small values of the modulation index β , we have

$$J_0(\beta) \cong 1$$

$$J_1(\beta) \cong \beta/2$$

$$J_3(\beta) \cong 0 \quad \text{for } n > 2$$

$$\sum_{n=-\infty}^{\infty} J_n^2(\beta) = 1$$

• The total BW of an FM signal can be determined by knowing the modulation index and Bessel function.

$$BW = 2f_m N$$

N = number of significant sidebands $f_m =$ modulating signal frequency (Hz)

- Another way to determine the BW is use Carson's rule
- This rule recognizes only the power in the most significant sidebands with amplitude greater than 2% of the carrier.

Calculate the bandwidth occupied by a FM signal with a modulation index of 2 and a highest modulating frequency of 2.5 kHz. Determine bandwidth with table of Bessel functions.

Referring to the table, this produces 4 significant pairs of sidebands. $BW = 2 \times 4 \times 2.5$ = 20 kHz

CARSON'S RULE

$$BW = 2[f_{d(\max)} + f_{m(\max)}]$$

$$f_{d (max)}$$
 = max. frequency deviation
 $f_{m (max)}$ = max. modulating frequency

- Carson's rule always give a lower BW calculated with the formula BW = 2f_mN.
- Consider only the power in the most significant sidebands whose amplitudes are greater than 1% of the carrier.
- Rule for the transmission bandwidth of an FM signal generated by a single of frequency f., as follows:

$$B_T = BW \cong 2\Delta f + 2f_m = 2\Delta f \left(1 + \frac{1}{\beta}\right)$$

or
$$= 2f_m \left(1 + \beta\right)$$

For an FM modulator with a modulation index β

= 1, a modulating signal

 $v_m(t) = V_m sin(2\pi 1000t)$ and unmodulated carrier

 $v_{c}(t) = 10sin(2\pi 500kt)$, determine

- a) Number of sets of significant sideband
- b) Their amplitude
- c) Then draw the frequency spectrum showing their relative amplitudes

- For an FM modulator with a peak freq deviation $\Delta f = 10$ kHz, a modulating signal freq f_m= 10kHz, V_c =10V and 500kHz carrier, determine
- a) Actual minimum bandwidth from the Bessel function table
- b) Approximate minimum bandwidth using Carson's rule
- c) Plot the output freq spectrum for the Bessel approximation

DEVIATION RATIO (DR)

- Minimum bandwidth is greatest when maximum freq deviation is obtained with the maximum modulating signal frequency
- Worst case modulation index and is equal to the maximum peak frequency deviation divided by the maximum modulating signal frequency
- Worst case modulation index produces the widest output frequency spectrum
- Mathematically,



- Determine the deviation ratio and bandwidth for the worst case (widest bandwidth) modulation index for an FM broadcast band transmitter with a maximum frequency deviation of 75kHz and a maximum modulating signal frequency of 15kHz
- Determine the deviation ratio and maximum bandwidth for an equal modulation index with only half the peak frequency deviation and modulating signal frequency

POWER IN ANGLE-MODULATED SIGNAL

• The power in an angle-modulated signal is easily computed

$$P = V_{\rm C}^2 / 2R W$$

- Thus the power contained in the FM signal is independent of the message signal. This is an important difference between FM and AM.
- The time-average power of an FM signal may also be obtained from

$$v_{FM}(t) = V_c \cos(2\pi f_c t + \theta(t))$$

- An FM signal is given as $v_{FM}(t)=12cos[(6\pi 10^{6}t) + 5sin(2\pi x 1250t)]$ V. Determine
- a. freq of the carrier signal
- b. freq of the modulating signal
- c. modulation index
- d. freq deviation
- e. power dissipated in 10 ohm resistor.

Determine the unmodulated carrier power for the FM modulator given that $\beta = 1$, V_c=10 V, R = 50 Ω . Then, determine the total power in the angle-modulated wave.

Solution:

→ not exactly equal because values in Bessel table have been rounded off.

An FM signal expressed as is measured in a 50 ohm antenna. Determine the following :- $v = (t) = 1000 \cos(2\pi t)^{-100} t + 0$

$$v_{FM}(t) = 1000\cos(2\pi 10^7 t + 0.5\sin 2\pi 10^4 t)$$

- a. total power
- b. modulation index
- c. peak freq deviation
- d. modulation sensitivity if 200 mV is required to achieve part c
- e. amplitude spectrum
- f. bandwidth (99%) and approximate bandwidth by Carson's rule
- g. power in the smallest sideband of the 99% BW
- h. total information power

An FM signal with 5W carrier power is fluctuating at the rate of 10000 times per second from 99.96 MHz to 100.04 MHz. Find

- a. carrier freq
- b. carrier swing
- c. freq deviation
- d. modulation index
- e. power spectrum

In an FM transmitter, the freq is changing between 100 MHz to 99.98 MHz, 400 times per seconds. The amplitude of the FM signal is 5 V, determine :-

- 1. carrier and modulating freq
- 2. carrier freq swing
- 3. amplitude spectrum
- 4. bandwidth by using Bessel Table and Carson's rule
- 5. average power at the transmitter if the modulator carrier power is 5 W.

FM SIGNAL GENERATION

- They are two basic methods of generating frequency-Modulated signals:
 - Direct Method
 - Indirect Method

DIRECT FM

• In a direct FM system the instantaneous frequency is directly varied with the information signal. To vary the frequency of the carrier is to use an Oscillator whose resonant frequency is determined by components that can be varied. The oscillator frequency is thus changed by the modulating signal amplitude.

$$f_i = f_c + k_f v_m(t)$$

• For example, an electronic Oscillator has an output frequency that depends on energy-storage devices. There are a wide variety of oscillators whose frequencies depend on a particular capacitor value. By varying the capacitor value, the frequency of oscillation varies. If the capacitor variations are controlled by $v_m(t)$, the result is an FM waveform

INDIRECT FM

- Angle modulation includes frequency modulation FM and phase modulation PM.
- FM and PM are interrelated; one cannot change without the other changing. The information signal frequency also deviates the carrier frequency in PM.
- Phase modulation produces frequency modulation. Since the amount of phase shift is varying, the effect is that, as if the frequency is changed.
- Since FM is produced by PM , the later is referred to as indirect FM.
- The information signal is first integrated and then used to phase modulate a crystal-controlled oscillator, which provides frequency stability.

NOISE AND PHASE SHIFT

- The noise amplitude added to an FM signal introduces a small frequency variation or phase shift, which changes or distorts the signal.
- Noise to signal ratio N/S



• Signal to noise ration S/N

$$\frac{S}{N} - \frac{1}{N} / \frac{1}{S}$$

INTERFERENCE

- A major benefit of FM is that interfering signals on the same frequency will be effectively rejected.
- If the signal of one is more than twice the amplitude of the other, the stronger signal will "capture" the channel and will totally eliminate the weaker, interfering signal.
- This is known as the *capture effect* in FM.
- In FM, the capture effect allows the stronger signal to dominate while the weaker signal is eliminated.
- However, when the strengths of the two FM signals begin to be nearly the same, the capture effect may cause the signals to alternate in their domination of the frequency.

- Despite the fact that FM has superior noise rejection qualities, noise still interferes with an FM signal. This is particularly true for the high-frequency components in the modulating signal.
- Since noise is primarily sharp spikes of energy, it contains a considerable number of harmonics and other high-frequency components.
- These high frequencies can at times be larger in amplitude than the high-frequency content of the modulating signal.
- This causes a form of frequency distortion that can make the signal unintelligible.
- To overcome this problem Most FM system use a technique known as Pre-emphasis and De-emphasis.

Noise in electrical terms may be defined as any unwanted introduction of energy tending to interfere with the proper reception and reproduction of transmitted signals.

➢ Noise is mainly of concern in receiving system, where it sets a lower limit on the size of signal that can be usefully received. Even when precautions are taken to eliminate noise from faulty connections or that arising from external sources, it is found that certain fundamental sources of noise are present within electronic equipment that limit the receivers sensitivity.

NOISE

Classification of noise

NOISE WHOSE SOURCES ARE EXTERNAL TO THE RECEIVER

NOISE CREATED WITHIN THE RECEIVER ITSELF

EXTERNAL NOISE

- Noise created outside the receiver
- > External noise can be further classified as:
- 1. Atmospheric
- 2. Extraterrestrial
- 3. Industrial

ATMOSPHERIC NOISE

Atmospheric noise or static is generally caused by lightning discharges in thunderstorms and other natural electrical disturbances occurring in the atmosphere.

Since these processes are random in nature, it is spread over most of the RF spectrum normally used for broadcasting.
➢ Atmospheric Noise consists of spurious radio signals with components distributed over a wide range of frequencies. It is propagated over the earth in the same way as ordinary radio waves of same frequencies, so that at any point on the ground, static will be received from all thunderstorms, local and distant.

Atmospheric Noise becomes less at frequencies above 30 MHz Because of two factors:-

- Higher frequencies are limited to line of sight propagation i.e. less than 80 km or so.
- 2. Nature of mechanism generating this noise is such that very little of it is created in VHF range and above.



Solar Noise

➤ Under normal conditions there is a constant noise radiation from sun, simply because it is a large body at a very high temperature (over 6000°C on the surface, it therefore radiates over a very broad frequency spectrum which includes frequencies we use for communication.

➢ Due to constant changing nature of the sun, it undergoes cycles of peak activity from which electrical disturbances erupt, such as corona flares and sunspots. This additional noise produced from a limited portion of the sun, may be of higher magnitude than noise received during periods of quite sun.

Cosmic Noise

Sources of cosmic noise are distant stars (as they have high

Itemperatures), they radiate RF noise in a similar manner as our Sun, and their lack in nearness is nearly compensated by their significant number.

The noise received is called Black Body noise and is distributed fairly uniformly over the entire sky.

INDUSTRIAL NOISE

This noise ranges between 1 to 600 MHz (in urban, suburban and other industrial areas) and is most prominent.

Sources of such Noise : Automobiles and aircraft ignition, electric motors, switching equipment, leakage from high voltage lines and a multitude of other heavy electrical machines.

The Noise is produced by the arc discharge present in all these operations. (this noise is most intense industrial and densely populated areas)

INTERNAL NOISE

Noise created by any of the active or passive devices found in receivers.

Is Such noise is generally random, impossible to treat on individual voltage basis, but easy to observe and describe statistically. Because the noise is randomly distributed over the entire radio spectrum therefore it is proportional to bandwidth over which it is measured.

Internal noise can be further classified as:

- 1. Thermal Noise
- 2. Shot Noise
- 3. Low frequency or flicker Noise

4. Burst Noise

Thermal Noise

- The noise generated in a resistance or a resistive component is random and is referred to as thermal, agitation, white or Johnson noise.
- **CAUSE** :
- The free electrons within an electrical conductor possess kinetic energy as a result of heat exchange between the conductor and its surroundings.
- Due to this kinetic energy the electrons are in motion, this motion is randomized through collisions with imperfections in the structure of the conductor. This process occurs in all real conductors and gives rise to conductors resistance.
- As a result, the electron density throughout the conductor varies

randomly, giving rise to randomly varying voltage across the ends of conductor. Such voltage can be observed as flickering on a very sensitive voltmeter.



- The average or mean noise voltage across the conductor is zero, but the root-mean-square value is finite and can be measured.
- The mean square value of the noise voltage is proportional to the resistance of the conductor, to its absolute temperature, to the frequency bandwidth of the device measuring the noise.
- The mean-square voltage measured on the meter is found to be

$$E_n^2 = 4RkTB_n$$



MEASUREMENT OF THERMAL NOISE

Where E_n = root-mean-square noise voltage, volts

- R = resistance of the conductor, ohms
- T = conductor temperature, kelvins
- B_n = noise bandwidth, hertz
- k = Boltzmann's constant (1.38×10^{-23} J/K)

And the rms noise voltage is given by :

 $E_n = v(4RkTB_n)$

NOTE: Thermal Noise is not a free source of energy. To abstract the noise power, the resistance **R** is to be connected to a resistive load, and in thermal equilibrium the load will supply as much energy to **R** as it receives.



- In analogy with any electrical source, the available average power is defined as the maximum average power the source can deliver. Consider a generator of EMF E_n volts and internal resistance R.
- I Assuming that R_L is noiseless and receiving the maximum noise power generated by R; under these conditions of maximum power transfer, R_L must be equal to R. Then

 $P_n = V^2/R_L = V^2/R = (E_n/2)^2/R = E_n^2/4R$ Using Equation 1,

$$P_n = kTB_n$$

Example:

Calculate the thermal noise power available from any resistor at room temperature (290 K) for a bandwidth of 1MHz. Calculate also the corresponding noise voltage, given that $R = 50 \Omega$ Solution For a 1MHz bandwidth, the noise power is

$$P_n = 1.38 \times 10^{-23} \times 290 \times 10^6$$

$$E_n^2 = 4 \times 50 \times 1.38 \times 10^{-23} \times 290$$

= 810⁻¹³
= 0.895 µV



Image: The thermal noise properties of a resister R may be a.) Equivalent Voltagerepresented be the equivalent voltage generator .Socurce

> Equivalent current generator is found using the Norton's Theorem. Using conductance G = (1/R), the rms noise current is given by :

$$I_n^2 = 4GkTB_n$$

Resisters in Series

 \geq let R_{ser} represent the total resistance of the series chain, where R_{ser} = R₁ + R₂ + R₃ +; then the noise voltage of equivalent series resistance is

$$E_n^2 = 4R_{ser} kTB_n$$

= 4(R₁ + R₂ + R₃ + ...)kTB_n
= E_{n1}² + E_{n2}² + E_{n3}² +

Hence the noise voltage of the series chain is given by:

$$E_n = V (E_{n1}^2 + E_{n2}^2 + E_{n3}^2 +)$$

Resisters in Parallel

With resistors in parallel it is best to work in terms of conductance.
 Let G_{par} represent the parallel combination where G_{par} = G₁ + G₂ + G₃ + ...; then

$$I_n^2 = 4G_{par} kTB_n$$

= 4(G_1 + G_2 + G_3 + ...)kTB_n
= I_n^2 + I_n^2 + I_n^3 +

REACTANCE

- Reactances do not generate thermal noise. This follows from the fact that reactances cannot
 Dissipate power.
- Consider an inductive or capacitive reactance connected in parallel with a resistor R.



In thermal equilibrium, equal amounts of power must be exchanged; that is, $P_1 = P_2$. But since the reactance cannot dissipate power, the power P_2 must be zero, and hence P_1 must also be zero.

Shot Noise

Shot noise is random fluctuation that accompanies any direct current crossing potential barrier. The effect occurs because the carriers (electrons and holes in semiconductors) do not cross the barrier simultaneously but rather with random distribution in the timing of each carrier, which gives rise to random component of current superimpose on the steady current.

In case of bipolar junction transistors, the bias current crossing the forward biased emitter base junction carries the shot noise.
 When amplified, this noise sounds as though a shower of lead shots were falling on a metal sheet. Hence the name shot noise.

Although it is always present, shot noise is not normally observed during measurement of direct current because it is small compared to the DC value; however it does contribute significantly to the noise in amplifier circuits.

The mean square noise component is proportion to the DC flowing, and for most devices the mean Square, shot-noise is given by:

$$l_n^2 = 2 l_{dc} q_e B_n$$
 ampere²

Where I_{dc} is the direct current in ampere's, q_e is the magnitude of electronic charge and B_n is the equivalent noise bandwidth in hertz.

Example

Calculate the shot noise component of the current present on the direct current of 1mA flowing across a semiconductor junction, given that the effective noise bandwidth is 1 MHz.

SOLUTION

$$I_n^2 = 2 \times 10^{-3} \times 1.6 \times 10^{-19} \times 10^6$$

= 3.2 × 10⁻¹⁶ A²
= 18 nA

Flicker Noise (or 1/f noise)

This noise is observed below frequencies of few kilohertz and its spectral density increases with decrease in frequency. For this reason it is sometimes referred to as 1/f noise.

The cause of flicker noise are not well understood and is recognizable by its frequency dependence. Flicker noise becomes significant at frequency lower than about 100 Hz. Flicker noise can be reduced

- significantly by using wire-wound or metallic film resistors rather than the more common carbon composition type.
- In semiconductors, flicker noise arises from fluctuations in the carrier densities (holes and electrons), which in turn give rise to fluctuations in the conductivity of the material. I.e the noise voltage will be developed whenever direct current flows through the semiconductor, and the mean square voltage will be proportional to the square of the direct current.
- In Electronic devices, it shows up as a low frequency phenomenon, as the higher frequencies overshadowed by white noise from other sources.

Burst Noise

It consists of sudden step-like transitions between two or more discrete voltage or current levels, as high as several hundred microvolts, at random and unpredictable times. Each shift in offset voltage or

SPECTRAL DENSITY

- spectral density is power distribution in frequency spectrum it use to distinguish type of noise. plote of light intensity/power as a function of frequency or wavelength.
- Thermal noise lies in category of power signals has spectral densities. B_n is property of external receiving system and B_n assume flat.

? from eq. $P_n = E_n^2/4R = 4RkTB_n/4R = kTB_n$, since $E_n^2 = 4RkTB_n$ where $E_n = rms$ noise voltage(volt) R=resistance of conductor(Ω) $B_n = noise$ bandwidth(hertz) K=Boltzmaan constant=1.38x10-23(J/k) T=conductor temperature(kelvin) available power spectral density in Watts/Hz or Joule is $G_a(f) = P_n/B_n = kT$ spectral density for mean square voltage is given by
 G_v(f)=E²n/Bn=4RkT(v²/hz) since E²n=4RkTB_n. Spectral densities are flat that is independent of frequency in fig. below



- So thermal noise is also called white noise because of analogy to white light that has flat spectrum means signal contain equal power within a fixed bandwidth at any center frequency.
- when white noise is passed through a network then spectral density is changed by shape of network frequency response.
- total noise power at output is sum of the noise contribution over complete frequency range. taking into account of frequency response shape.

> Consider a power spectral density response in figure below



at frequency f1 the noise power for small band width δf about f1 is δP_{n1}=S_p(f1).δf Here δf assume flat about f1

- $\sim \delta P_{n1}$ = spectral density (watts/hertz). Bandwidth (Hz) or δP_{n1} = S_p(f1).δf
- So noise power is equal to area of shaded strip about f1 similarly for f2,f3,....so that power is sum of all these small areas equal to total area under the curve. Area of curves gives total mean square voltage

```
> area of curve= \int G_a(f); for f=0 to f=∞
```

for mean square voltage S_p(f1)xδf=S_p(f1)δf(V²)=area of curves gives total mean square voltage.

Equivalent noise bandwidth

- it is the frequency span of a noise power curve with amplitude equal to actual peak value and with same integrated area
- If R is connected to input of LC filter as in figure (a) this represent an input generator of mean square voltage spectral density 4RkT feeding a network of R and LC filter
- Let transfer function of network including R be H(f), so spectral density for mean square voltage is=4RkT|H(f)|²; H(f) is ratio of output to input voltage for mean square voltage.





➤ Total mean square output voltage is given by V_n²=∫4RkT.|H(f)|²δf for f=0 to ∞ =4RkTx(area under |H(f)|²) curve

or total mean square voltage at the output can be stated as
V_n²=4RkTB_n

By above two equation gets equivalent noise bandwidth of network

 \succ B_n=∫(|H(f)|²δf) =area under curve |H(f)|² for f=0 to ∞

Example considered in fig. below input capacitance of the voltmeter used measure the noise voltage across R Circuit diagram



RC network and its transfer function used in determining noise bandwidth.

- ▶ transfer function of RC network |H(f)|=1/[1+(ωCR)]^{1/2}
 ▶ Equivalence noise bandwidth of the RC network
 is B_n=∫|H(f)|2df=1/4RC; f=0 to ∞
- V_n²=4RkTx1/4RC=kT/C ,so mean square voltage orginates from R even though it is independent of R and inversly proportional to C even though C does not generate noise.

transfer function |H(f)|=|X_c/Z_s| ; Z_s=r(1+jyQ) is impedance of the series tuned circuit and,Xc=1/jωc i.e. reactance of c. ➢ let circuit is resonant at f₀ and noise restricted to bandwidth Δf« f₀ about resonant frequency f₀ so transfer function given by |H(f)|=1/ω₀ Cr=Q ; area under|H(f)|² curve of small bandwidth δf is Q²δf so

➤ mean square noise voltage is $V_n^2 = 4rkTB_n = 4rQ^2kT\delta f = 4R_DkT\Delta f$ use the relation $Q^2r = R_D$; f=0 to ∞ and B_n = 1/4R_DC

R_D is dynamic resistance of the tuned circuit . Noise bandwidth expressed as a function of 3-dB bandwidth of circuit

From equ. $B_{3dB} = f_o/Q$ and $R_D = Q/\omega_o C$ combine these equ. Gets $B_n = \prod/2B_{3dB}$

The mean square voltage at the output as V²_n²=4R_DkTx1/4R_DC=kT/C So noise from resister R_D is limited by bandwidth B_n is V²n=4R_DkTx1/4R_DC=kT/C

- Provide the second s
- In radio receivers noise is generated at antenna receiver input and output noise bandwidth is determined by the audio part of the receiver
- Equivalent noise bandwidth=area of normalized frequency curve for low frequency section. normalized means curve max. value is unity

 Response curve show output in decibels relative to maximum as in next slide fig.

Equivalent noise bandwidth is area of curve for a single sideband type, then noise bandwidth appears on both side of the carrier and gets doubled.

Response curve



(a)Amplifier frequency response curve (b) curve of (a) using linear scales (c) noise bandwidth Of a double sideband receiver

Signal to noise ratio

- in communication it is the signal to noise ratio rather than absolute value of noise.
- ? It is defined as a power ratio $S/N=P_s/P_n=V_s^2/V_n^2$
- Repeater /amplifier insert to make up for the loss in analog telephone cable
 - If power loss of a line section is L then repeater amplifier power gain G is chosen so LG=1,long line divided into identical section

If input signal power= P_s to first section as signal passes along the link power output at

- ➤ each repeater is Ps since LG=1 for each link but noise power are additive and the total noise at the output of mth link is $P_n = P_{n1} + P_{n2} + \dots + P_{nm}$
- If each links are identical and contribute Pn then total noise power is P_{nm}=MP_n then output signal to noise ratio is (N/S)_odB=10logP_s/MP_n=(S/N)₁dB-(M)dB
- Where (S/N)₁ is ratio for one link and (M)dB is no of links expressed as power ratio in decibels

Ques: the is equivalent noise resistance for an amplifier is 300Ω and equivalent shot noise current 5µA.the amplifier is fed from 150Ω 10µV rms sinusoidal signal source. Calculate the individual noise voltage at the input signal to noise ratio in decibels. the noise bandwidth is 10MHz.

Solution: let room temperature so that $kT=4x10^{-21}J$ And $q_e=1.6x10-19C$ shot noise current is $I_{na}=[2q_eI_{EQ}B_n]^{1/2}=4nA$ So noise voltage across source resistance is

 $I_{na}R_s=0.6\mu$ V shot noise current does not develop a voltage across R_n . The noise voltage generated by R_n is $V_{na}=[4R_n kT_o B_n]^{1/2}=6.93\mu$ V Thermal noise voltage from source is $V_{ns}=[4R_s kT_o B_n]^{1/2}=4.9\mu$ V total noise voltage at input to the amplifier is $V_n=[4.9^2+6.93^2+.6^2]^{1/2}=8.51\mu$ V so signal to noise ratio in decibels is

 $S/N=20logV_s/V_n=1.4dB$

NOISE FACTOR

 \succ Noise factor is the ratio of available S/N ratio at the input to the available S/N ratio at the output .

> Consider a signal source at room temperature $T_o = 290K$ providing an input to an amplifier. The available noise power from this would be

> $P_{ni} = kT_{o}B_{n}$. where , k = boltzmann constant = 1.38X10⁻²³ J/K B_{n} = equivalent noise bandwidth in Hz



- The source connected to the amplifier represents available signal to noise ratio.
- If amplifier has the available power gain denoted by G, the available output signal power P_{so} = GP_{si} and if the amplifier was entire Noise power P_{so} = GP_{si} and if the noise power would be P_{so} = G kT^G_{B,G} P_{so} = G

The noise factor F us defined as

F = (available S/N power ratio at the input) / (available S/N power ratio at the output)

$$F = (P_{si} / kT_o B_n) X (P_{no} / GP_{si})$$
$$F = P_{no} / GkT_o B_n$$

It follows from this that the available output noise power is given by $P_{no} = FGkT_o B_n$

F can be interpreted as the factor by which the amplifier increases the output noise , for , if amplifier were noiseles the output noise would be $GkT_n B_n$.

The available output power depends on the actual input power delivered to the amplifier .

Noise factor is a measured quantity and will be specified for given amplifier or network. It is usually specified in decibels, when it is referred to as the noise figure. Thus

```
noise figure = (F) dB = 10logF
```

Example

The noise figure of an amplifier is 7dB. Calculate the output signal to noise ratio when the input signal to noise ratio is 35 dB.

Sol. From the definition of noise factor,

 $(S/N)_o = (S/N)_{in} - (F) dB$ = (35 - 7) dB = **28 db**

Amplifier Input Noise in terms of F

➤Amplifier noise is generated in many components throughout the amplifier , but it proves convenient to imagine it to originate from some equivalent power source at the input of the amplifier . Then the total available power input noise is

$$P_{ni} = P_{no} / G$$

$$= FkT_{o}B_{n}$$

$$KT_{o}B_{n} + F_{o}B_{n}$$
Noiseless
amplifier
Gain, G
Noise Factor
F
Noiseless
amplifier
Gain, G
Noise Factor
F
Noiseless
amplifier
Gain, G
Noise Factor
F
P
na , where

$$P_{na} = FkT_{o}B_{n} - kT_{o}B_{n}$$

$$= (F - 1)kT_{o}B_{n}$$


An amplifier has a noise figure of 13dB. Calculate equivalent amplifier input noise for a bandwidth of 1 MHz.

Sol. 13 dB is a power ratio of approximately 20 : 1. hence

$$P_{na} = (20 - 1)X 4 X 10^{-21} X 10^{6}$$

= **1.44pW**.

Noise figure must be converted to a power ratio F to be used in the calculation.

Noise factor of amplifiers in cascade

consider first two amplifiers in cascade . The problem is to determine the overall noise factor F in terms of individual noise factors and available power gains .

the available noise power at the output of the amplifier 1 is $P_{no1} = F_1 G_1 kT_0 B_n$ and this available to amplifier 2.



e 4.15.1 Noise factor of two amplifiers in cascade.

> Amplifier 2 has noise $(F_2 - 1)kT_0 B_n$ of its own at its input, hence total available noise power at the input of amplifier 2 is

$$P_{ni2} = F_1 G_1 kT_0 B_n + (F_2 - 1)kT_0 B_n$$

Now since the noise of amplifier 2 is represented by its equivalent input source , the amplifier itself can be regarded as being noiseless and of available power gain G₂, so the available noise output of amplifier 2 is

$$P_{no2} = G_2 P_{ni2}$$

= G_2 (F_1 G_1 kT_0 B_n + (F_2 - 1)kT_0 B_n) (1)

The overall available power of the two amplifiers in cascade is

 $G = G_1 G_2$ and let overall noise factor be **F**; then output noise power can also be expressed as

$$P_{no} = FGkT_{o}B_{n}$$
 (2)

equating the two equations for output noise (1) and (2)

☑ This equation shows the importance of high gain , low noise amplifier as the first stage of a cascaded system. By making G₁ large, the noise contribution of the second stage can be made negligible, and F₁ must also be small so that the noise contribution of the first amplifier is low.

The argument is easily extended for additional amplifiers to give

$F = F_1 + (F_2 - 1)/G_1 + (F_3 - 1)/G_1 G_2$

This is known as **FRISS' FORMULA**.

There are two particular situations where a low noise, front end amplifier is employed to reduce the noise. One of these is in satellite receiving systems.

The other is in radio receivers used to pick up weak signals such as short wave receivers.

In most receivers, a stage known as the *mixer stage* is employed to change the frequency of the incoming signal, and it is known that the mixer stages have notoriously high noise factors. By inserting an RF amplifier ahead of the mixer, the effect of the mixer noise can be reduced to negligible levels. This is illustrated in following example.

Example

A mixer stage has a noise figure of 20dB and this is preceded by an amplifier that has a noise figure of 9 dB and an available power gain of 15dB. Calculate overall noise figure referred to the input .

Sol. It is necessary to convert all decibel values to the equivalent power ratios :

$$F_{2} = 20dB = 100:1 \text{ power ratio}$$

$$F_{1} = 9dB = 7.94:1 \text{ power ratio}$$

$$G_{1} = 15dB = 31.62:1 \text{ power ratio}$$

$$F = F_{1} + (F_{2} - 1)/G_{1}$$

$$= 7.94 + (100-1)/31.62$$

$$= 11.07$$

This is overall noise factor. The overall noise figure is

NOISE TEMPERATURE

The concept of noise temperature is based on available noise power equation

$$P_n = kT_a B_n$$

Here the subscript has been included to indicate the noise temperature is associated only with available noise power.

In general, T_a will not be same as that physical temperature of the noise source. As an example, an antenna pointed at deep space will pick up a small amount of cosmic noise. The equivalent noise temperature of antenna that represents this noise power may be a few tens of kelvins, well below the physical ambient temperature of the antenna. If the antenna is directly pointed at the sun, the received noise power increases enormously and the corresponding equivalent noise temperature is well above the ambient temperature.

When the concept is applied to an amplifier, it relates to equivalent noise of the amplifier referred to the input. If the amplifier noise referred to the input is denoted by P_{na}, the equivalent noise temperature of the amplifier referred to the input is

$$T_{e} = P_{na} / kB_{n}$$
 (3)

We know equivalent input power for an amplifier is given in terms of its noise factor by

 $P_{na} = (F-1)kT_o B_n$

putting this in equation (3)

we get equivalent noise temperature of the amplifier as

$$T_e = (F-1)/T_a$$

This shows the proportionality between T_e and F.

In practice it is found that noise temperature is the better measure for low noise devices , such as low noise amplifiers used in satellite receiving systems while noise factor is a better measure for the main receiving system.

➢ Friss's formula can be expressed in terms of equivalent noise temperatures. Denoting by T_e the overall noise of the cascaded system referred to the input , and by T_{e1}, T_{e2}, and so on , the noise temperatures of the individual stages , the in Friss's formula is easily rearranged to give

$$T_e = T_{e1} + T_{e2} / G_1 + T_{e3} / G_1 G_2 + \dots$$

Q. A receiver has a noise figure of 12dB and it is fed by a low noise amplifier that has gain of 50dB and a noise temperature of 90 K. calculate the noise temperature of the receiver and the overall noise temperature of the receiving system.

SOL. 12dB represents a power ratio of 15.85 : 1. Hence

T_{em}= (15.85-1) X 290 = 4306 K

The 50dB gain represents a power ratio of $10^5: 1$. Hence

 $T_{e} = 90 + 4306 / 10^{5}$

= 90 K

This example shows the relatively high noise temperature of the receiver , which clearly cannot be its physical temperature. It also shows how the low noise amplifier controls the noise temperature of the overall receiving system.

RECEIVERS

Radio receiver is an electronic equipment which pick ups the desired signal, reject the unwanted signal and demodulate the carrier signal to get back the original modulating signal.



Function of Radio Receivers

- Intercept the incoming modulated signal
- Select desired signal and reject unwanted signals
- Amplify selected R.F signal
- Detect modulated signal to get back original modulating signal
- Amplify modulating frequency signal

Design of Receiver

- The radio receiver has to be cost effective
- Requirements:
 - Has to work according to application as for AM or FM signals
 - Tune to and amplify desired radio station
 - Filter out all other stations
 - Demodulator has to work with all radio stations regardless of carrier frequency

Classification of Radio Receivers

Depending upon application

- <u>AM Receivers</u> receive broadcast of speech or music from AM transmitters which operate on long wave, medium wave or short wave bands.
- <u>FM Receivers</u> receive broadcast programs from FM transmitters which operate in VHF or UHF bands.

- <u>Communication Receivers</u> used for reception of telegraph and short wave telephone signals.
- <u>Television Receivers</u> used to receive television broadcast in VHF or UHF bands.
- <u>Radar Receivers</u> used to receive radio detection and ranging signals.

Depending upon fundamental aspects

- Tuned Radio Frequency (TRF)Receivers
- Super-heterodyne Receivers

RECEIVERS

Tuned Radio Frequency (TRF) Receiver:

- Composed of RF amplifiers and detectors.
- No frequency conversion
- It is not often used.
- Difficult to design tunable RF stages.
- Difficult to obtain high gain RF amplifiers

Super-hetrodyne Receiver

- Downconvert RF signal to lower IF frequency
- Main amplifixcation takes place at IF

Communication Receiver

• Downconvert RF signal to two IF frequency

TRF (Tuned Radio frequency) RECEIVER



- TRF receiver includes an
 - RF stage
 - a detector stage
 - and an audio stage .
- Two or three RF amplifiers are required to filter and amplify the received signal to a level sufficient to drive the detector stage.



- RF section (Receiver front end)
 > used to detect the signal
 - ➤ bandlimit the received RF signal
 - \succ and amplifying the received RF signal.
- AM detector

Demodulates the AM wave and converts it to the original information signal.

• Audio section

≻Used to amplify the recovered signal

Advantages of TRF

- TRF receivers are simple to design and allow the broadcast frequency 535 KHz to 1640 KHz.
- High senstivity.

Disadvantages of TRF

- At the higher frequency, it produces difficulty in design.
- It has poor audio quality.
- Drawbacks
 - Instability
 - Variation in BW
 - Poor Selectivity

- <u>INSTABILITY</u>
 - ➤Due to high frequency, multi stage amplifiers are susceptible to breaking into oscillation.
 - ➤As gain of RF amplifier is very high ,a small feedback from output to input with correct phase can lead to oscillations.
 - ➢Correct phase means a positive feedback and it takes place due through stray capacitances
 - ➤As reactance of stray capacitances decreases at higher frequencies resulting in increased feedback.
 - ➢ Forcing the device to work as an oscillator instead of an amplifier.

VARIATION IN BANDWIDTH

- ➤ The bandwidth is inconsistent and varies with the center frequency when tuned over a wide range of input frequencies.
- ➤As frequency increases, the bandwidth (f/Q) increases. Thus, the selectivity of the input filter changes over any appreciable range of input frequencies.

Example

Suppose required BW=10KHz

We have f1=545KHz,f2=1640KHz

- > Q1 = f1/BW = 54.5,
- \triangleright Q2=f2/BW=164
- ➢ But practically Q is limited upto 120
- Considering Q limit 120, BW changes to13.6 KHz (as BW=f2/Q2=1640/120)
- So Adjacent channel is picked up resulting in variation in bandwidth.

- <u>POOR SELECTIVITY</u>
 - The gains are not uniform over a very wide frequency range.
 - Due to higher frequencies ability to select desired signal is affected.

Due to these drawbacks TRF are rarely used.

SUPER HETRODYNE RECEIVER

The shortcomings of the TRF receiver are overcome by the super heterodyne receiver.



- *Heterodyne* to mix two frequencies together in a nonlinear device or to transmit one frequency to another using nonlinear mixing.
- Also known as *frequency conversion*, high frequency down converted to low frequency.(IF)
- A super heterodyne receiver converts all incoming radio frequency (RF) signals to a lower frequency known as an intermediate frequency (IF).

DRAWBACKS OVERCOMED

- <u>Stability</u> as high frequency is down converted to IF the reactance of stray capacitances will not decrease as it was at higher frequencies resulting in increased feedback.
- <u>No variation in BW</u>- as IF range is 438 to 465 KHz (in case of AM receivers) mostly 455KHz ,appropriate for Q limit (120).
- <u>Better selectivity</u>- as no adjacent channels are picked due to variation in BW.



RF section

- Consists of a pre-selector and an amplifier
- Pre-selector is a broad-tuned bandpass filter with an adjustable center frequency used to reject unwanted radio frequency and to reduce the noise bandwidth.
- RF amplifier determines the sensitivity of the receiver and a predominant factor in determining the noise figure for the receiver.

- <u>Mixer/converter section</u>
 - Consists of a radio-frequency oscillator and a mixer.
 - Choice of oscillator depends on the stability and accuracy desired.
 - Mixer is a nonlinear device to convert radio frequency to intermediate frequencies (i.e. heterodyning process).
 - The shape of the envelope, the bandwidth and the original information contained in the envelope remains unchanged although the carrier and sideband frequencies are translated from RF to IF.

IF section

- Consists of a series of IF amplifiers and bandpass filters to achieve most of the receiver gain and selectivity.
- The IF is always lower than the RF because it is easier and less expensive to construct high-gain, stable amplifiers for low frequency signals.
- IF amplifiers are also less likely to oscillate than their RF counterparts.

Detector section

- To convert the IF signals back to the original source information (demodulation).
- Can be as simple as a single diode or as complex as a PLL or balanced demodulator.

Audio amplifier section

 Comprises several cascaded audio amplifiers and one or more speakers
AGC (Automatic Gain Control)

- Adjust the IF amplifier gain according to signal level(to the average amplitude signal almost constant).
- AGC is a system by means of which the overall gain of radio receiver is varied automatically with the variations in the strength of received signals, to maintain the output constant.

- AGC circuit is used to adjust and stabilize the frequency of local oscillator.
- Types of AGC –
- ➢ No AGC
- ➢ Simple AGC
- ➢ Delayed AGC

- FREQUENCY CONVERSION in the mixer stage is identical to the frequency conversion in the modulator except that in the receiver, the frequencies are down-converted rather that up-converted.
 - In the mixer, RF signals are combined with the local oscillator frequency
 - The local oscillator is designed such that its frequency of oscillation is always above or below the desired RF carrier by an amount equal to the IF center frequency.
 - Therefore the difference of RF and oscillator frequency is always equal to the IF frequency

- The adjustment for the center frequency of the preselector and the local oscillator frequency are gang-tune (the two adjustments are tied together so that single adjustment will change the center frequency of the preselector and at the same time change the local oscillator)
- when local oscillator frequency is tuned above the RF *high side injection* when local oscillator frequency is tuned below the RF – *low side injection*
- Mathematically expressed : High side injection Low side injection

$$f_{lo} = f_{RF} + f_{IF}$$
$$f_{lo} = f_{RF} - f_{IF}$$



COMPARISON

TRF Receiver

- No frequency conversion
- No IF frequency
- Instability , variation in BW and poor selectivity due to high frequencies
- Difficult to design tunable RF stages.
- Rarely used

Super hetrodyne Receiver

- Frequency conversion
- Downconvert RF signal to lower IF frequency
- No instability, variation in BW and poor selectivity as IF introduced.
- Main amplifixcation takes place at IF
- Mostly used

CHARACTERISTICS OF RADIO RECEIVERS

- Sensitivity
- Selectivity
- Fidelity

Sensitivity

- Ability to amplify weak signals.
- Minimum RF signal level that can be detected at the input to the receiver and still produce a usable demodulated information signal.
- Broadcast receivers/ radio receivers should have reasonably high sensitivity so that it may have good response to the desired signal
- But should not have excessively high sensitivity otherwise it will pick up all undesired noise signals.
- It is function of receiver gain and measures in decibels.

- Sensitivity of a receiver is expressed in microvolts of the received signal.
- Typical sensitivity for commercial broadcast-band AM receiver is 50 μ V.
- Sensitivity of the receiver depends on :
 - 1.Noise power present at the input to the receiver
 - 2. Receiver noise figure
 - 3.Bandwidth improvement factor of the receiver

The best way to improve the sensitivity is to reduce the noise level.

Selectivity

Selectivity of radio receiver is its ability to differentiate desired signal from unwanted signals.



• Selectivity is obtained by using tuned circuits, which are tuned to desired frequency. The quality factor of these LC circuits determines the selectivity. It is given by,

Q=XL/R

• For better selectivity 'Q' should be high.

Fidelity

- Fidelity is defined as a measure of the ability of a communication system to produce an exact replica of the original source information at the output of the receiver.
- Any variations in the demodulated signal that are not in the original information signal is considered as distortion.
- Radio receiver should have high fidelity or accuracy.
- Example- In an A.M. broadcast the maximum audio frequency is 5 KHz hence receiver with good fidelity must produce entire frequency up to 5KHz.

IMAGE FREQUENCY

- In radio reception using heterodyning in the tuning process, an undesired input frequency that is capable of producing the same intermediate frequency (IF) that the desired input frequency produces.
- Image frequency any frequency other than the selected radio frequency carrier that will produce a cross-product frequency that is equal to the intermediate frequency if allowed to enter a receiver and mix with the local oscillator.
- It is given by signal frequency plus twice the intermediate frequency

fsi = fs + 2fi

- It is equivalent to a second radio frequency that will produce an IF that will interfere with the IF from the desired radio frequency.
 - if the selected RF carrier and its image frequency enter a receiver at a same time, they both mix with the local oscillator frequency and produce different frequencies that are equal to the IF.
 - Consequently, two different stations are received and demodulated simultaneously

- The higher the IF, the farther away the image frequency is from the desired radio frequency.
 Therefore, for better image frequency rejection, a high IF is preferred.
- However, the higher the IF, it is more difficult to build a stable amplifier with high gain. i.e. there is a trade-off when selecting the IF for a radio receiver (image frequency rejection vs IF gain and stability)



MATHEMATICAL ANALYSIS

- Basic principle with two frequencies component f1 and f2,we have harmonics f1,f2,f1+f2,f1-f2
- In case of radio receivers, two frequency components are fo and fs
- So harmonic we have fo,fs,fo+fs,fo-fs
- Let Undesired frequency fsi(=fo+fif) able to reach at the mixer
- So now two frequency components will be fo (local oscillator) and fsi (undesired freq)
- And harmonics will be fo,fsi,fo+fsi,fo-fsi

- And harmonics will be fo,fsi,fo+fsi,fo-fsi
- Substituting value of fsi we have
- fo,fo+fs,2fo+fif,fif
- It was observed that difference component is a mirror image of IF
 - Consequently, 2 different stations are received and demodulated simultaneously

• Once an image frequency has down-converted to IF, it cannot be removed. In order to reject the image frequency, it has to be blocked prior to the mixer stage. the bandwidth of the pre-selector must be sufficiently narrow to prevent image frequency from entering the receiver.



CHOICE OF IF

- Very high IF will result in poor selectivity and poor adjacent channel rejection
- A high value of IF will result in tracking difficulties
- At low values of IF image frequency rejection is poor. Also the selectivity will be too sharp that cut off the sidebands

Pulse Amplitude Modulation (PAM)

If a message waveform is adequately described by periodic sample values, it can be transmitted using analogue pulse modulation wherein the sample values modulate the amplitude of pulse train.



Generation of the PAM signal

- There are two operations involved in the generation of the PAM signal:
- 2. Instantaneous sampling of the message signal x(t) every Ts seconds, where the sampling rate fs = 1/Ts is chosen in accordance with the sampling theorem
- **3.** Lengthening the duration of each sample so obtained to some constant value τ (sample-and-hold)



Flat-top Sampling and PAM

- Practical method for obtaining PAM (or implementing the steps 1. and 2. is the *sample-and-hold* (S/H) technique.
- This method produces flat-top pulses





PAM

- Flat-top sampling is equivalent to passing an *ideal sampled wave* through a network having *transfer function* P(f) = F[p(t)]
- Loss of high frequency content is called aperture effect
- The larger the pulse duration or aperture τ, the larger the effect





PAM

- There are many similarities between PAM and AM CW modulation
 - Modulation index
 - Spectral impulses
 - DC block
- PAM spectrum extends from DC up through several harmonics of f_s
- Required transmission bandwidth can be estimated based on timedomain considerations
- Assuming small pulse duration compared to time between pulses

$$\tau \ll T_s \leq \frac{1}{2W}$$

Adequate pulse resolution then requires Transmission Bandwidth

$$B_T \geq \frac{1}{2\tau} \gg W$$

Use PAM when transmitting pulses is advantageous and BW is not an issue

Pulse-Time Modulation (PTM)

- The sample values of a message can also modulate the time parameters of a pulse train:
- 1. Pulse width pulse-duration modulation (PDM)
- 2. Pulse position pulse-position modulation (PPM)
- The pulse width or pulse position varies in direct proportion to the sample values of x(t)

Pulse-Duration and Pulse-Position Modulation

- In both cases a time parameter of the pulse is being modulated
- In both cases amplitude remains constant
 - robust to nonlinear amplitude distortion (phase is important)
- Methods for producing PDM and PPM are similar



Generation of PDM and PPM

- When x(t) exceeds the sawtooth wave (period T_s) comparator output is a positive constant A
- Otherwise comparator output is zero
- This is an example of PDM with trailing edge modulation of the pulse duration
 - Reverse sawtooth for leading edge PDM
 - Triangle for both edges
- For PPM signal, the PDM signal triggers a monostable pulse generator (triggers on trailing edge and produces short pulse of fixed duration



Generation of PDM

• An approximation for the PDM can be formulated if we assume rectangular pulses centred at $t = kT_s$ and assuming t_k varies slowly from pulse to pulse. Fourier Series expansion is

$$x_p(t) \approx Af_s \tau_0[1 + \mu x(t)] + \sum_{n=1}^{\infty} \frac{2A}{\pi n} \sin n\phi(t) \cos n\omega_s t$$

where

$$\phi(t) = \pi f_s \tau_0 [1 + \mu x(t)].$$

- PDM signal contains the message signal plus a dc component and *phase modulated* signal at the harmonics of f_s
- Message (c₁) recovered with LPF and DC block