

# NETWORK THEORY

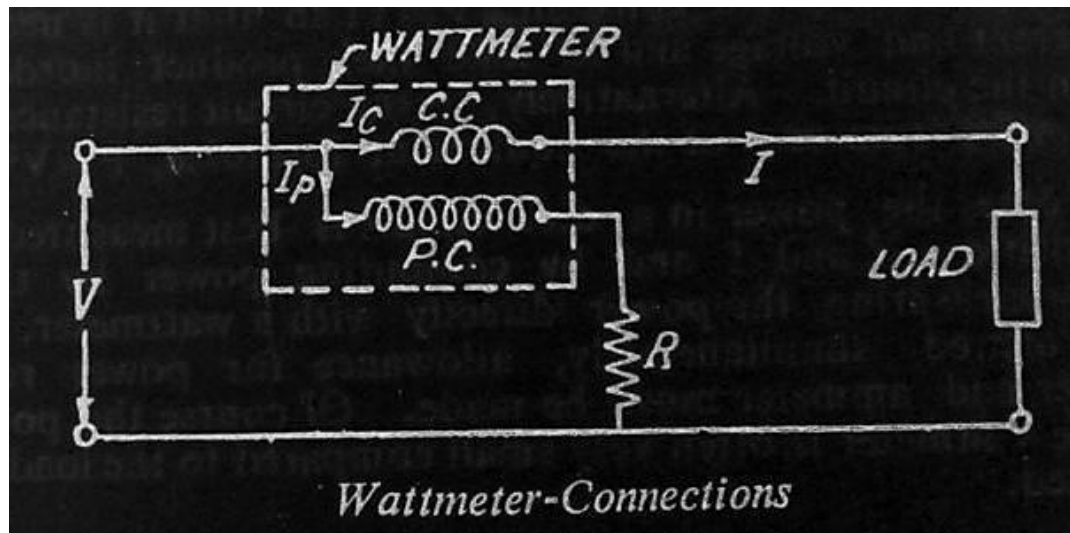
## POWER POINT PRESENTATION

PREPARED BY:

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# Wattmeter

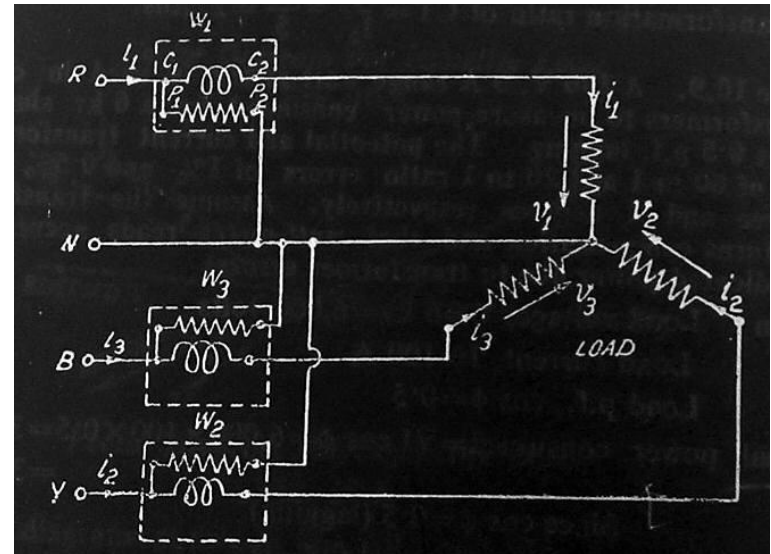
- A wattmeter is essentially an inherent combination of an ammeter and a voltmeter and, therefore, consists of two coils known as *current coil* and *pressure coil*.
- Wattmeter connection:



# Measurement of Power in 3-Phase Circuit

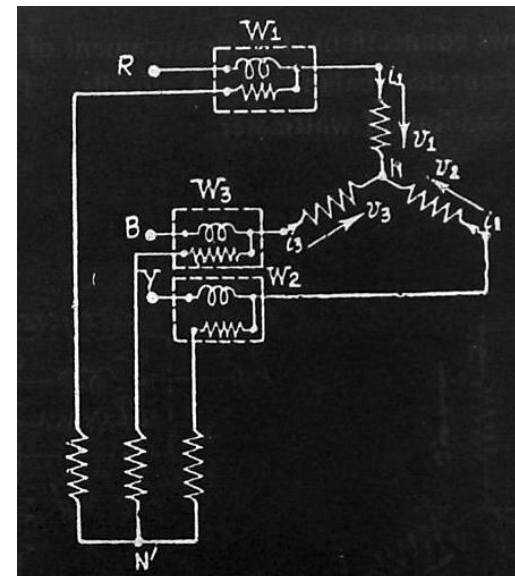
- Measurement of power in 3-phase, 4-wire circuits-----→

- $P = W_1 + W_2 + W_3$

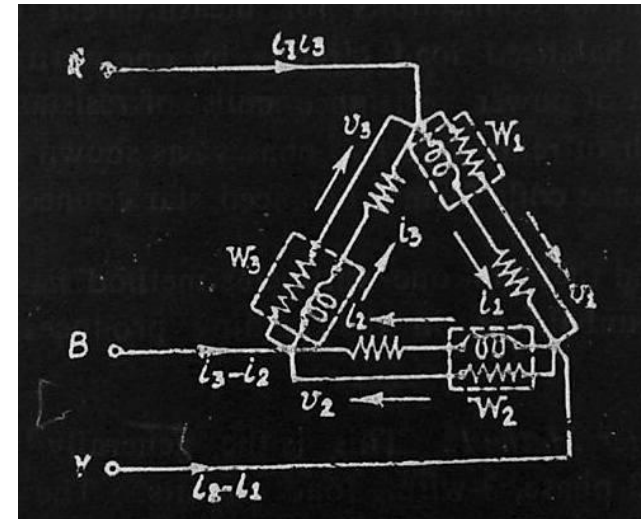


- Measurement of power in 3-phase, 3-wire circuits-----→

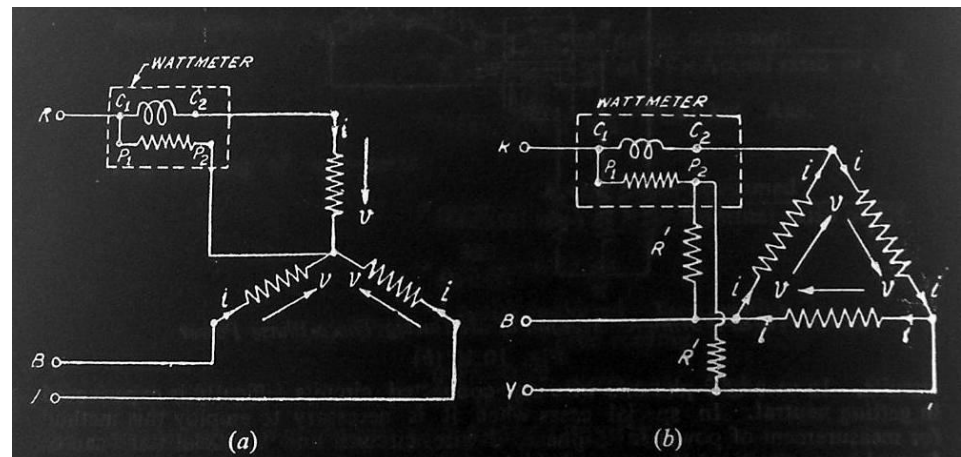
- $P = W_1 + W_2 + W_3$



- 3-wattmeter method of measuring 3-phase power of delta connected
- $P = W_1 + W_2 + W_3$



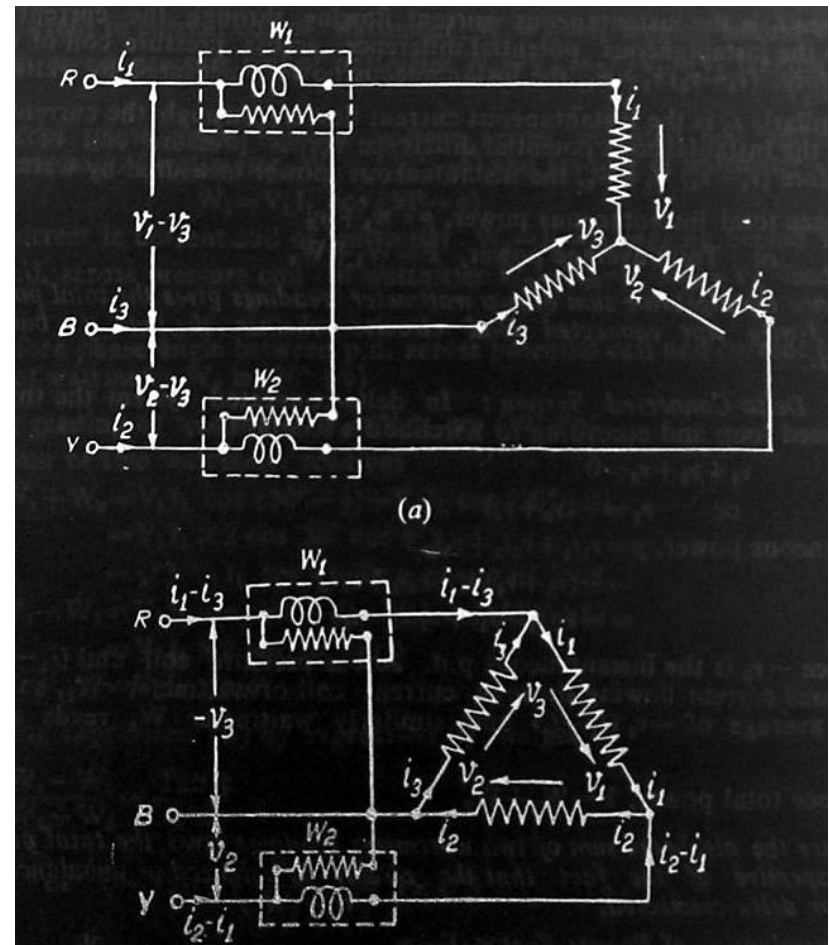
- 1-wattmeter method of measuring balanced 3-phase power (a) star connected, (b) delta connected
- $P = 3W$



- 2-wattmeter method of measuring 3-phase 3-wire power :

- (a) star connected,
- $P=W_1+W_2$

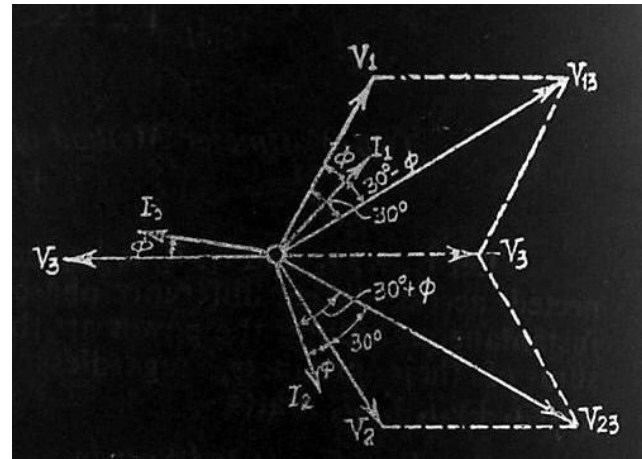
- (b) delta connected
- $P=W_1+W_2$



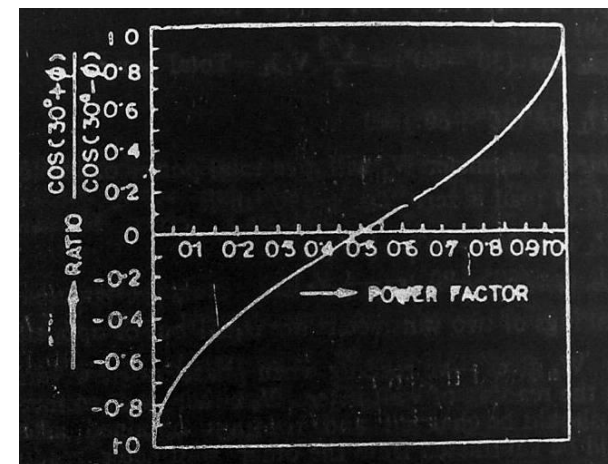
# Determination of P.F. from Wattmeter Reading

- If load is balanced, then p.f. of the load can be determined from the wattmeter readings
- Vector diagram for balanced star connected inductive load ----->

$$\cos \varphi = \cos \tan^{-1} \frac{\sqrt{3}(W_1 - W_2)}{W_1 + W_2}$$



- The watt-ratio Curve ----->
- p.f. can be determined from reading of two wattmeters



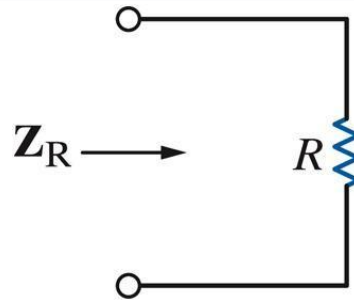


# AC STEADY STATE ANALYSIS

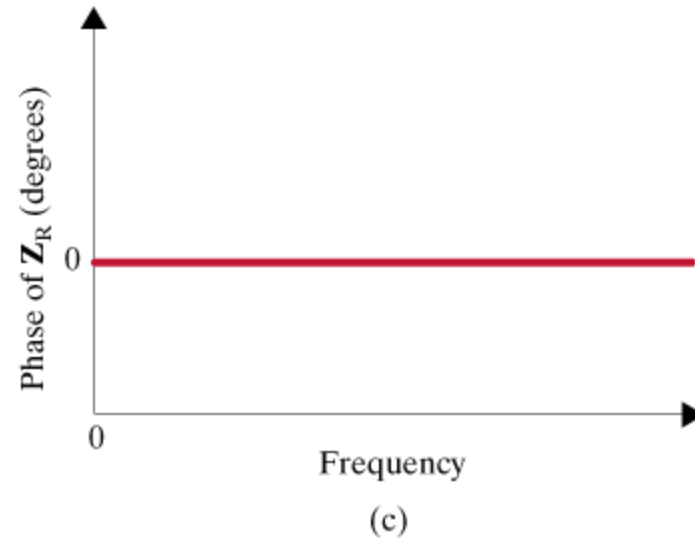
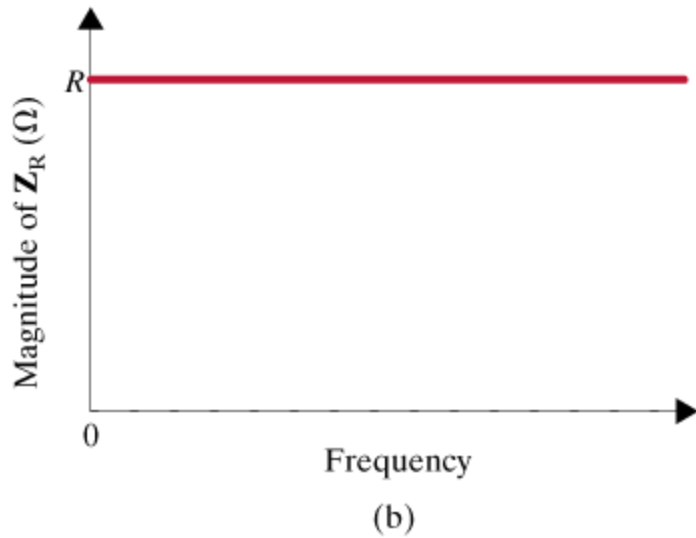
In AC steady state analysis the frequency is assumed constant (e.g., 60Hz). Here we consider the frequency as a variable and examine how the performance varies with the frequency.

## Variation in impedance of basic components

Resistor

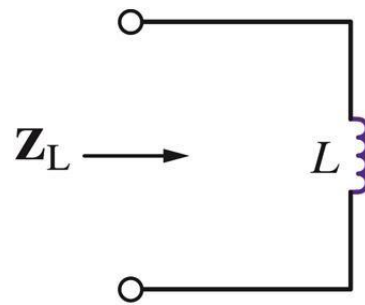


$$Z_R = R = R \angle 0^\circ$$

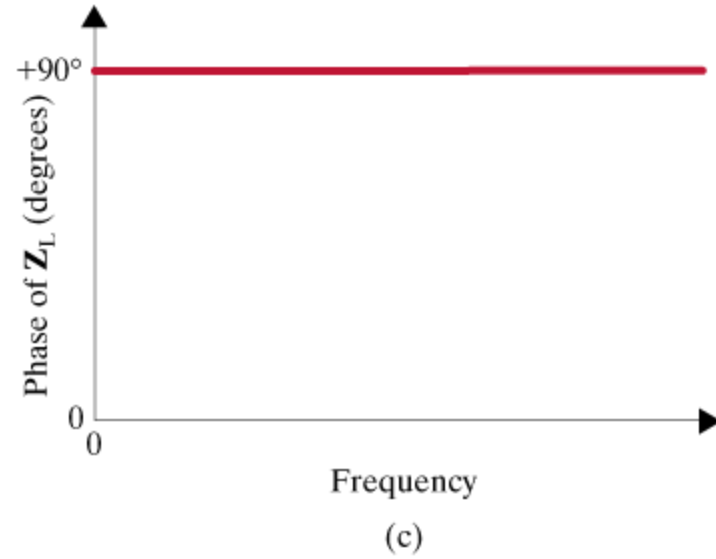
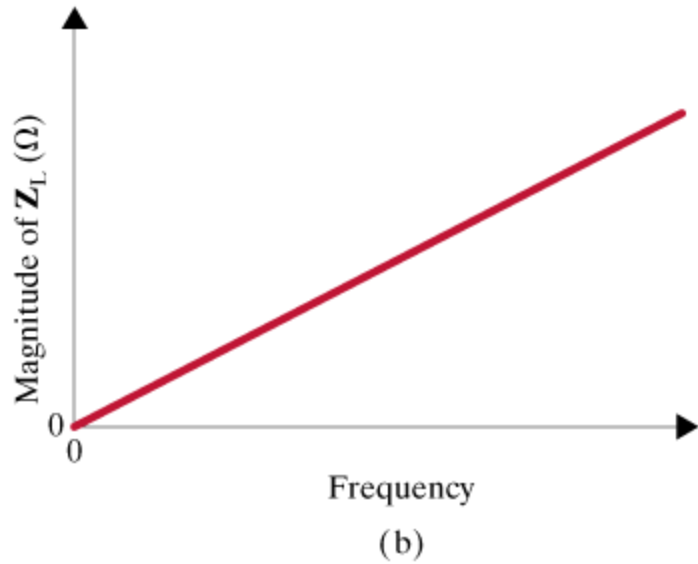




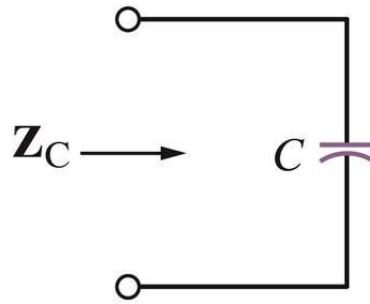
Inductor



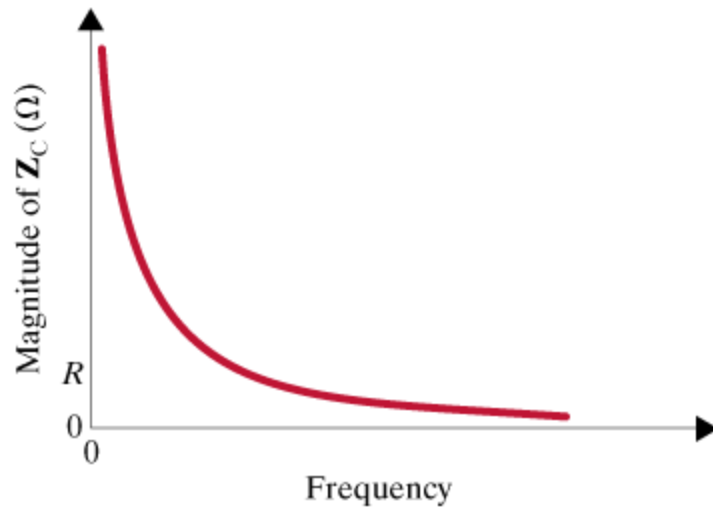
$$\mathbf{Z}_L = j\omega L = \omega L \angle 90^\circ$$



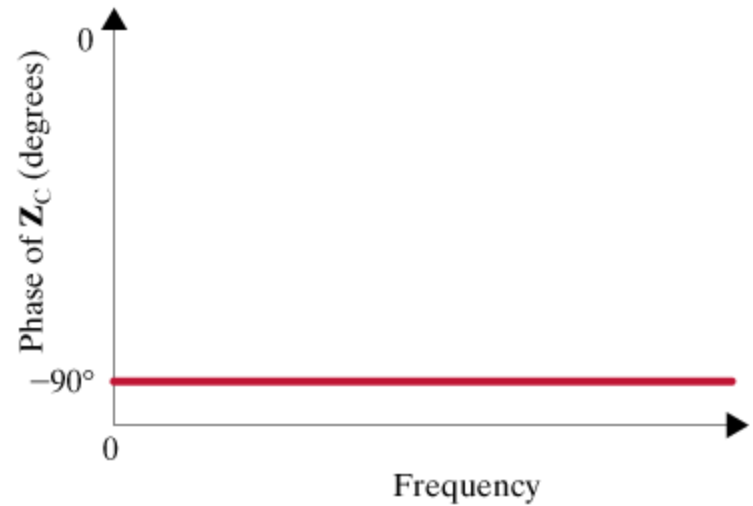
Capacitor



$$Z_c = \frac{1}{j\omega C} = \frac{1}{\omega C} \angle -90^\circ$$

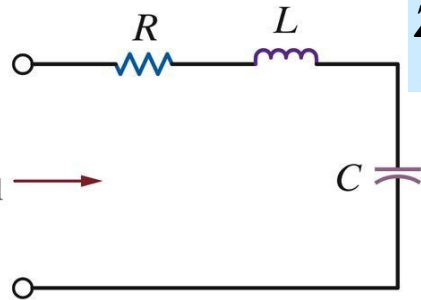


(b)



(c)

# Frequency dependent behavior of series RLC network



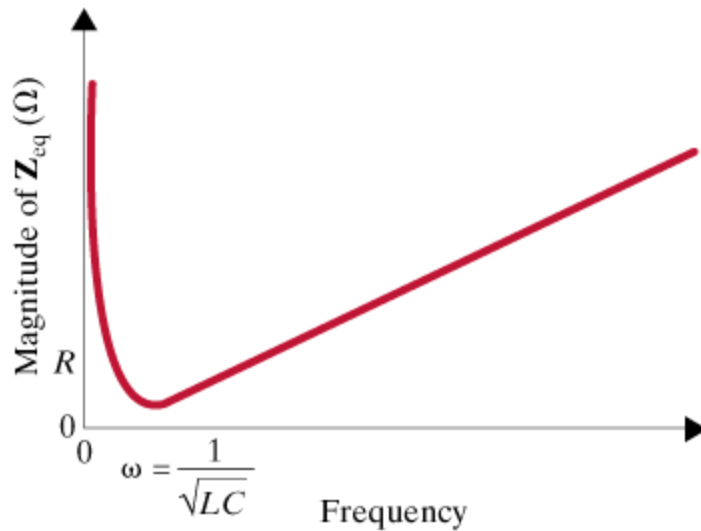
$$Z_{eq} = R + j\omega L + \frac{1}{j\omega C} = \frac{(j\omega)^2 LC + j\omega RC + 1}{j\omega C} \times \frac{-j}{-j} = \frac{\omega RC + j(\omega^2 LC - 1)}{\omega C}$$

"Simplification in notation"  $j\omega \approx s$

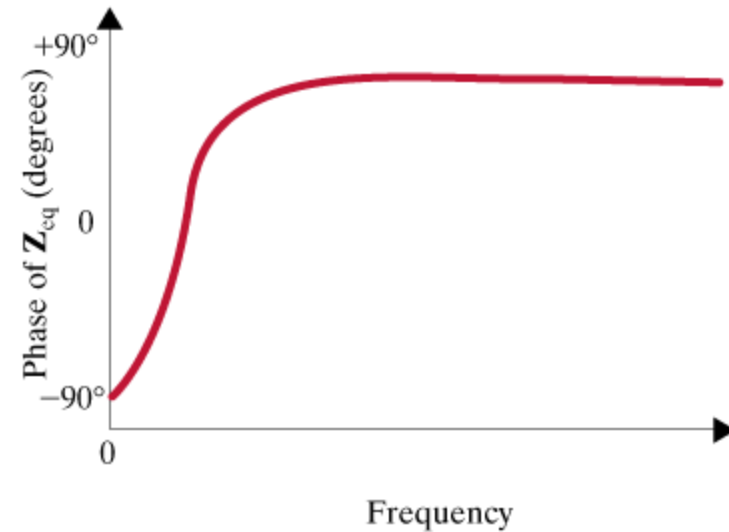
$$Z_{eq}(s) = \frac{s^2 LC + sRC + 1}{sC}$$

$$|Z_{eq}| = \frac{\sqrt{(\omega RC)^2 + (1 - \omega^2 LC)^2}}{\omega C}$$

$$\angle Z_{eq} = \tan^{-1} \left( \frac{\omega^2 LC - 1}{\omega RC} \right)$$



(b)



(c)



## Simplified notation for basic components

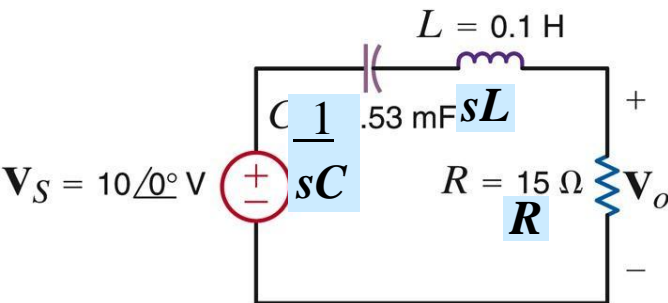
$$\mathbf{Z}_R(s) = R, \mathbf{Z}_L(s) = sL, \mathbf{Z}_C = \frac{1}{sC}$$

For all cases seen, and all cases to be studied, the impedance is of the form

$$\mathbf{Z}(s) = \frac{a_m s^m + a_{m-1} s^{m-1} + \dots + a_1 s + a_0}{b_n s^n + b_{n-1} s^{n-1} + \dots + b_1 s + b_0}$$

Moreover, if the circuit elements (L,R,C, dependent sources) are real then the expression for any voltage or current will also be a rational function in  $s$

### LEARNING EXAMPLE



$$V_o(s) = \frac{R}{R + sL + 1/sC} V_S = \frac{sRC}{s^2 LC + sRC + 1} V_S$$

$$s \approx j\omega$$

$$V_o = \frac{j\omega RC}{(j\omega)^2 LC + j\omega RC + 1} V_S$$

$$V_o = \frac{j\omega(15 \times 2.53 \times 10^{-3})}{(j\omega)^2(0.1 \times 2.53 \times 10^{-3}) + j\omega(15 \times 2.53 \times 10^{-3}) + 1} 10\angle 0^\circ$$



# NETWORK FUNCTIONS

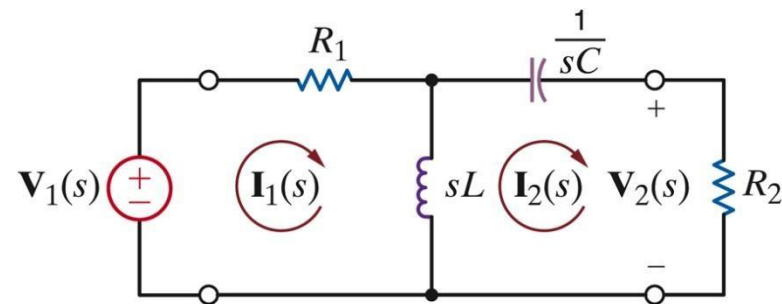
## Some nomenclature

When voltages and currents are defined at different terminal pairs we define the ratios as **Transfer Functions**

INPUT	OUTPUT	TRANSFER FUNCTION	SYMBOL
Voltage	Voltage	Voltage Gain	<b><math>G_v(s)</math></b>
Current	Voltage	Transimpedance	<b><math>Z(s)</math></b>
Current	Current	Current Gain	<b><math>G_i(s)</math></b>
Voltage	Current	Transadmittance	<b><math>Y(s)</math></b>

If voltage and current are defined at the same terminals we define **Driving Point Impedance/Admittance**

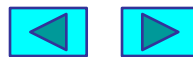
### EXAMPLE



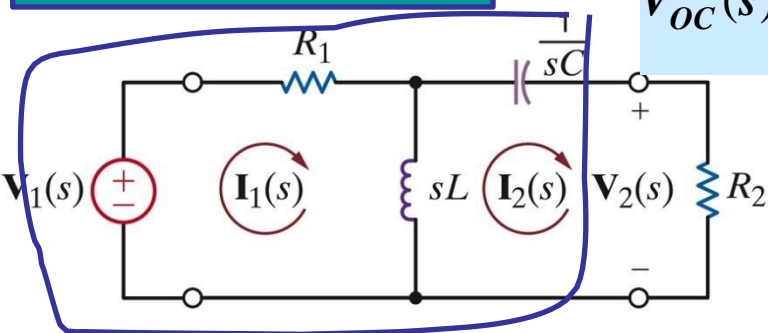
To compute the transfer functions one must solve the circuit. Any valid technique is acceptable

$$Y_T(s) = \frac{I_2(s)}{V_1(s)} \begin{cases} \text{Transadmittance} \\ \text{Transfer admittance} \end{cases}$$

$$G_v(s) = \frac{V_2(s)}{V_1(s)} \quad \text{Voltage gain}$$



# LEARNING EXAMPLE



$$V_{OC}(s) = \frac{sL}{sL + R_1} V_1(s)$$

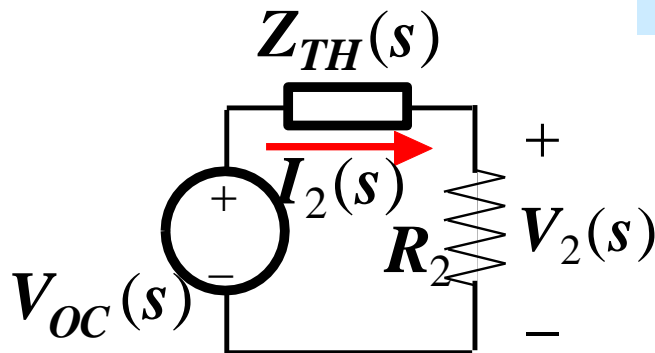
The textbook uses mesh analysis. We will use Thevenin's theorem

$$Z_{TH}(s) = \frac{1}{sC} + R_1 \parallel sL = \frac{1}{sC} + \frac{sLR_1}{sL + R_1}$$

$$Z_{TH}(s) = \frac{s^2 LCR_1 + sL + R_1}{sC(sL + R_1)}$$

$$Y_T(s) = \frac{I_2(s)}{V_1(s)} \begin{cases} \text{Transadmittance} \\ \text{Transfer admittance} \end{cases}$$

$$G_v(s) = \frac{V_2(s)}{V_1(s)} \quad \text{Voltage gain}$$



$$I_2(s) = \frac{V_{OC}(s)}{R_2 + Z_{TH}(s)} = \frac{\frac{sL}{sL + R_1} V_1(s)}{R_2 + \frac{s^2 LCR_1 + sL + R_1}{sC(sL + R_1)}} \times \frac{sC(sL + R_1)}{sC(sL + R_1)}$$

$$Y_T(s) = \frac{s^2 LC}{s^2 (R_1 + R_2) LC + s(L + R_1 R_2 C) + R_1}$$

$$G_v(s) = \frac{V_2(s)}{V_1(s)} = \frac{R_2 I_2(s)}{V_1(s)} = R_2 Y_T(s)$$

## POLES AND ZEROS (More nomenclature)

$$H(s) = \frac{a_m s^m + a_{m-1} s^{m-1} + \dots + a_1 s + a_0}{b_n s^n + b_{n-1} s^{n-1} + \dots + b_1 s + b_0}$$

Arbitrary network function

Using the roots, every (monic) polynomial can be expressed as a product of first order terms

$$H(s) = K_0 \frac{(s - z_1)(s - z_2) \dots (s - z_m)}{(s - p_1)(s - p_2) \dots (s - p_n)}$$

$z_1, z_2, \dots, z_m$  = zeros of the network function

$p_1, p_2, \dots, p_n$  = poles of the network function

The network function is uniquely determined by its poles and zeros and its value at some other value of  $s$  (to compute the gain)

### EXAMPLE

zeros :  $z_1 = -1$ ,

poles :  $p_1 = -2 + j2, p_2 = -2 - j2$

$H(0) = 1$

$$H(s) = K_0 \frac{(s + 1)}{(s + 2 - j2)(s + 2 + j2)} = K_0 \frac{s + 1}{s^2 + 4s + 8}$$

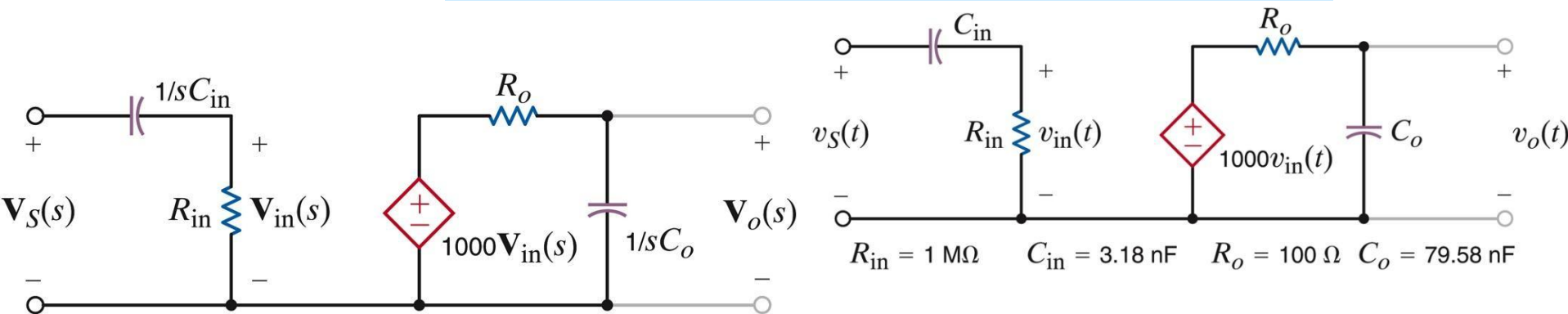
$$H(0) = K_0 \frac{1}{8} = 1 \Rightarrow H(s) = 8 \frac{s + 1}{s^2 + 4s + 8}$$



## LEARNING EXTENSION

Find the pole and zero locations and the value of  $K_o$

for the voltage gain  $G(s) = \frac{V_o(s)}{V_S(s)}$



$$H(s) = K_o \frac{(s - z_1)(s - z_2) \dots (s - z_m)}{(s - p_1)(s - p_2) \dots (s - p_n)}$$

Zeros = roots of numerator  
Poles = roots of denominator

For this case the gain was shown to be

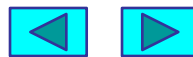
$$G(s) = \left[ \frac{sC_{in}R_{in}}{1 + sC_{in}R_{in}} \right] [1000] \left[ \frac{1}{1 + sC_oR_o} \right] = \left[ \frac{s}{s + 100\pi} \right] [1000] \left[ \frac{40,000\pi}{s + 40,000\pi} \right]$$

zero :  $z_1 = 0$

poles :  $p_1 = -50\text{Hz}$ ,  $p_2 = -20,000\text{Hz}$

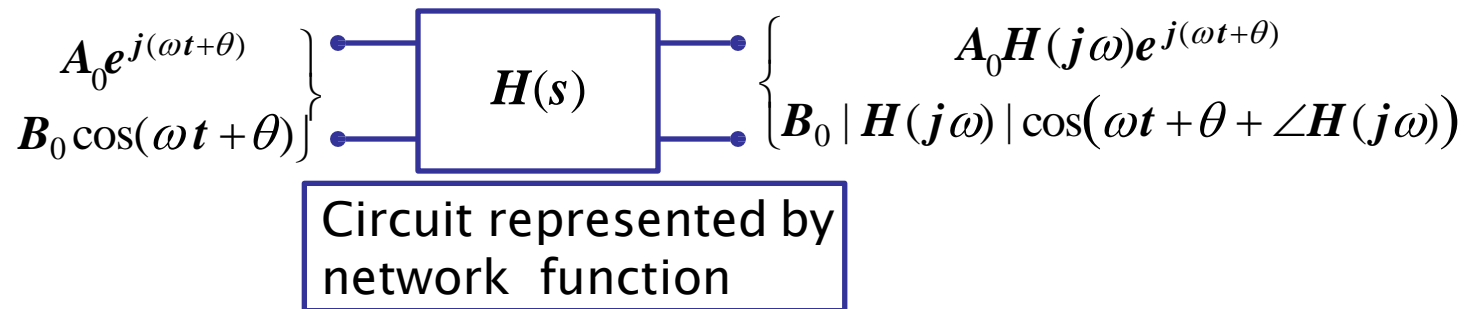
$K_o = (4 \times 10^7)\pi$

Variable  
Frequency  
Response





# SINUSOIDAL FREQUENCY ANALYSIS



To study the behavior of a network as a function of the frequency we analyze the network function  $H(j\omega)$  as a function of  $\omega$ .

Notation

$$M(\omega) = |H(j\omega)|$$

$$\phi(\omega) = \angle H(j\omega)$$

$$H(j\omega) = M(\omega) e^{j\phi(\omega)}$$

Plots of  $M(\omega)$ ,  $\phi(\omega)$ , as function of  $\omega$  are generally called magnitude and phase characteristics.

$$\text{BODE PLOTS} \begin{cases} 20 \log_{10}(M(\omega)) \\ \phi(\omega) \end{cases} \text{ vs } \log_{10}(\omega)$$



## HISTORY OF THE DECIBEL

Originated as a measure of relative (radio) power

$$P_2|_{dB} \text{ (over } P_1) = 10 \log \frac{P_2}{P_1}$$

$$P = I^2 R = \frac{V^2}{R} \Rightarrow P_2|_{dB} \text{ (over } P_1) = 10 \log \frac{V_2^2}{V_1^2} = 10 \log \frac{I_2^2}{I_1^2}$$

By extension

$$V|_{dB} = 20 \log_{10} |V|$$

$$I|_{dB} = 20 \log_{10} |I|$$

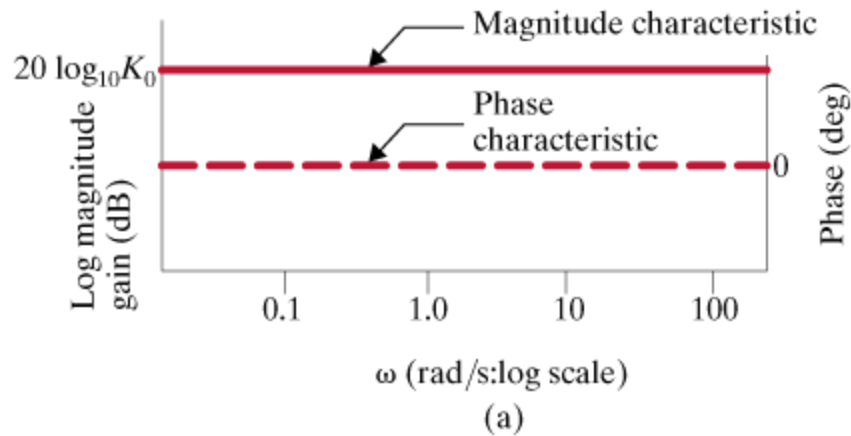
$$G|_{dB} = 20 \log_{10} |G|$$

Using log scales the frequency characteristics of network functions have simple asymptotic behavior.

The asymptotes can be used as reasonable and efficient approximations



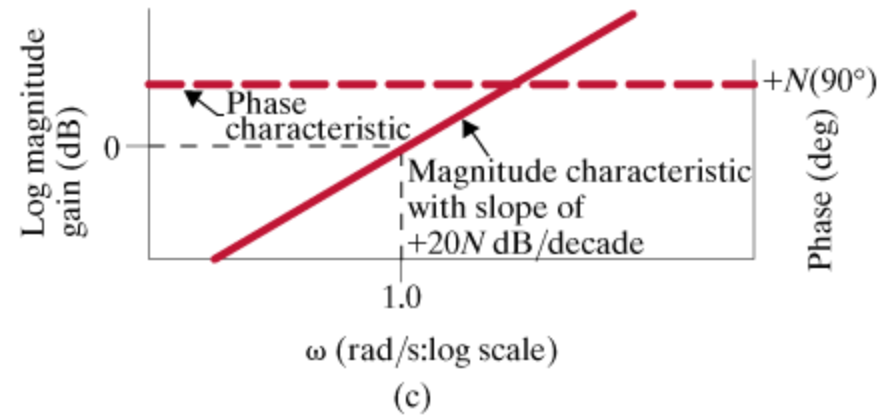
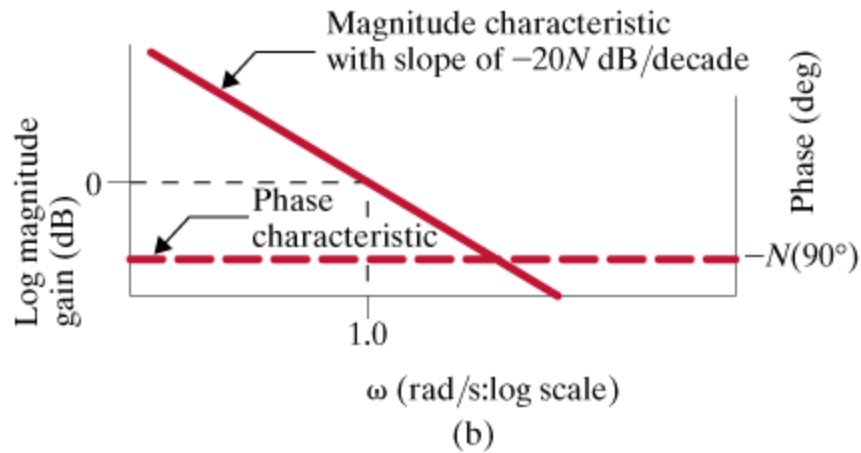
## Constant Term

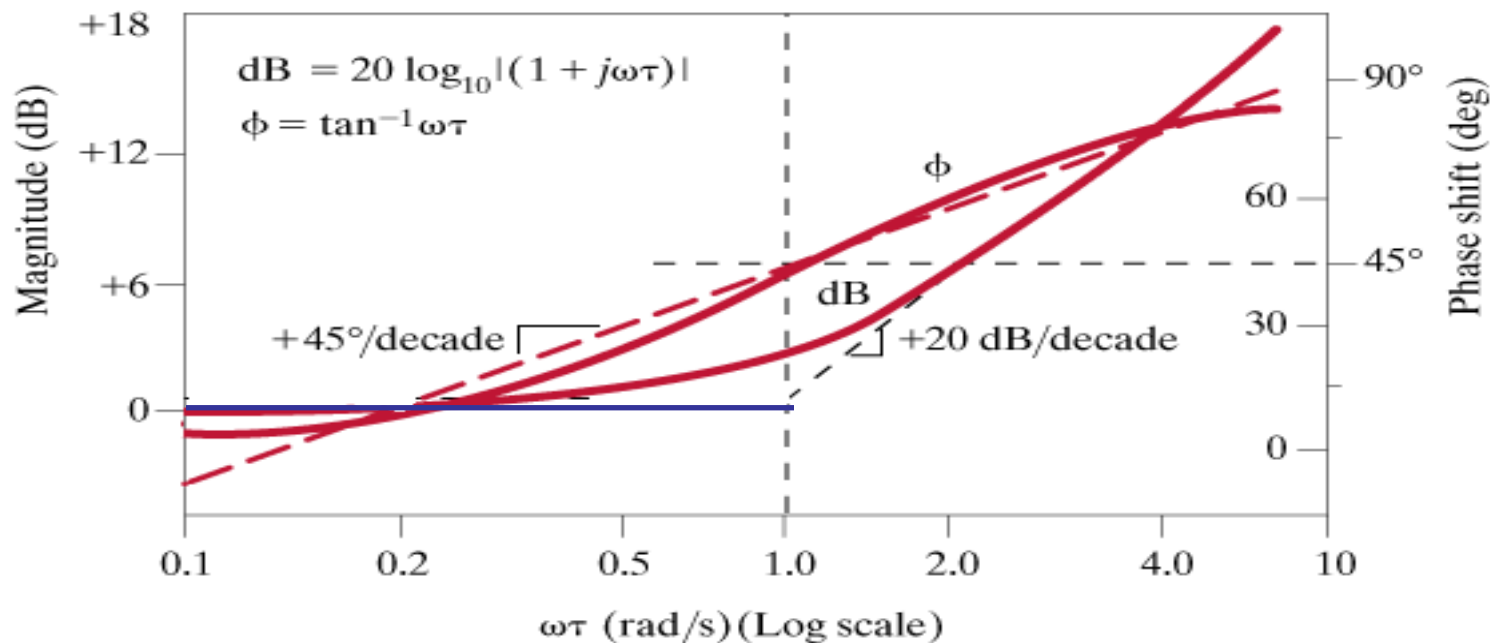


the x - axis is  $\log_{10} \omega$   
this is a straight line

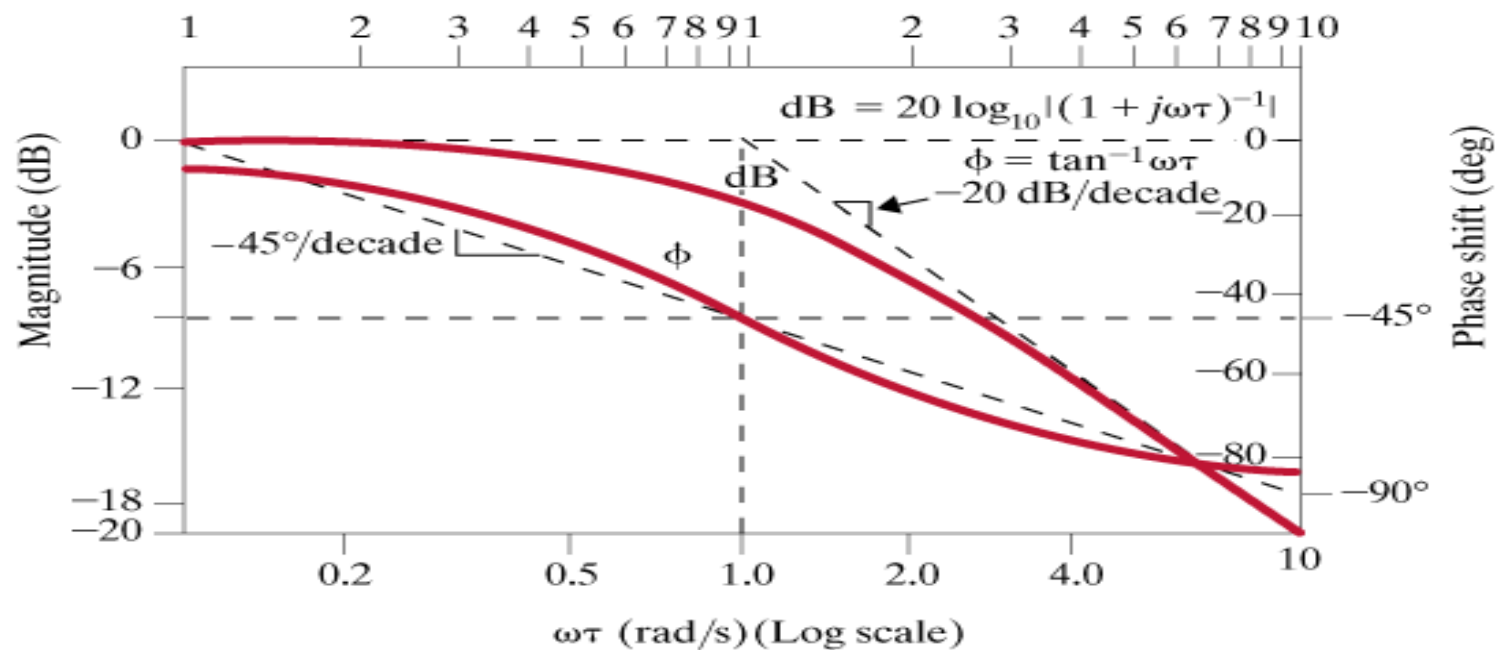
## Poles/Zeros at the origin

$$(j\omega)^{\pm N} \rightarrow \begin{cases} |(j\omega)^{\pm N}|_{dB} = \pm N \times 20 \log_{10}(\omega) \\ \angle(j\omega)^{\pm N} = \pm N 90^\circ \end{cases}$$



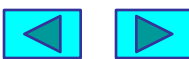


Simple zero



Simple pole

(a)



## LEARNING EXAMPLE

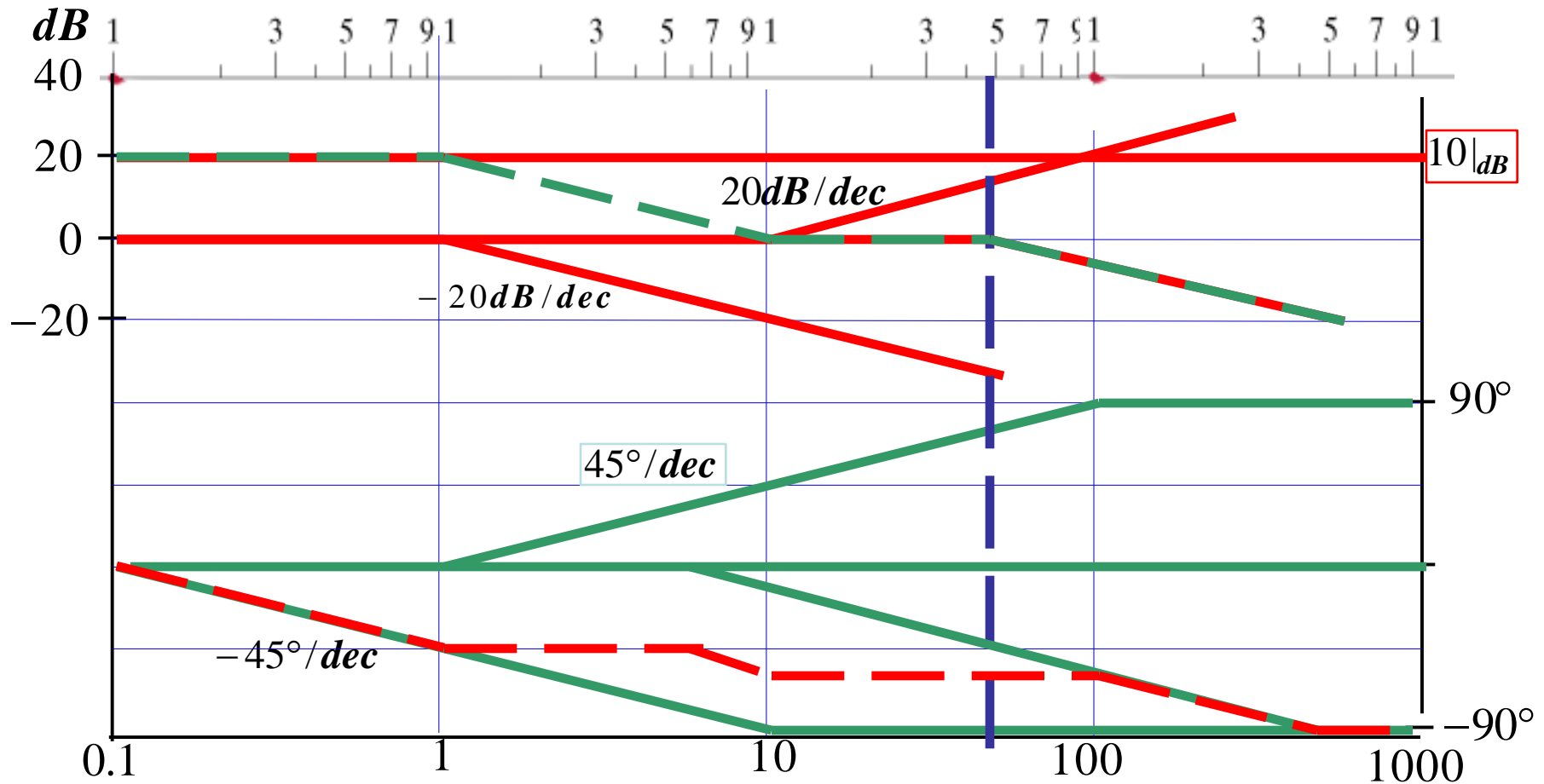
Draw asymptotes  
for each term

Draw composites

Generate magnitude and phase plots

$$G(j\omega) = \frac{10(0.1j\omega+1)}{(j\omega+1)(0.02j\omega+1)}$$

Breaks/corners : 1,10,50



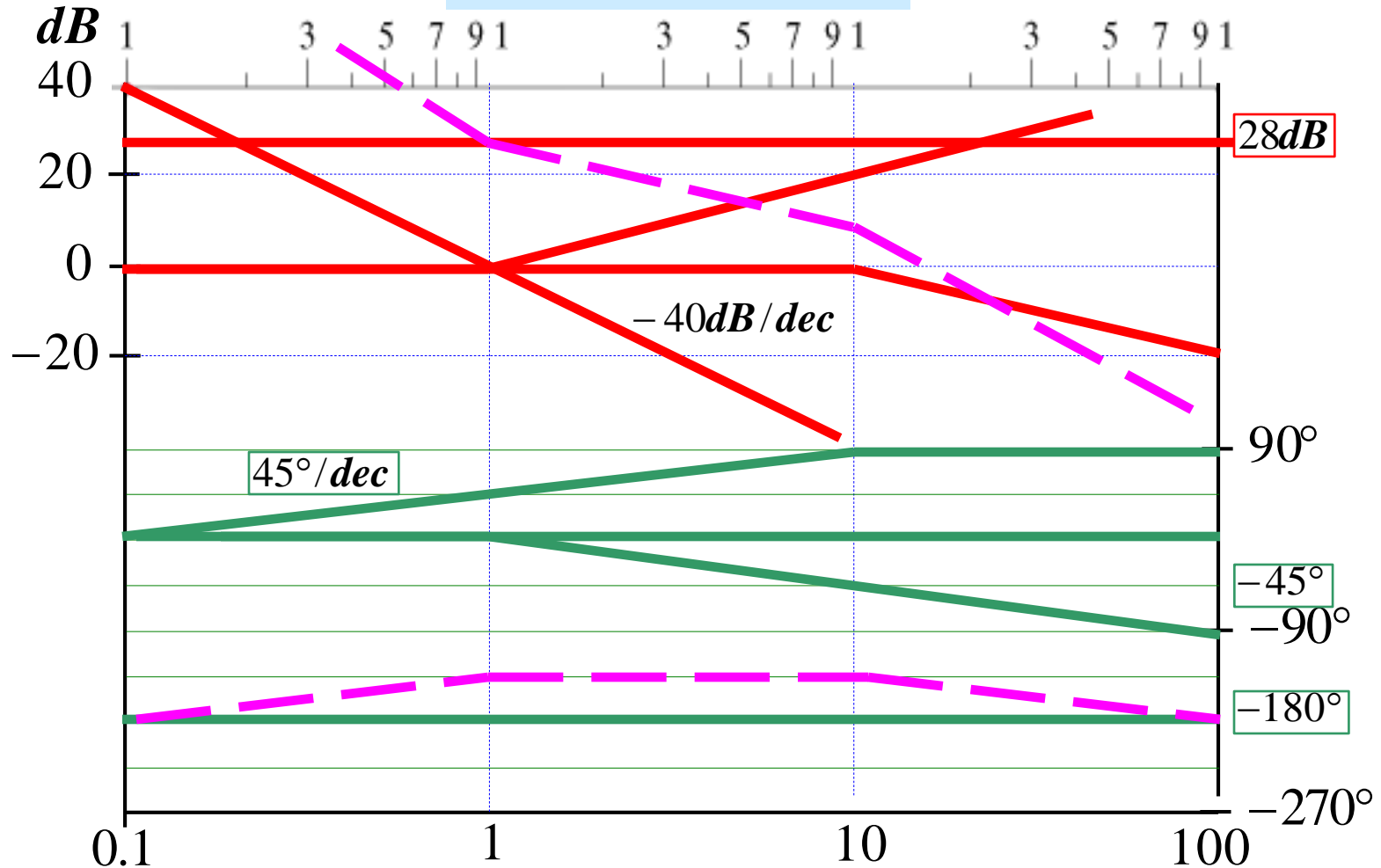
# LEARNING EXAMPLE

Generate magnitude and phase plots

$$G(j\omega) = \frac{25(j\omega + 1)}{(j\omega)^2(0.1j\omega + 1)}$$

Breaks (corners) : 1, 10

Form composites



# LEARNING EXTENSION

Sketch the magnitude characteristic

$$G(j\omega) = \frac{10^4(j\omega + 2)}{(j\omega + 10)(j\omega + 100)}$$

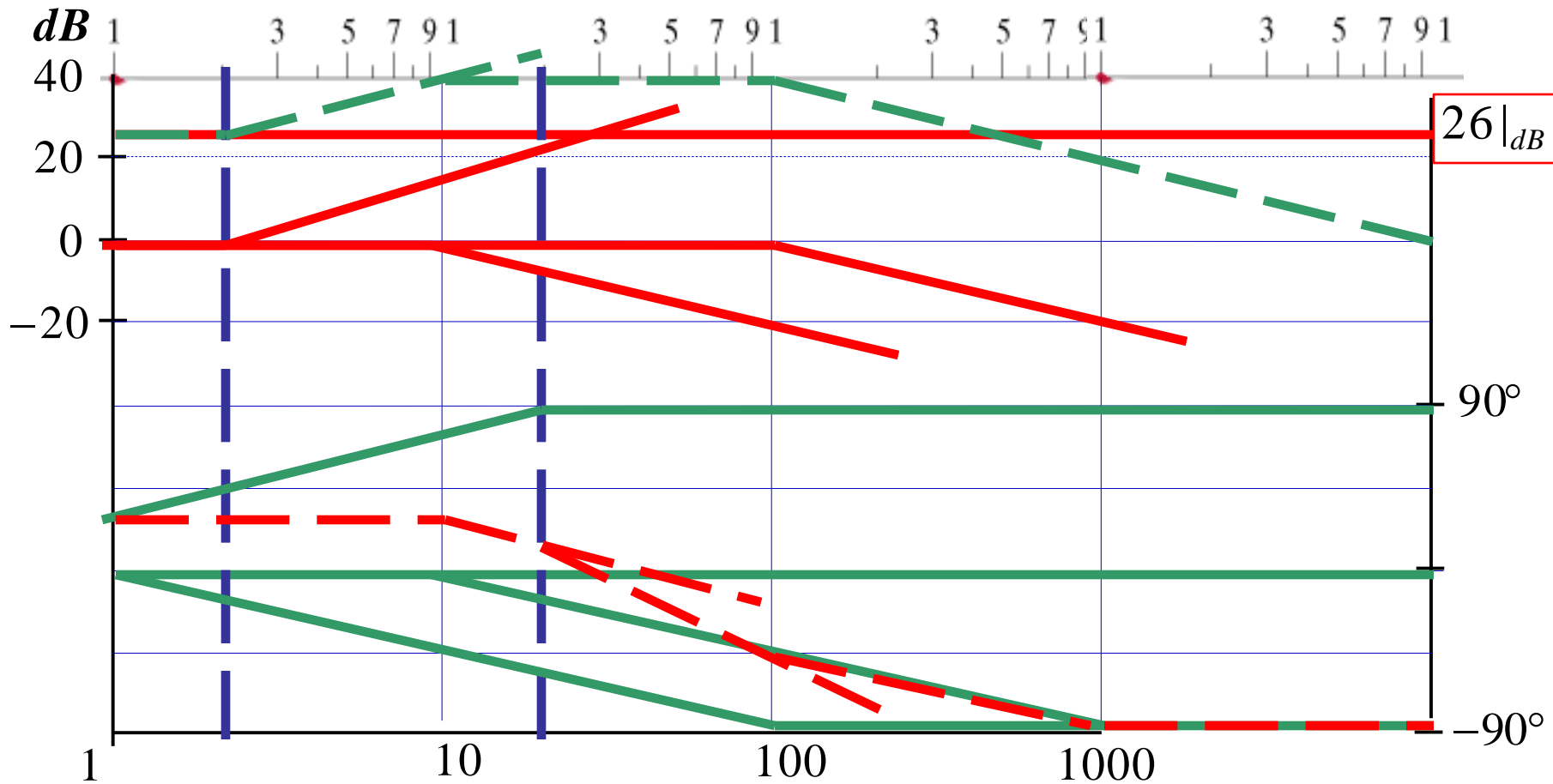
breaks : 2, 10, 100

But the function is NOT in standard form

Put in standard form

$$G(j\omega) = \frac{20}{(j\omega/10 + 1)(j\omega/100 + 1)}$$

We need to show about 4 decades



## LEARNING EXTENSION

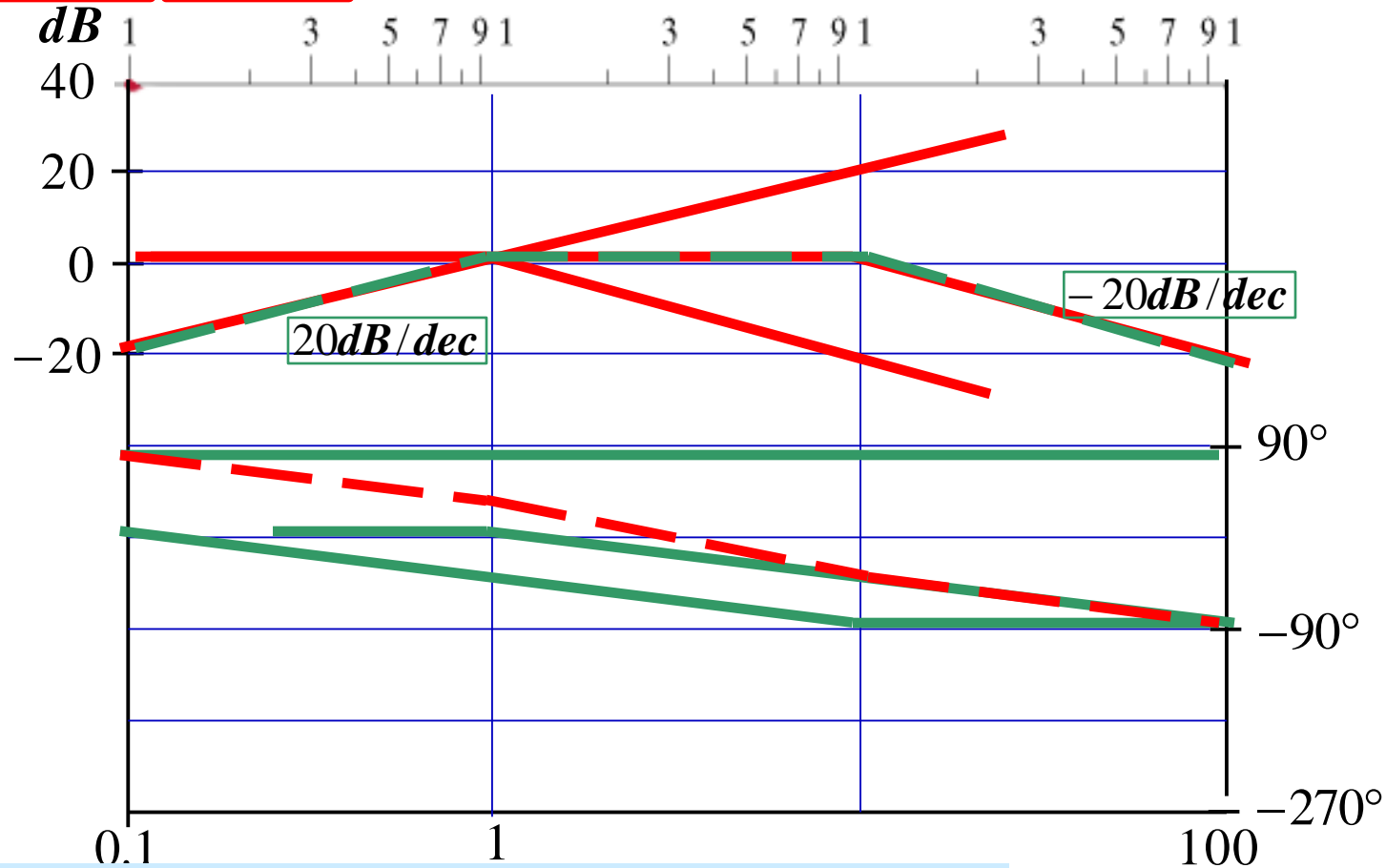
Put in standard form

$$G(j\omega) = \frac{j\omega}{(j\omega+1)(j\omega/10+1)}$$

Sketch the magnitude characteristic

$$G(j\omega) = \frac{10j\omega}{(j\omega+1)(j\omega+10)}$$

not in standard form  
zero at the origin  
breaks : 1, 10



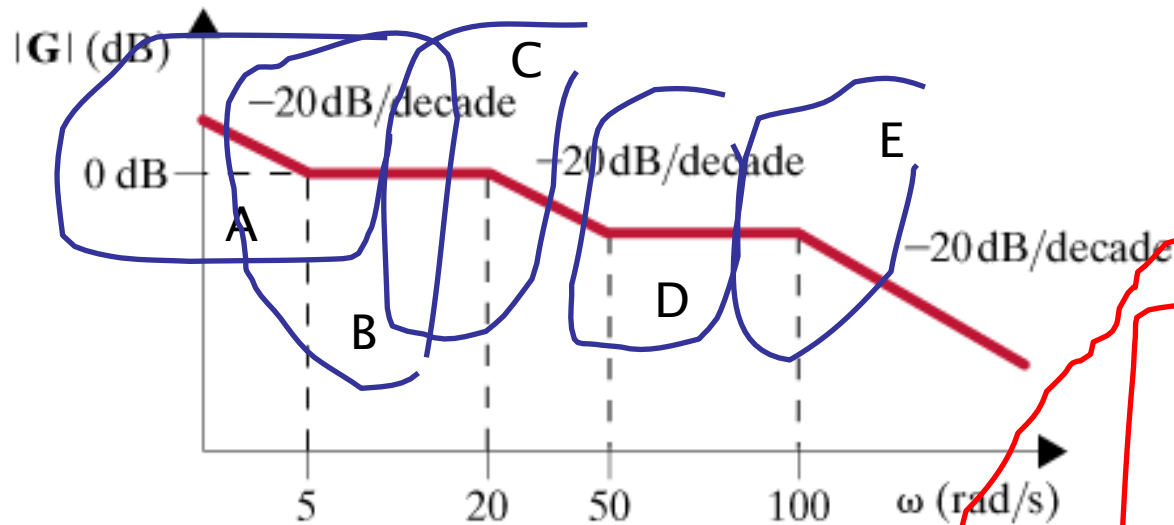
Once each term is drawn we form the composites





## LEARNING EXTENSION

Determine a transfer function from the composite magnitude asymptotes plot



A. Pole at the origin.  
Crosses 0dB line at 5

$$\frac{5}{j\omega}$$

B. Zero at 5

C. Pole at 20

D. Zero at 50

E. Pole at 100

$$G(j\omega) = \frac{5(j\omega/5 + 1)(j\omega/50 + 1)}{j\omega(j\omega/20 + 1)(j\omega/100 + 1)}$$

Sinusoidal

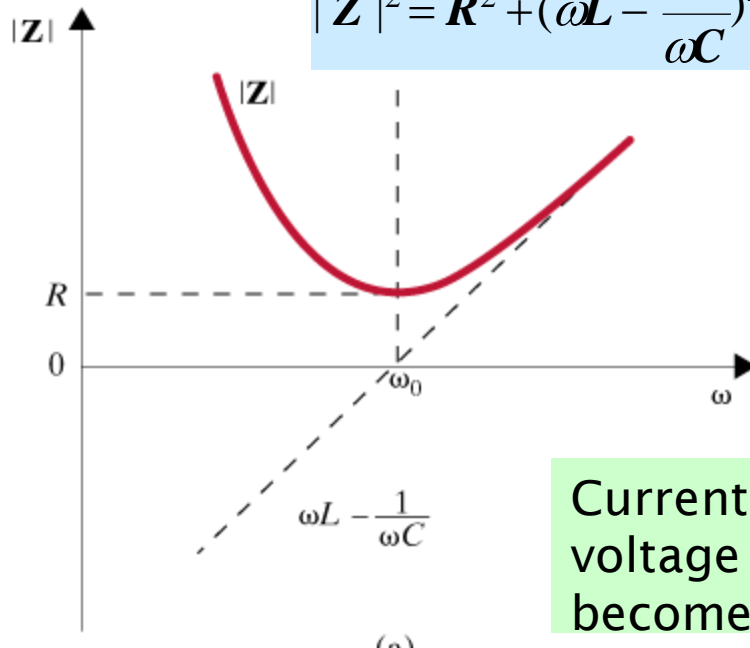


## Properties of resonant circuits

At resonance the impedance/admittance is minimal

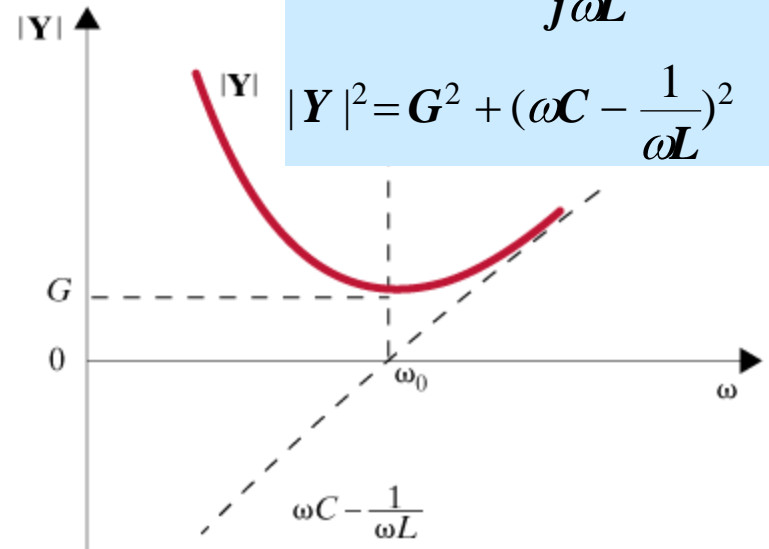
$$Z(j\omega) = R + j\omega L + \frac{1}{j\omega C}$$

$$|Z|^2 = R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2$$



$$Y(j\omega) = G + \frac{1}{j\omega L} + j\omega C$$

$$|Y|^2 = G^2 + \left(\omega C - \frac{1}{\omega L}\right)^2$$



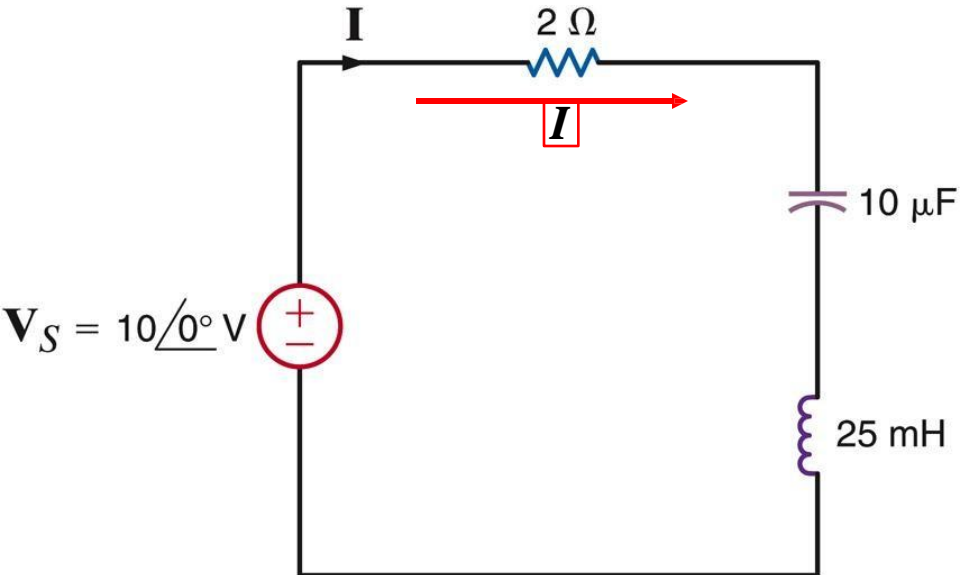
Current through the serial circuit/  
voltage across the parallel circuit can  
become very large

$$\text{Quality Factor: } Q = \frac{\omega_0 L}{R} = \frac{1}{\omega_0 C R}$$

Given the similarities between series and parallel resonant circuits,  
we will focus on serial circuits

## LEARNING EXAMPLE

Determine the resonant frequency, the voltage across each element at resonance and the value of the quality factor



$$\frac{1}{\omega_0 C} = \omega_0 L = 50\ \Omega$$

$$V_C = \frac{1}{j\omega_0 C} I = -j50 \times 5 = 250\angle -90^\circ$$

$$Q = \frac{\omega_0 L}{R} = \frac{50}{2} = 25$$

$$\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{(25 \times 10^{-3} \text{ H})(10 \times 10^{-6} \text{ F})}} = 2000 \text{ rad/sec}$$

At resonance  $Z = 2\ \Omega$

$$I = \frac{V_S}{Z} = \frac{10\angle 0^\circ}{2} = 5 \text{ A}$$

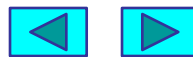
$$\omega_0 L = (2 \times 10^3)(25 \times 10^{-3}) = 50\ \Omega$$

$$V_L = j\omega_0 L I = j50 \times 5 = 250\angle 90^\circ \text{ (V)}$$

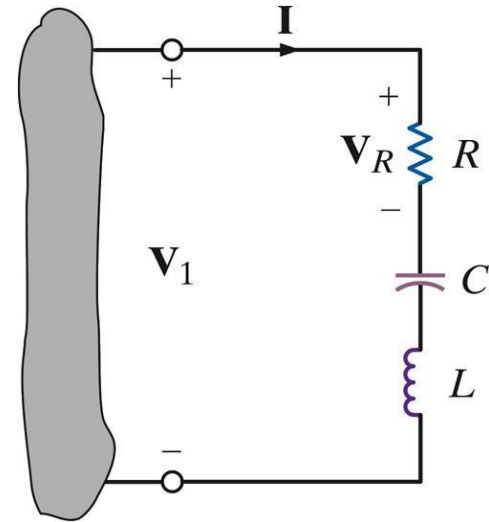
At resonance

$$|V_L| = \omega_0 L \left| \frac{V_S}{R} \right| = Q |V_S|$$

$$|V_C| = Q |V_S|$$



# Resonance for the series circuit



$$Z(j\omega) = R + j\omega L + \frac{1}{j\omega C}$$

$$|Z|^2 = R^2 + (\omega L - \frac{1}{\omega C})^2$$

Claim: The voltage gain

$$G_v = \frac{V_R}{V_1} = \frac{1}{1 + jQ(\frac{\omega}{\omega_0} - \frac{\omega_0}{\omega})}$$

$$G_v = \frac{R}{R + j\omega L + \frac{1}{j\omega C}} = \frac{R}{Z(j\omega)}$$

At resonance:

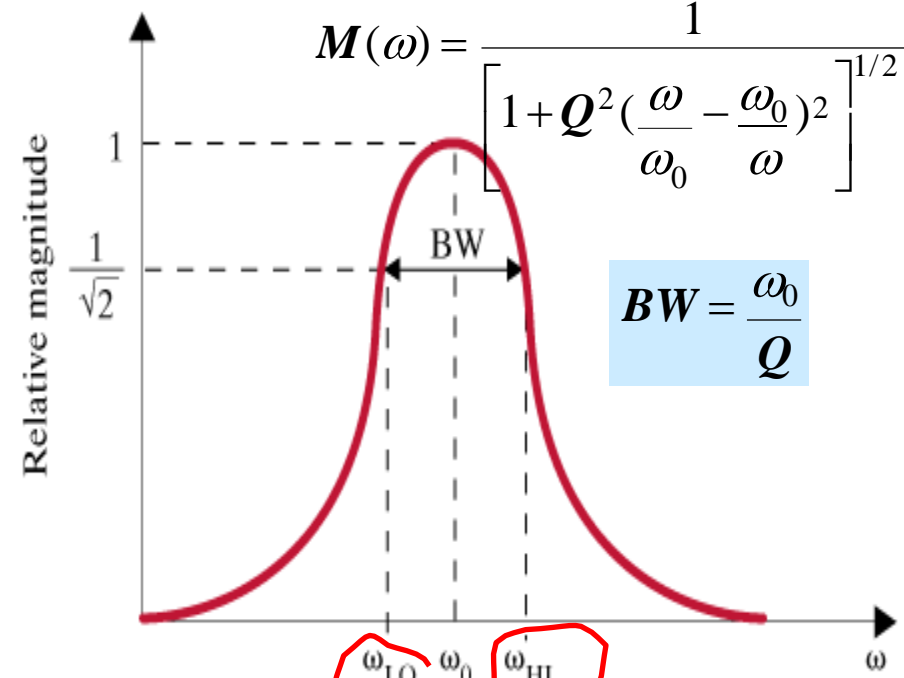
$$\omega_0 L = QR, \quad \omega_0 C = \frac{1}{QR}$$

$$Z(j\omega) = R + j\frac{\omega}{\omega_0}QR - j\frac{\omega_0}{\omega}QR$$

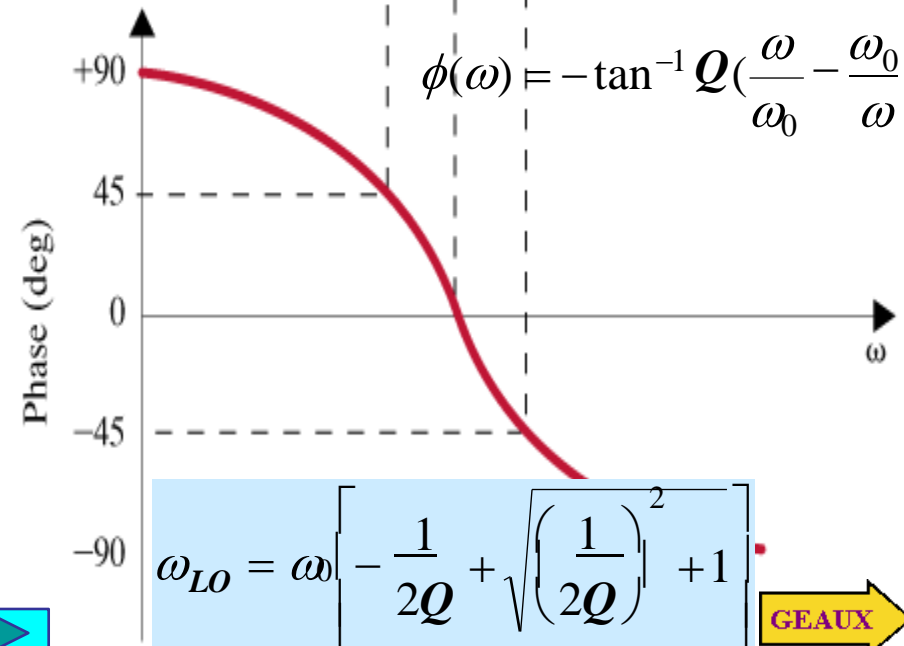
$$= R \left[ 1 + jQ \left( \frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right) \right]$$

$$G_v = \frac{R}{Z}$$

$$M(\omega) = |G_v|, \quad \phi(\omega) = \angle G_v$$



Half power frequencies



## LEARNING EXTENSION

A series RLC circuit as the following properties:

$$R = 4\Omega, \omega_0 = 4000\text{rad/sec}, BW = 100\text{rad/sec}$$

Determine the values of L, C.

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

$$Q = \frac{\omega_0 L}{R} = \frac{1}{\omega_0 CR}$$

$$BW = \frac{\omega_0}{Q}$$

1. Given resonant frequency and bandwidth determine Q.
2. Given R, resonant frequency and Q determine L, C.

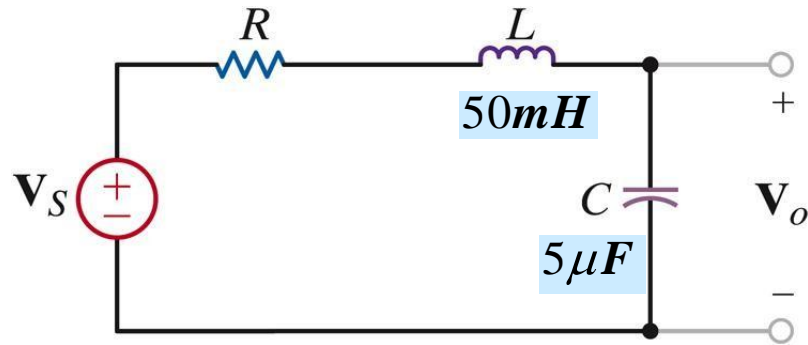
$$Q = \frac{\omega_0}{BW} = \frac{4000}{100} = 40$$

$$L = \frac{QR}{\omega_0} = \frac{40 \times 4}{4000} = 0.040H$$

$$C = \frac{1}{L\omega_0^2} = \frac{1}{\omega_0 R Q} = \frac{1}{4 \times 10^{-2} \times 16 \times 10^6} = 1.56 \times 10^{-6}F$$

# LEARNING EXAMPLE

Determine  $\omega_0$ ,  $\omega_{\max}$  when  $R = 50\Omega$  and  $R = 1\Omega$



$$\omega_0 = \frac{1}{\sqrt{LC}}$$

$$Q = \frac{\omega_0 L}{R} = \frac{1}{\omega_0 CR}$$

$$u_{\max} = \frac{\omega_{\max}}{\omega_0} = \sqrt{1 - \frac{1}{2Q^2}}$$

$$\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{(5 \times 10^{-2})(5 \times 10^{-6})}} = 2000 \text{ rad/s}$$

$$Q = \frac{2000 \times 0.050}{R}$$

$$\omega_{\max} = 2000 \times \sqrt{1 - \frac{1}{2Q^2}}$$

R	Q	Wmax
50	2	1871
1	100	2000

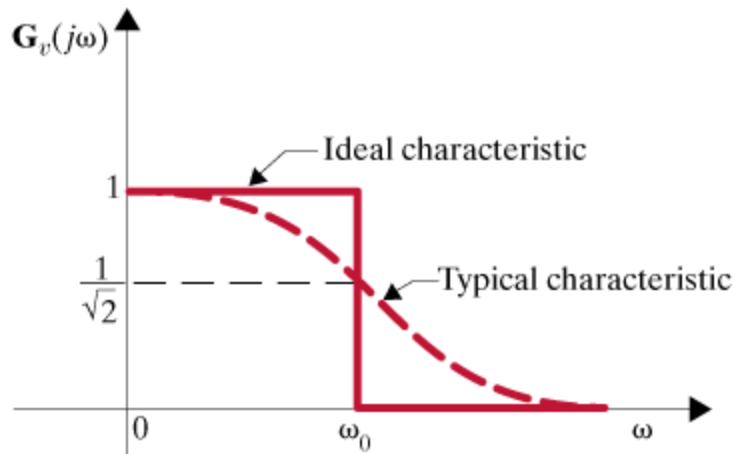
Evaluated with EXCEL and rounded to zero decimals

Using MATLAB one can display the frequency response

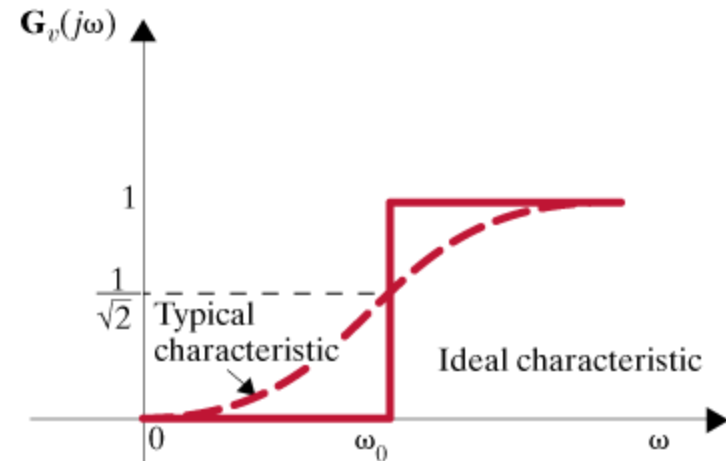
# FILTER NETWORKS

Networks designed to have frequency selective behavior

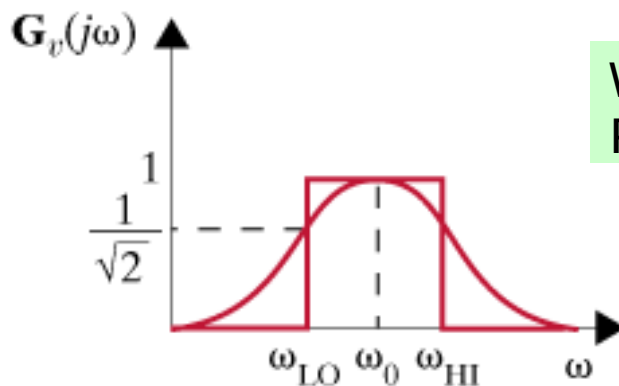
## COMMON FILTERS



Low-pass filter

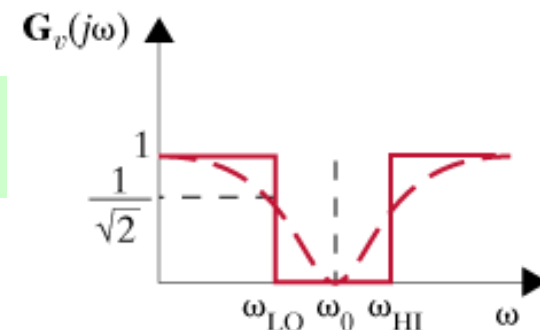


High-pass filter



Band-pass filter

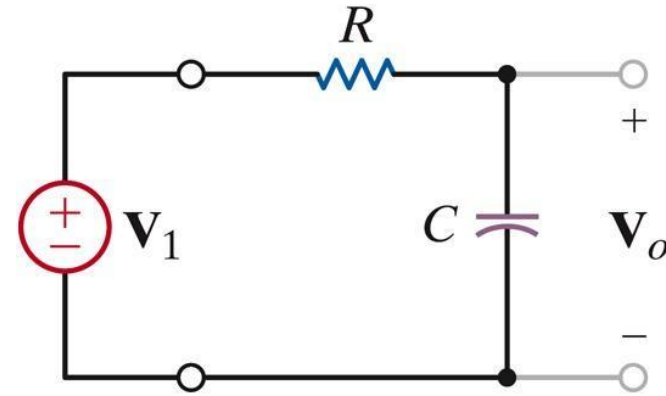
We focus first on  
PASSIVE filters



Band-reject filter



## Simple low-pass filter



$$G_v = \frac{V_o}{V_1} = \frac{1}{R + \frac{1}{j\omega C}} = \frac{1}{1 + j\omega RC}$$

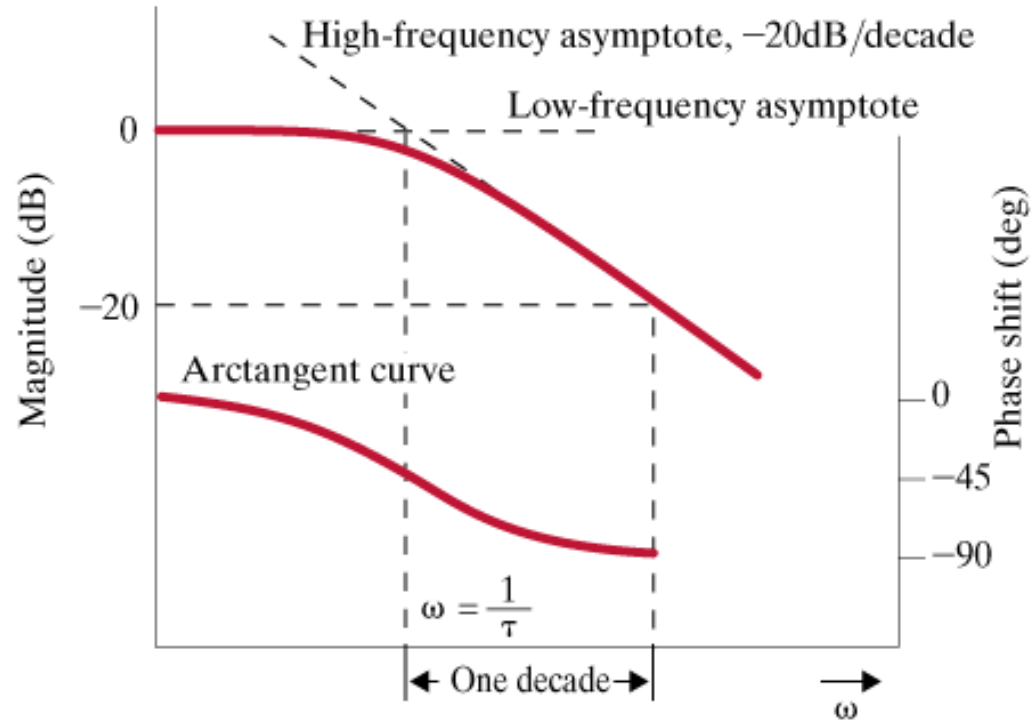
$$G_v = \frac{1}{1 + j\omega\tau}; \quad \tau = RC$$

$$M(\omega) = |G_v| = \frac{1}{\sqrt{1 + (\omega\tau)^2}}$$

$$\angle G_v = \phi(\omega) = -\tan^{-1} \omega\tau$$

$$M_{\max} = 1, \quad M\left(\omega = \frac{1}{\tau}\right) = \frac{1}{\sqrt{2}}$$

$$\omega = \frac{1}{\tau} = \text{half power frequency}$$



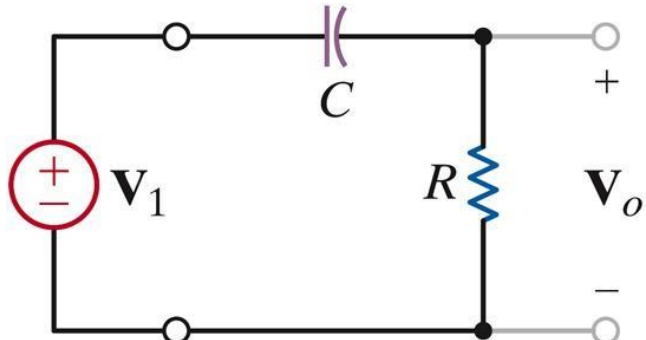
(c)

$$BW = \frac{1}{\tau}$$





## Simple high-pass filter



$$G_v = \frac{V_o}{V_1} = \frac{R}{R + \frac{1}{j\omega C}} = \frac{j\omega CR}{1 + j\omega CR}$$

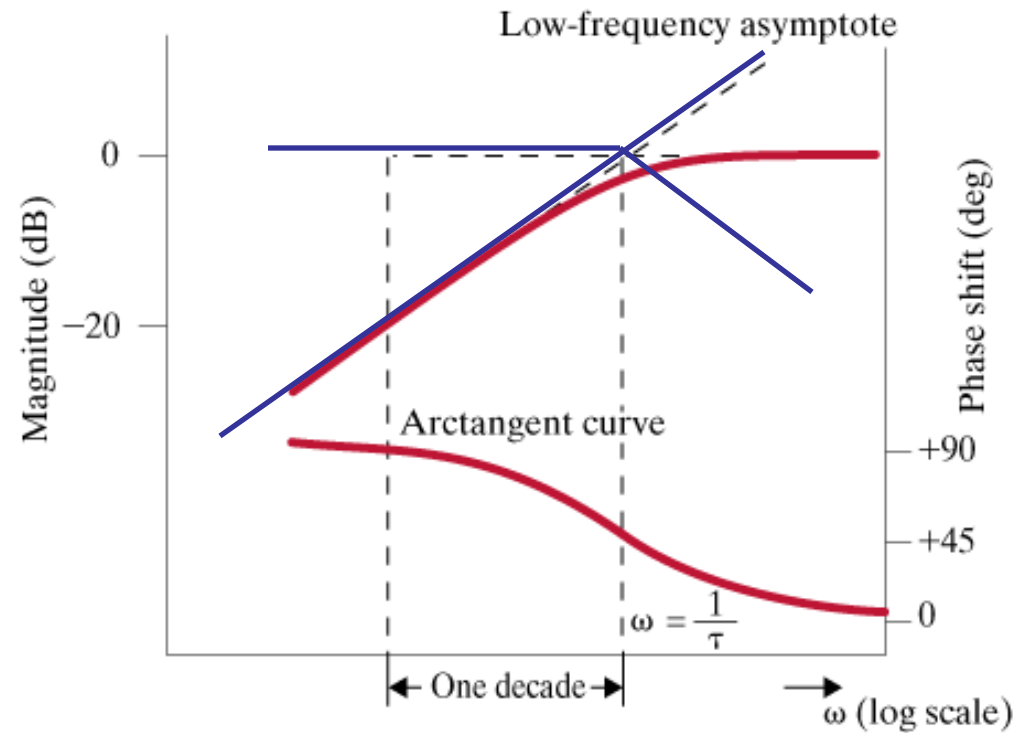
$$G_v = \frac{j\omega\tau}{1 + j\omega\tau}; \tau = RC$$

$$M(\omega) = |G_v| = \frac{\omega\tau}{\sqrt{1 + (\omega\tau)^2}}$$

$$\angle G_v = \phi(\omega) = \frac{\pi}{2} - \tan^{-1} \omega\tau$$

$$M_{\max} = 1, M\left(\omega = \frac{1}{\tau}\right) = \frac{1}{\sqrt{2}}$$

$$\omega = \frac{1}{\tau} = \text{half power frequency}$$

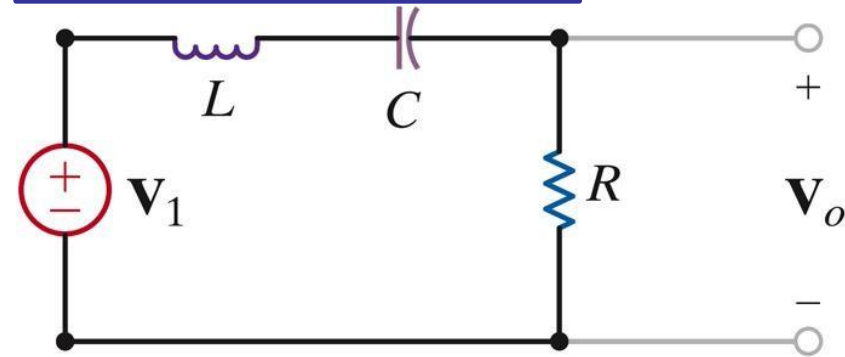


(c)

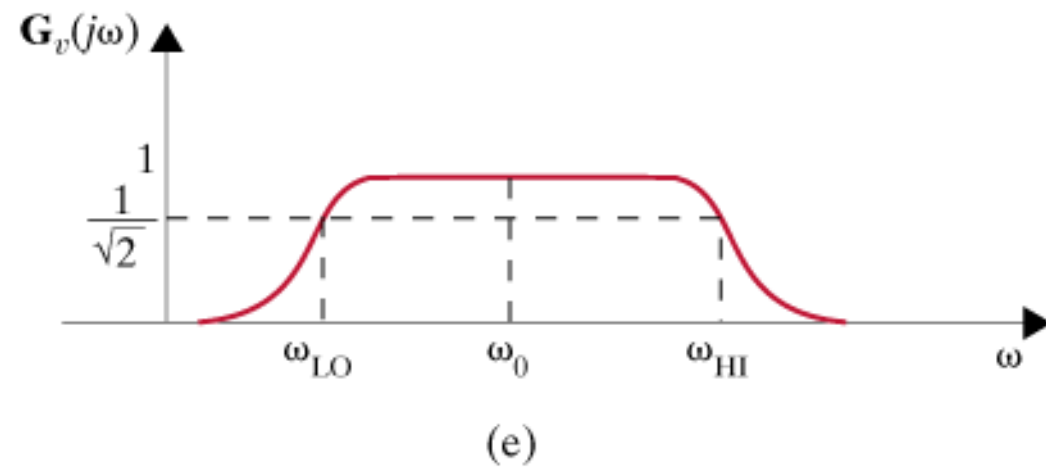
$$\omega_{LO} = \frac{1}{\tau}$$



# Simple band-pass filter



Band-pass



$$G_v = \frac{V_o}{V_1} = \frac{R}{R + j\left(\omega L - \frac{1}{\omega C}\right)}$$

$$M(\omega) = \frac{\omega RC}{\sqrt{(\omega RC)^2 + (\omega^2 LC - 1)^2}}$$

$$M\left(\omega = \frac{1}{\sqrt{LC}}\right) = 1 \quad M(\omega = 0) = M(\omega = \infty) = 0$$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

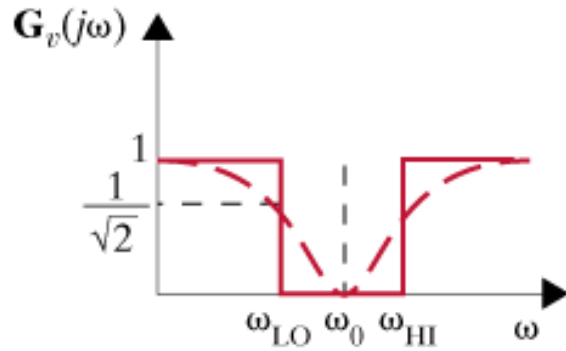
$$M(\omega_{LO}) = \frac{1}{\sqrt{2}} = M(\omega_{HI})$$

$$\omega_{LO} = \frac{-(R/L) + \sqrt{(R/L)^2 + 4\omega_0^2}}{2}$$

$$\omega_{HI} = \frac{(R/L) + \sqrt{(R/L)^2 + 4\omega_0^2}}{2}$$

$$BW = \omega_{HI} - \omega_{LO} = \frac{R}{L}$$

## Simple band-reject filter



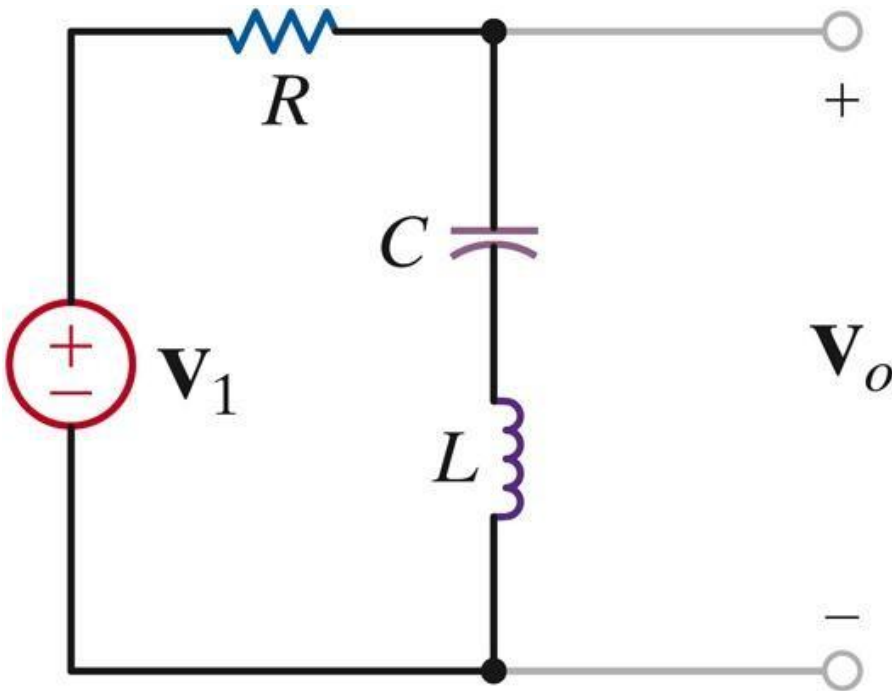
(b)

$$\omega_0 = \frac{1}{\sqrt{LC}} \Rightarrow j \left( \omega_0 L - \frac{1}{\omega_0 C} \right) = 0$$

at  $\omega = 0$  the capacitor acts as open circuit  $\Rightarrow V_0 = V_1$

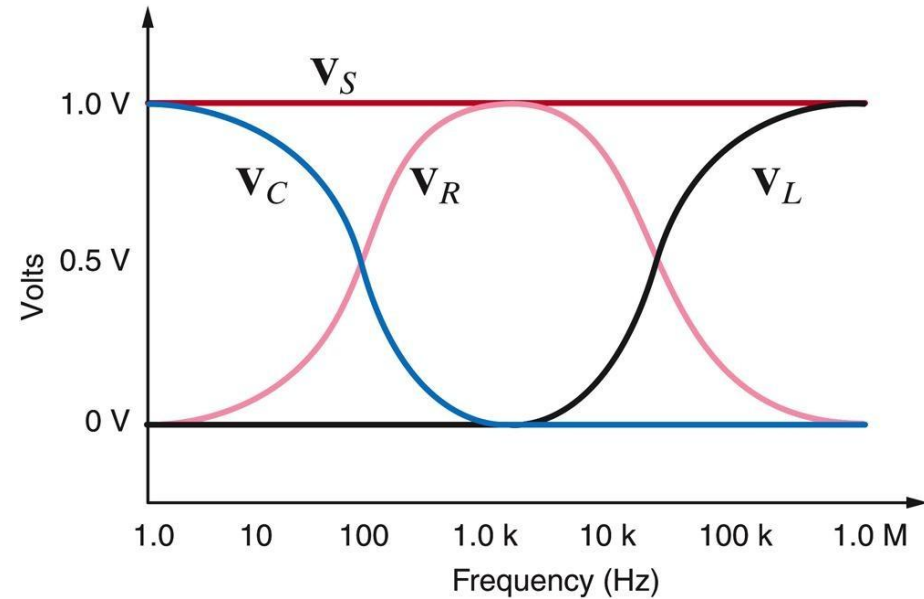
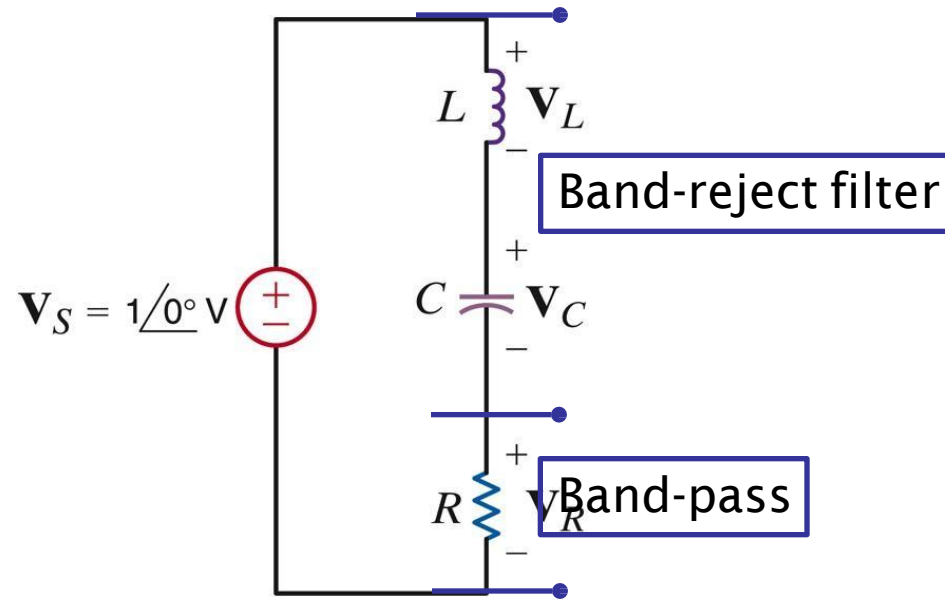
at  $\omega = \infty$  the inductor acts as open circuit  $\Rightarrow V_0 = V_1$

$\omega_{LO}$ ,  $\omega_{HI}$  are determined as in the band-pass filter



## LEARNING EXAMPLE

Depending on where the output is taken, this circuit can produce low-pass, high-pass or band-pass or band-reject filters



Bode plot for  $R = 10\Omega$ ,  $L = 159\mu\text{H}$ ,  $C = 159\mu\text{F}$

$$\frac{V_L}{V_S} = \frac{j\omega L}{R + j\left(\omega L - \frac{1}{\omega C}\right)}$$

$$\frac{V_L}{V_S}(\omega = 0) = 0, \quad \frac{V_L}{V_S}(\omega = \infty) = 1$$

High-pass

$$\frac{V_C}{V_S} = \frac{1}{R + j\left(\omega L - \frac{1}{\omega C}\right)}$$

$$\frac{V_C}{V_S}(\omega = 0) = 1, \quad \frac{V_C}{V_S}(\omega = \infty) = 0$$

Low-pass



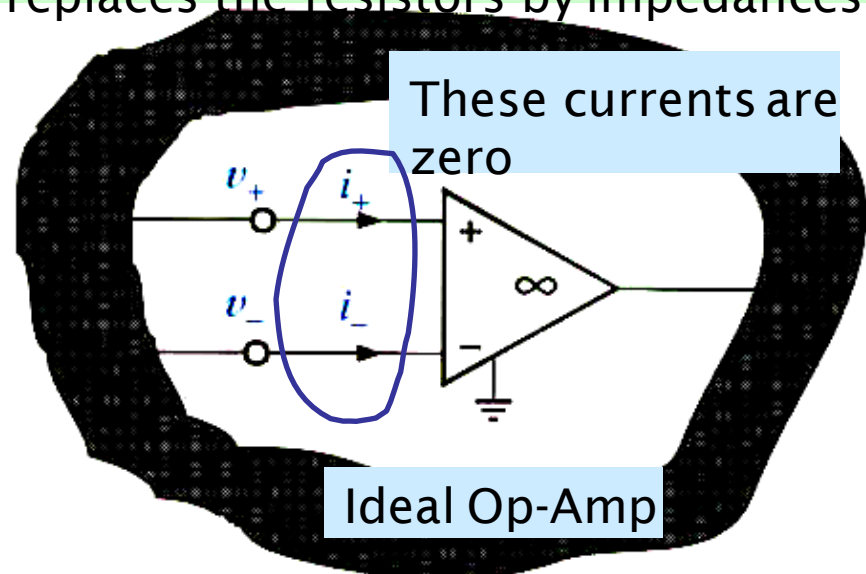
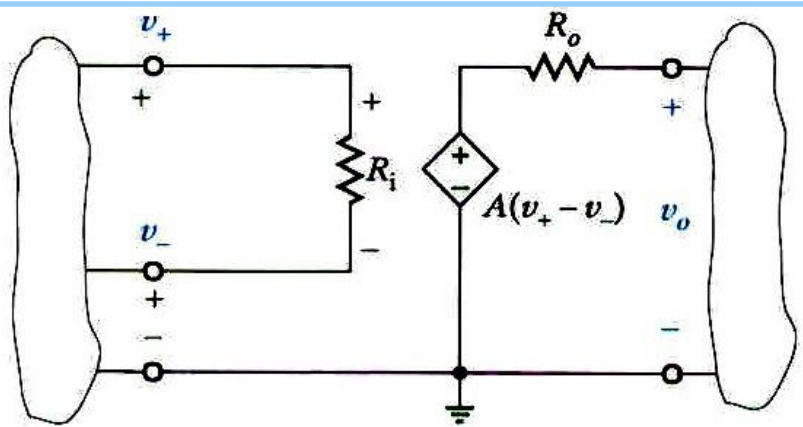
# ACTIVE FILTERS

Passive filters have several limitations

1. Cannot generate gains greater than one
2. Loading effect makes them difficult to interconnect
3. Use of inductance makes them difficult to handle

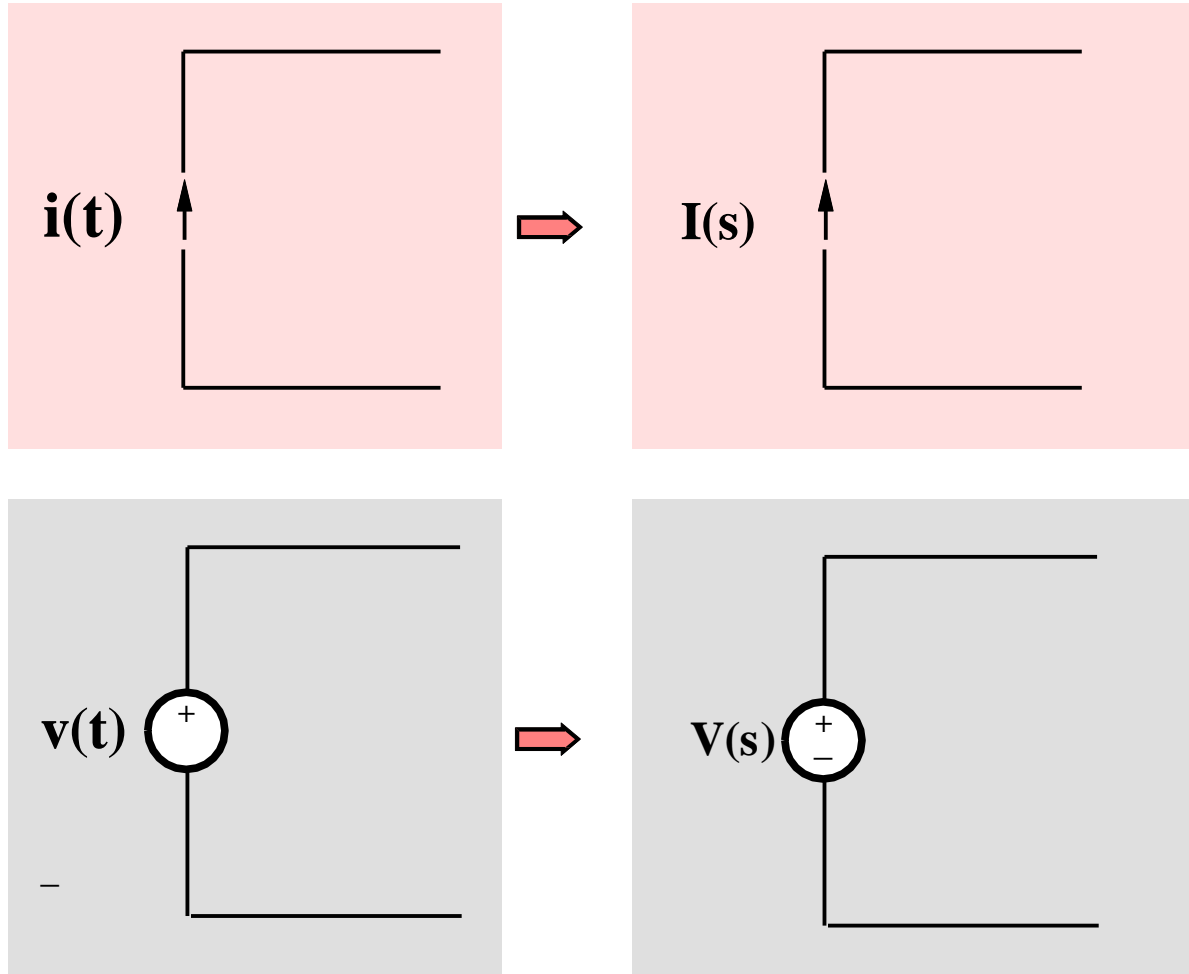
Using operational amplifiers one can design all basic filters, and more, with only resistors and capacitors

The linear models developed for operational amplifiers circuits are valid, in a more general framework, if one replaces the resistors by impedances



# Laplace Circuit Analysis

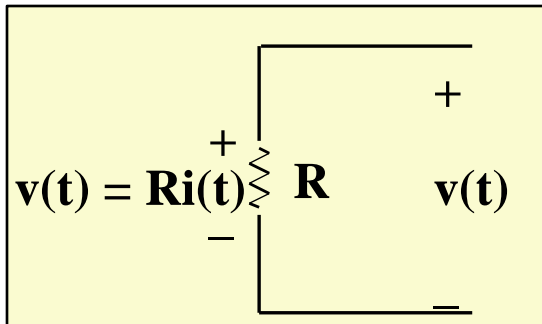
## Circuit Element Modeling



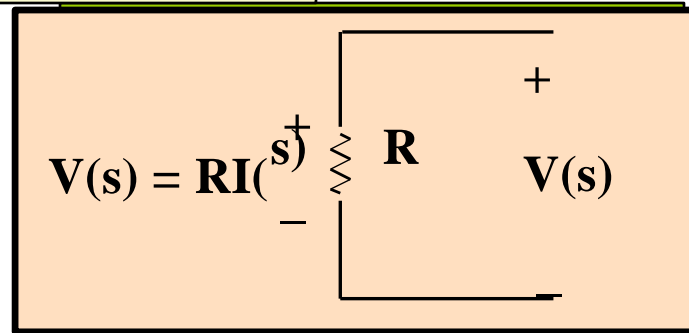
# Laplace Circuit Analysis

## Circuit Element Modeling

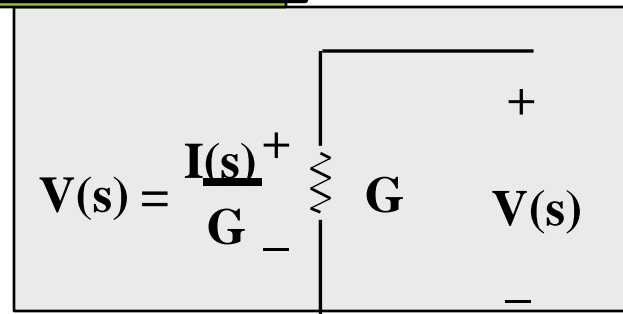
### Resistance



Time Domain



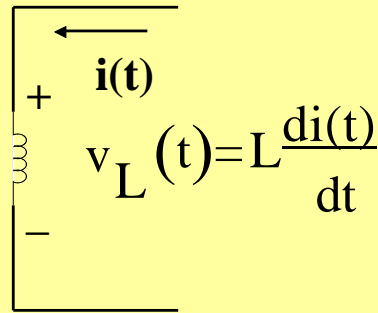
Complex Frequency Domain



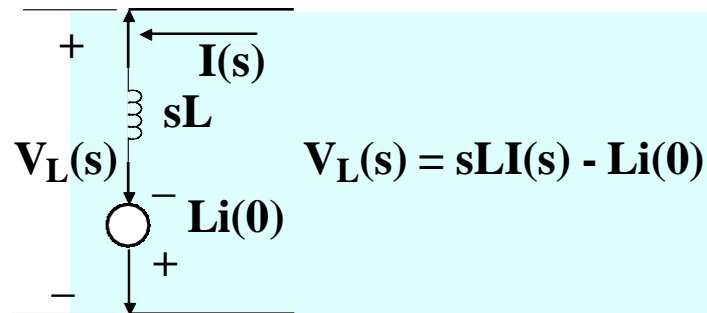
# Laplace Circuit Analysis

## Circuit Element Modeling

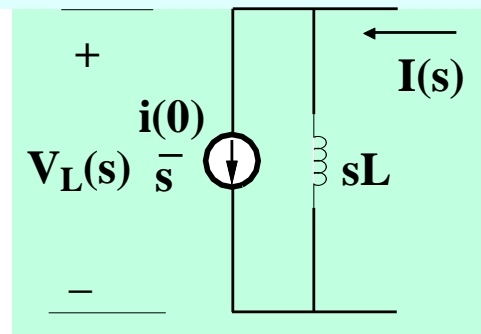
### Inductor



**Best for mesh**



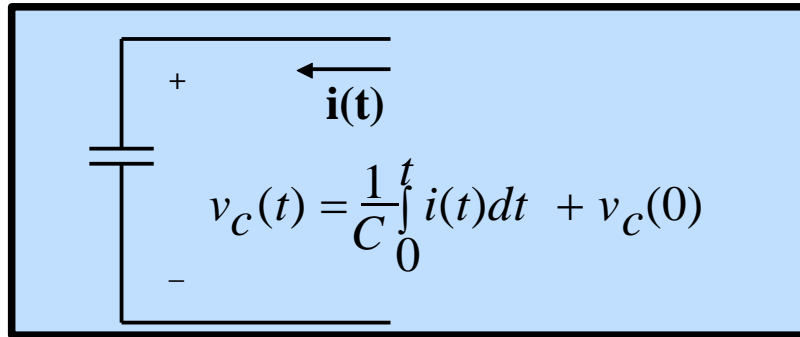
**Best for nodal**



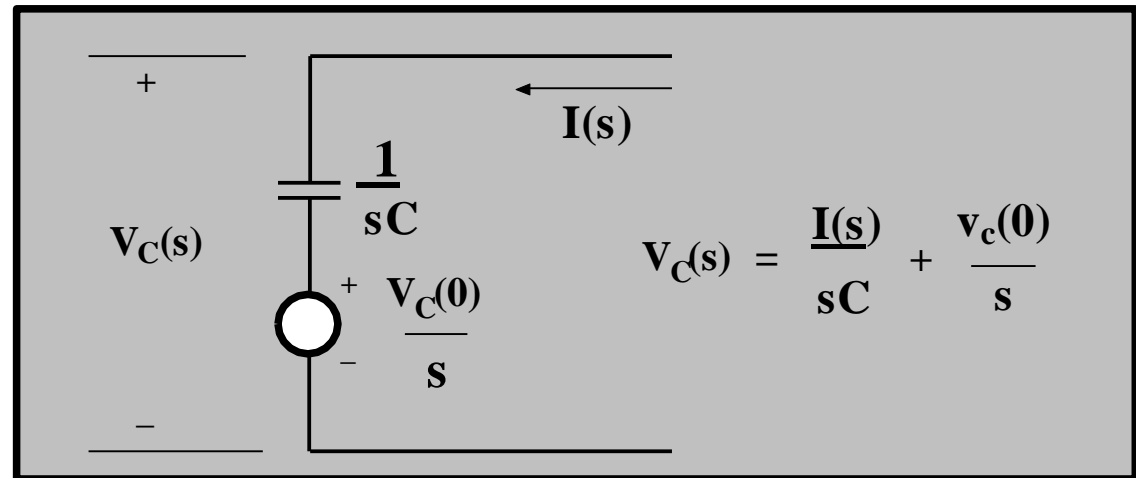


# Laplace Circuit Analysis

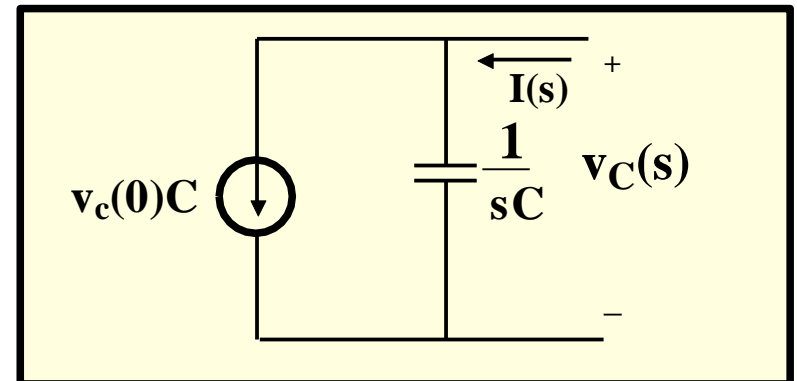
## Capacitor



## Mesh

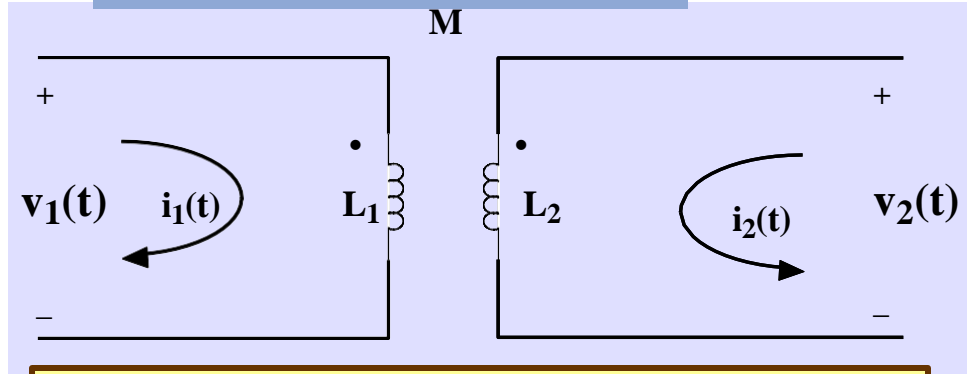


## Nodal



# Laplace Circuit Analysis

## Linear Transformer

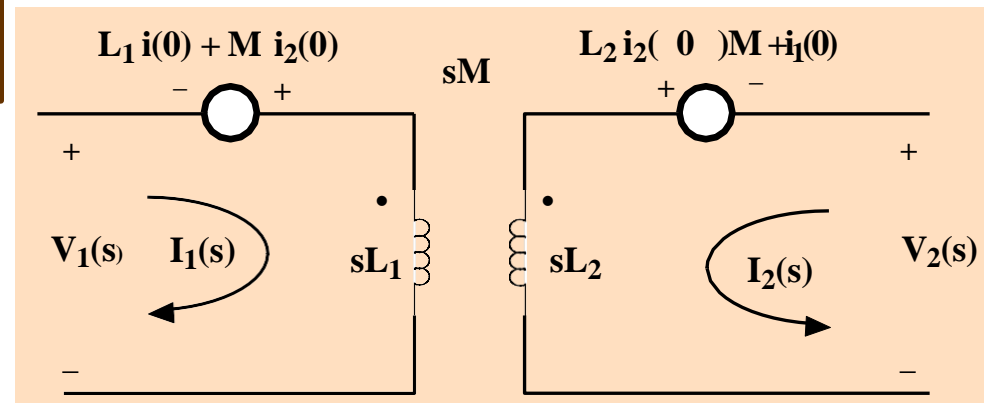


$$v_1(t) = L_1 \frac{di_1(t)}{dt} + M \frac{di_2(t)}{dt}$$

$$V_1(s) = sL_1 I_1(s) - L_1 i_1(0) + sM I_2(s) - M i_2(0)$$

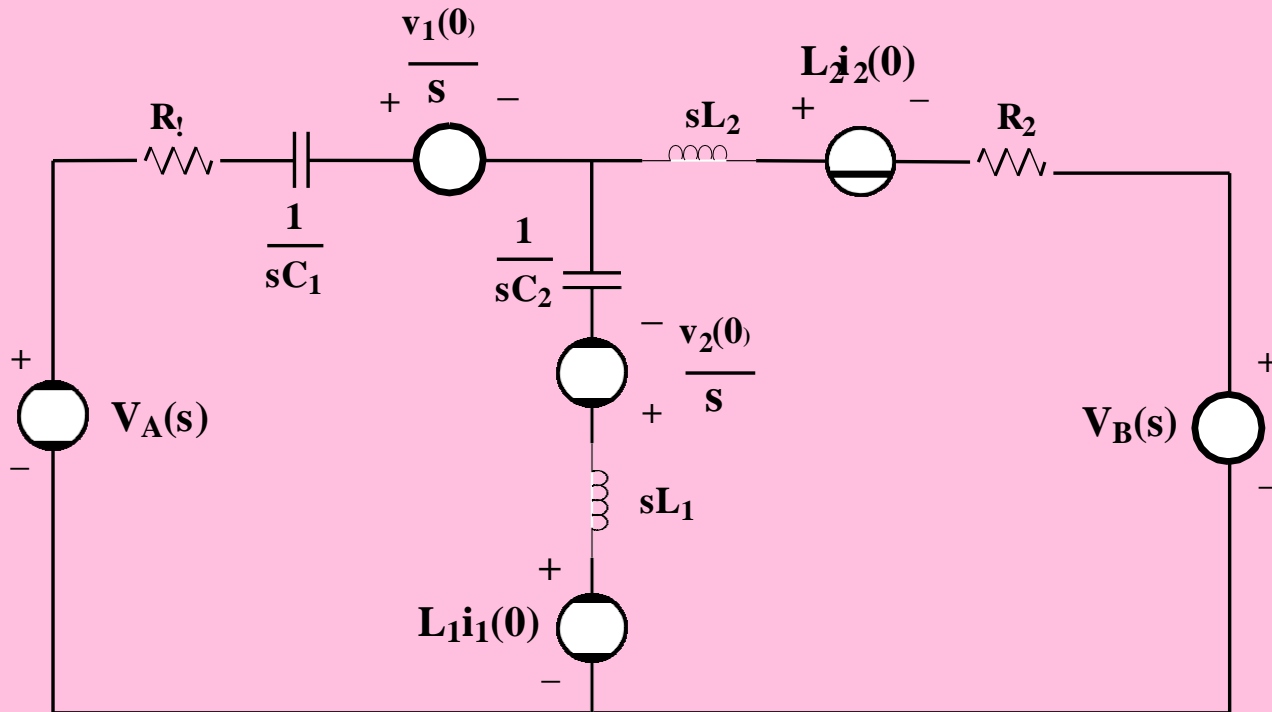
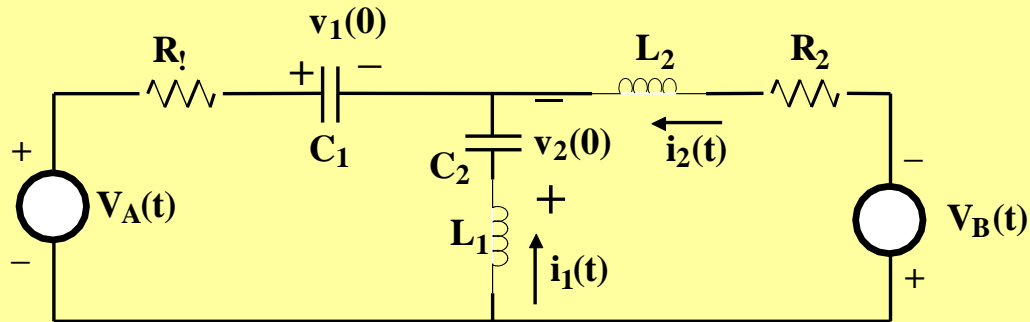
$$v_2(t) = L_2 \frac{di_2(t)}{dt} + M \frac{di_1(t)}{dt}$$

$$V_2(s) = sL_2 I_2(s) - L_2 i_2(0) + sM I_1(s) - M i_1(0)$$



# Laplace Circuit Analysis

Time domain to complex frequency domain

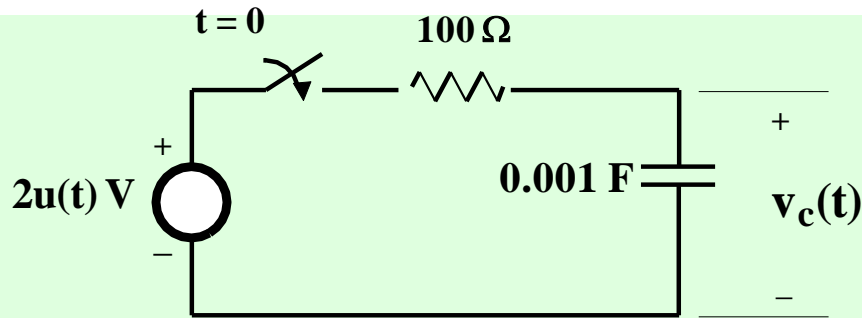


# Laplace Circuit Analysis

## Circuit Application:

Given the circuit below. Assume zero IC's. Use Laplace to find  $v_c(t)$ .

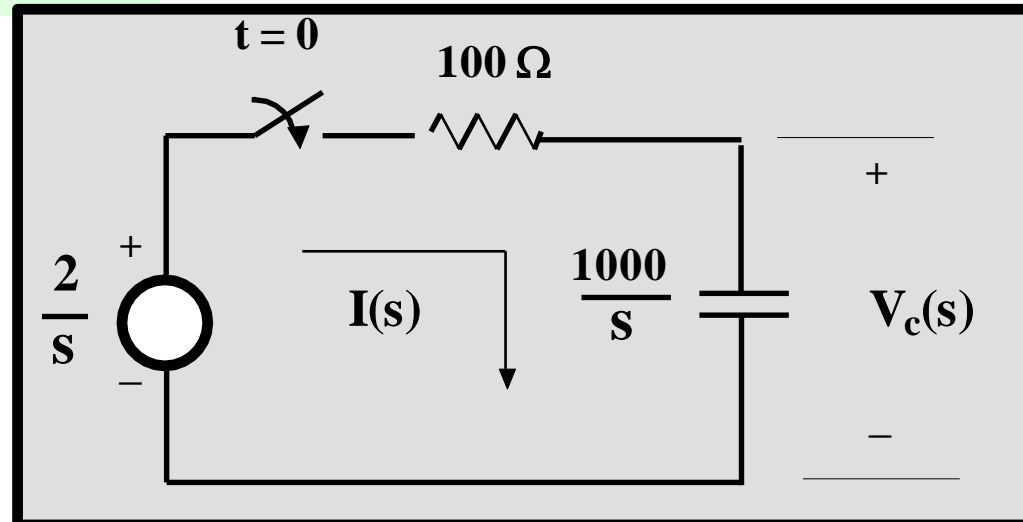
The time domain circuit:



Laplace circuit

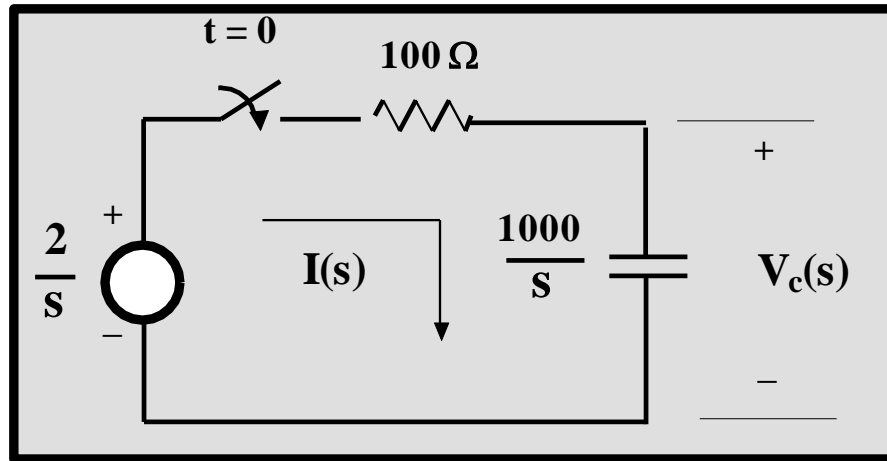
$$V_c(s) = \frac{\left(\frac{2}{s}\right)\left(\frac{1000}{s}\right)}{100 + \frac{1000}{s}}$$

$$V_c(s) = \frac{20}{s(s+10)}$$



# Laplace Circuit Analysis

## Circuit Application:



$$V_c(s) = \frac{20}{s(s+10)} = \frac{2}{s} - \frac{2}{s+10}$$

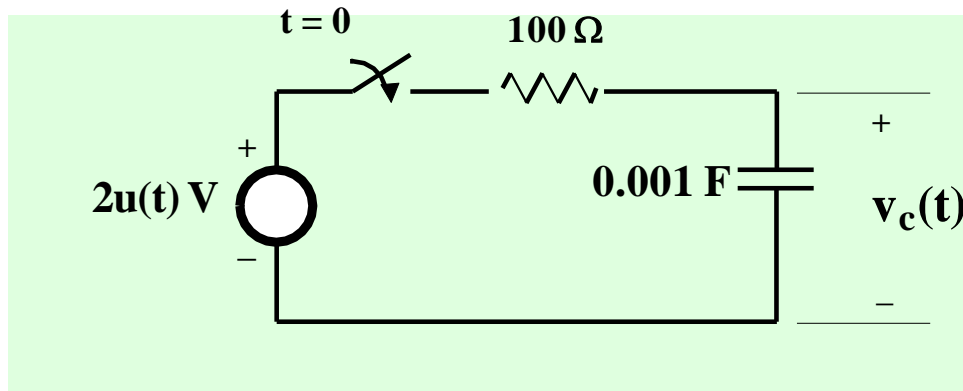
$$v_c(t) = \left[ 2 - 2e^{-10t} \right] u(t)$$

# Laplace Circuit Analysis

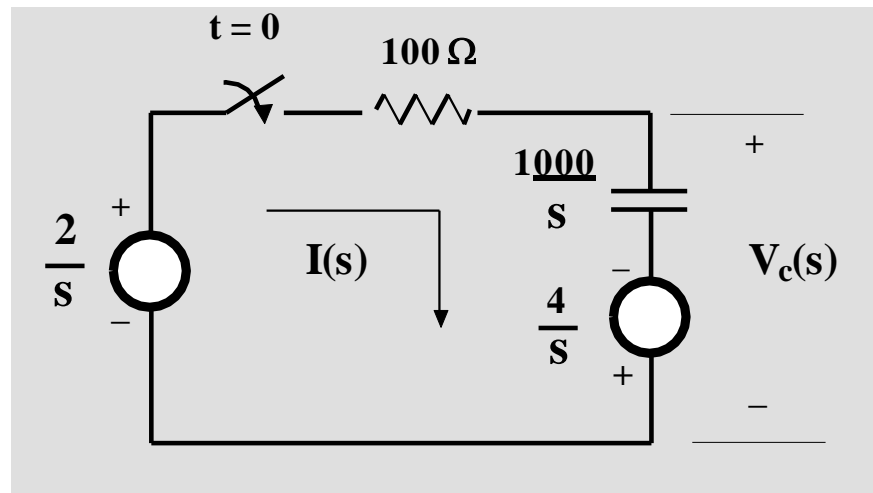
## Circuit Application:

Given the circuit below. Assume  $v_c(0) = -4$  V. Use Laplace to find  $v_c(t)$ .

The time domain circuit:



Laplace circuit:

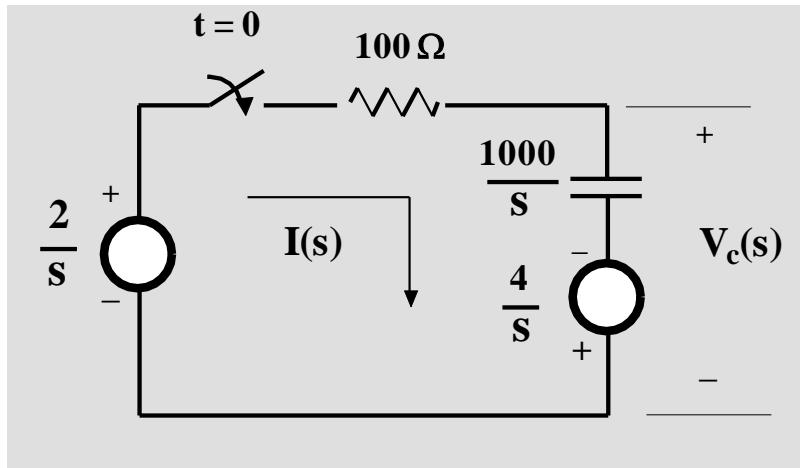


$$\frac{2}{s} + \frac{4}{s} = I(s) \left[ 100 + \frac{1000}{s} \right]$$

$$100I(s) = \frac{6}{s + 10}$$

# Laplace Circuit Analysis

## Circuit Application:



①

$$\frac{2}{s} - 100I(s) - V_c(s) = 0$$

$$\frac{2}{s} - \frac{6}{s+10} = V_c(s)$$

②

$$V_c(s) = \frac{-4s + 20}{s(s+10)} = \frac{A}{s} + \frac{B}{s+10}$$

$$V_c(s) = \frac{2}{s} - \frac{6}{s+10}$$

$$v(t) = [2 - 6e^{-10t}]u(t)$$

Check the boundary conditions

③

$$v_c(0) = -4\text{ V}$$

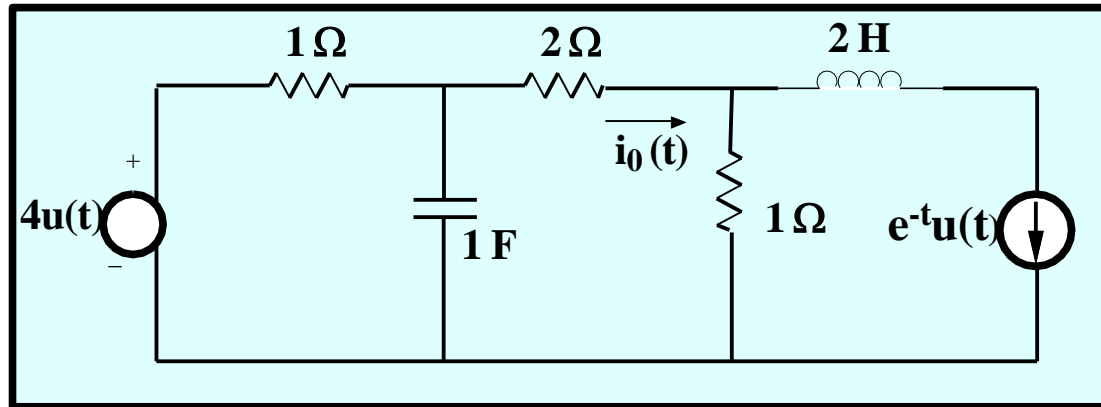
$$v_c(\infty) = 2\text{ V}$$

# Laplace Circuit Analysis

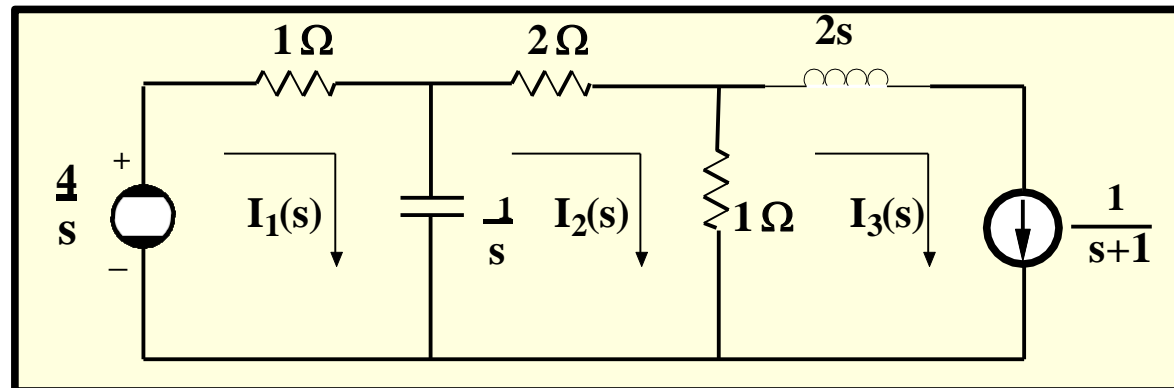
**Circuit Application:**

Find  $i_0(t)$  using Laplace

Time Domain



Laplace

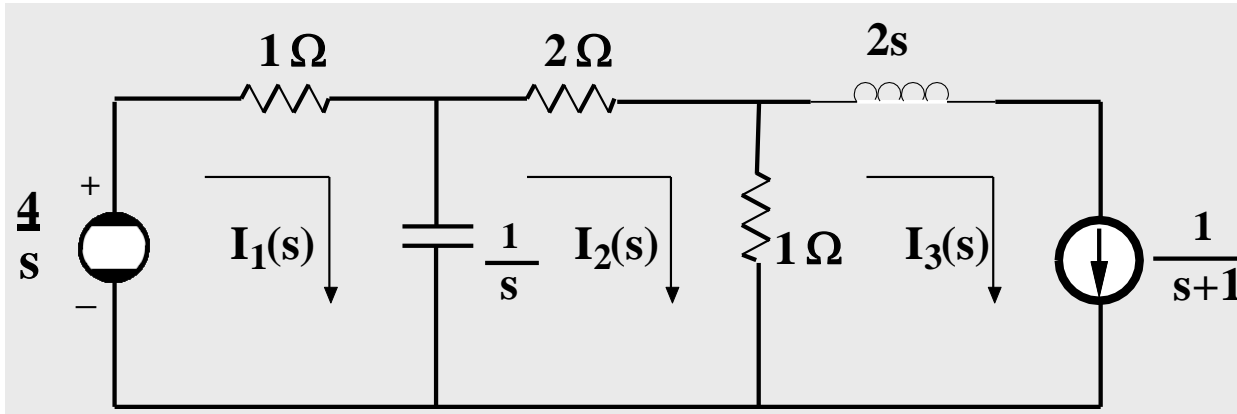




# Laplace Circuit Analysis

**Circuit Application:**

Find  $i_0(t)$  using Laplace



Mesh 1

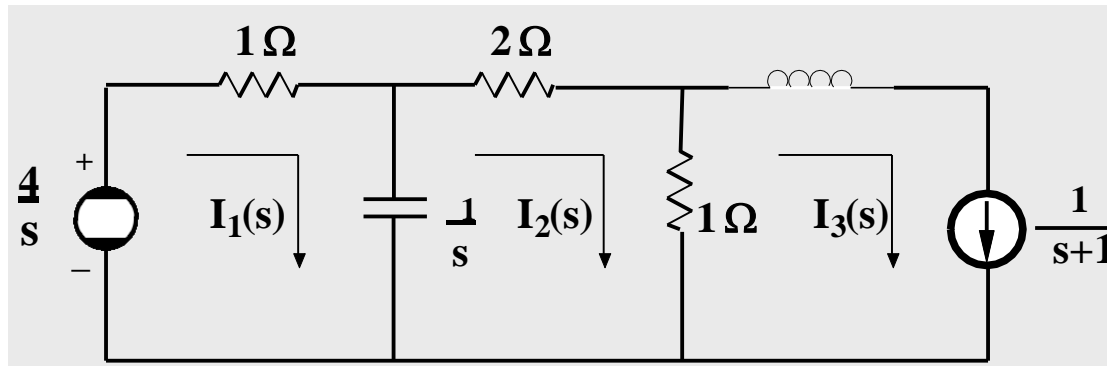
$$\frac{(s+1)}{s} I_1(s) - \frac{I_2(s)}{s} = \frac{4}{s}$$

$$(s+1)I_1(s) - I_2(s) = 4$$

# Laplace Circuit Analysis

**Circuit Application:**

Find  $i_0(t)$  using Laplace



**Mesh 2**

$$-\frac{1}{s} I_1(s) + \frac{3s+1}{s} I_2(s) - I_3(s) = 0$$

$$-\frac{1}{s} I_1(s) + \frac{3s+1}{s} I_2(s) - \frac{1}{s+1} = 0$$

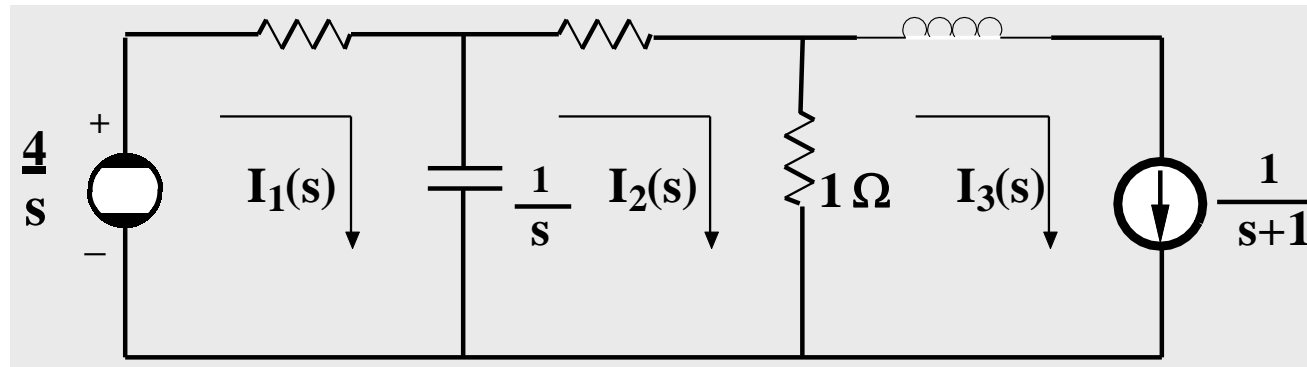
$$-I_1(s) + (3s+1) I_2(s) = \frac{s}{s+1}$$

$$-(s+1) I_1(s) + (s+1)(3s+1) I_2(s) = s$$

# Laplace Circuit Analysis

**Circuit Application:**

Find  $i_0(t)$  using Laplace



$$(s+1)I_1(s) - I_2(s) = 4$$

$$-(s+1)I_1(s) + (s+1)(3s+1)I_2(s) = s$$

**Add these 2  
equations**

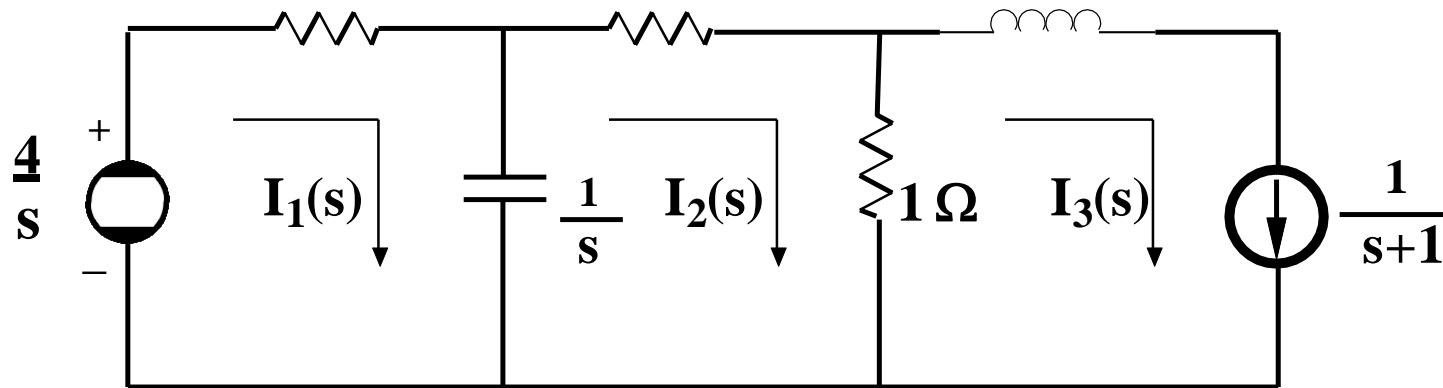
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$$s(3s+4)I_2(s) = s+4$$

# Laplace Circuit Analysis

**Circuit Application:**

Find  $i_0(t)$  using Laplace



$$s(3s + 4)I_2(s) = s + 4$$

$$I_2(s) = \frac{(s+4)}{s(s + 4/3)} = \frac{1}{s} - \frac{2/3}{s + 4/3}$$

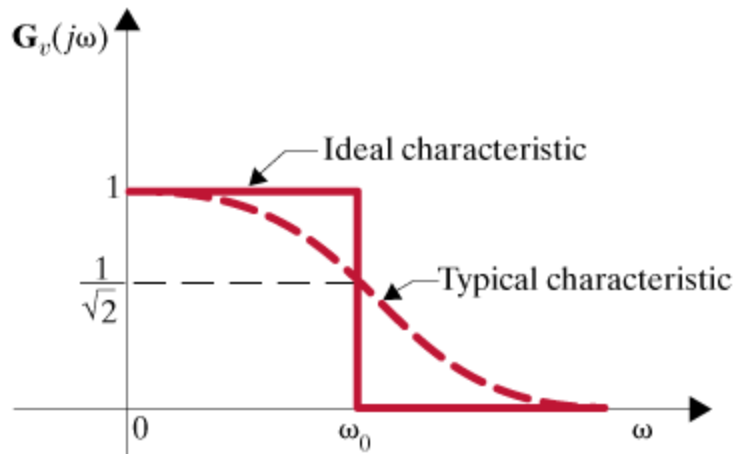
Is final value of  $i_2(t)$  reasonable?

$$i_2(t) = [1 - \frac{2}{3}e^{-4/3t}]u(t)$$

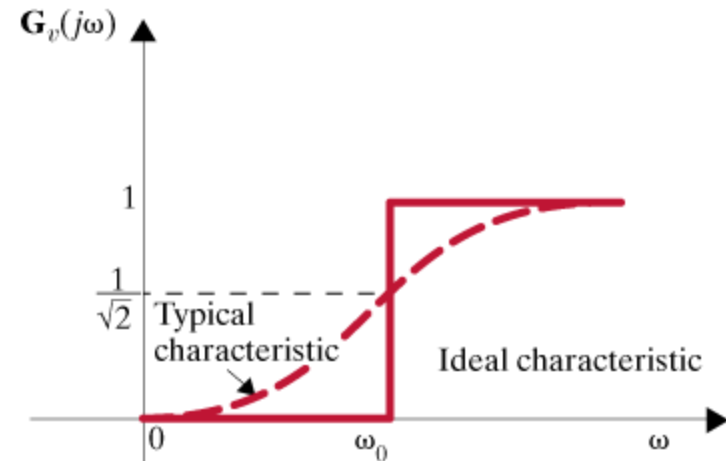
# FILTER NETWORKS

Networks designed to have frequency selective behavior

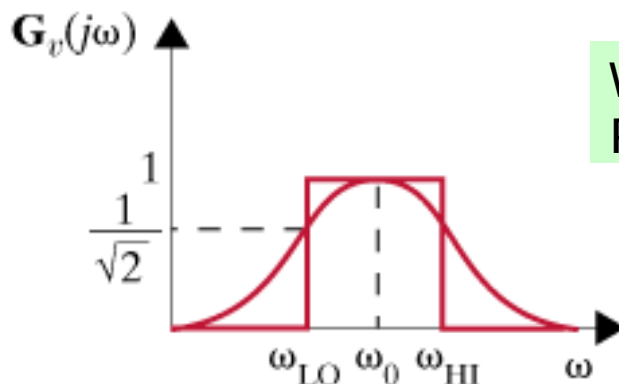
## COMMON FILTERS



Low-pass filter

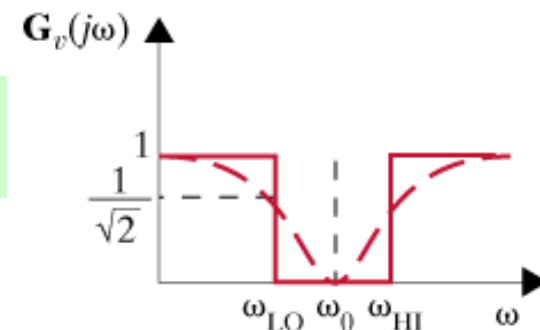


High-pass filter



Band-pass filter

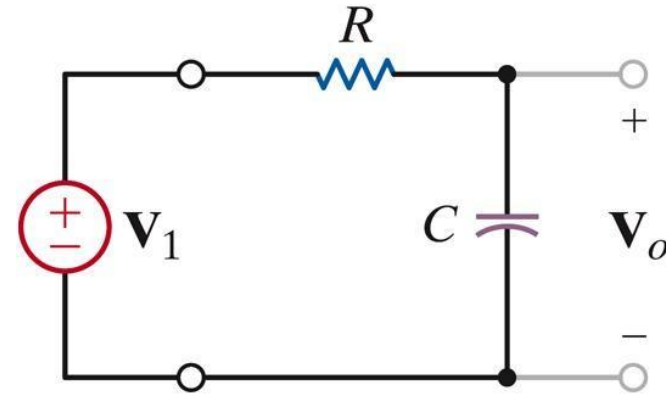
We focus first on  
PASSIVE filters



Band-reject filter



## Simple low-pass filter



$$G_v = \frac{V_o}{V_1} = \frac{1}{R + \frac{1}{j\omega C}} = \frac{1}{1 + j\omega RC}$$

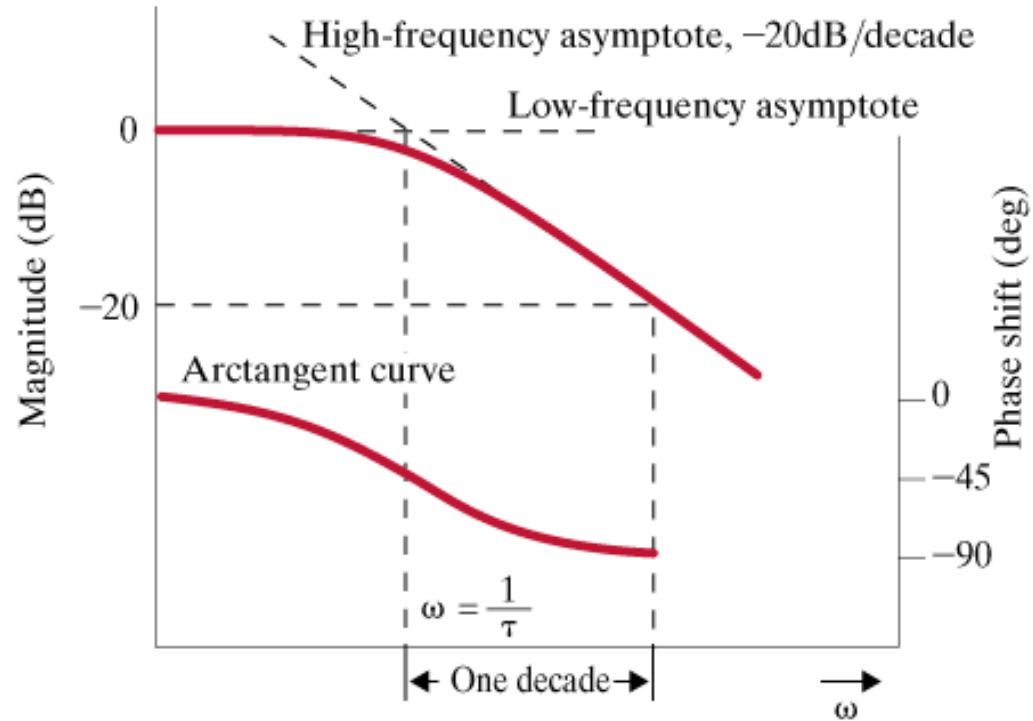
$$G_v = \frac{1}{1 + j\omega\tau}; \quad \tau = RC$$

$$M(\omega) = |G_v| = \frac{1}{\sqrt{1 + (\omega\tau)^2}}$$

$$\angle G_v = \phi(\omega) = -\tan^{-1} \omega\tau$$

$$M_{\max} = 1, \quad M\left(\omega = \frac{1}{\tau}\right) = \frac{1}{\sqrt{2}}$$

$$\omega = \frac{1}{\tau} = \text{half power frequency}$$

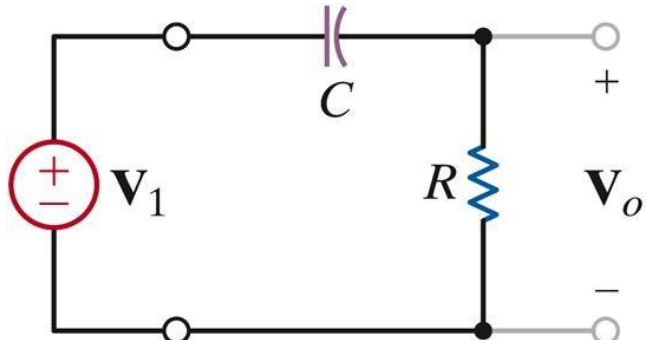


(c)

$$BW = \frac{1}{\tau}$$



## Simple high-pass filter



$$G_v = \frac{V_o}{V_1} = \frac{R}{R + \frac{1}{j\omega C}} = \frac{j\omega CR}{1 + j\omega CR}$$

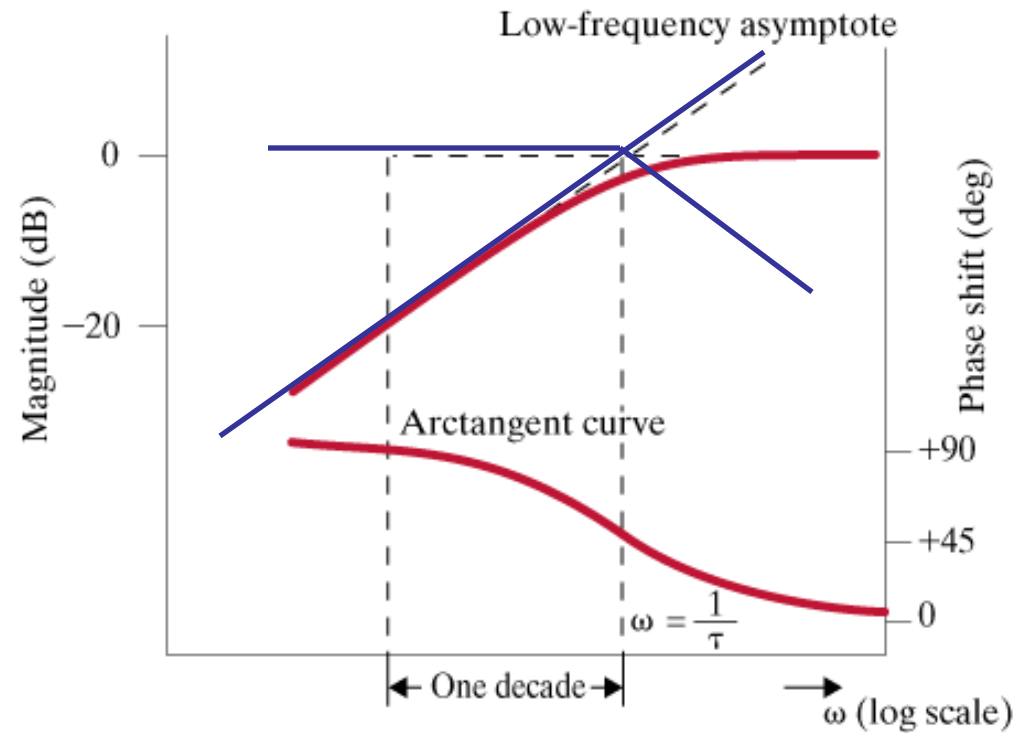
$$G_v = \frac{j\omega\tau}{1 + j\omega\tau}; \tau = RC$$

$$M(\omega) = |G_v| = \frac{\omega\tau}{\sqrt{1 + (\omega\tau)^2}}$$

$$\angle G_v = \phi(\omega) = \frac{\pi}{2} - \tan^{-1} \omega\tau$$

$$M_{\max} = 1, M\left(\omega = \frac{1}{\tau}\right) = \frac{1}{\sqrt{2}}$$

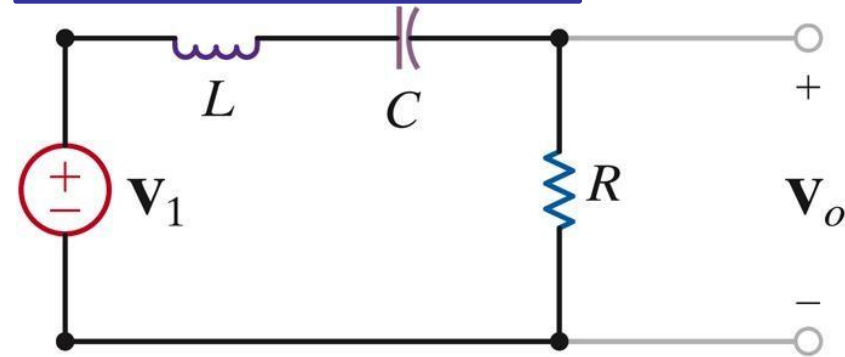
$$\omega = \frac{1}{\tau} = \text{half power frequency}$$



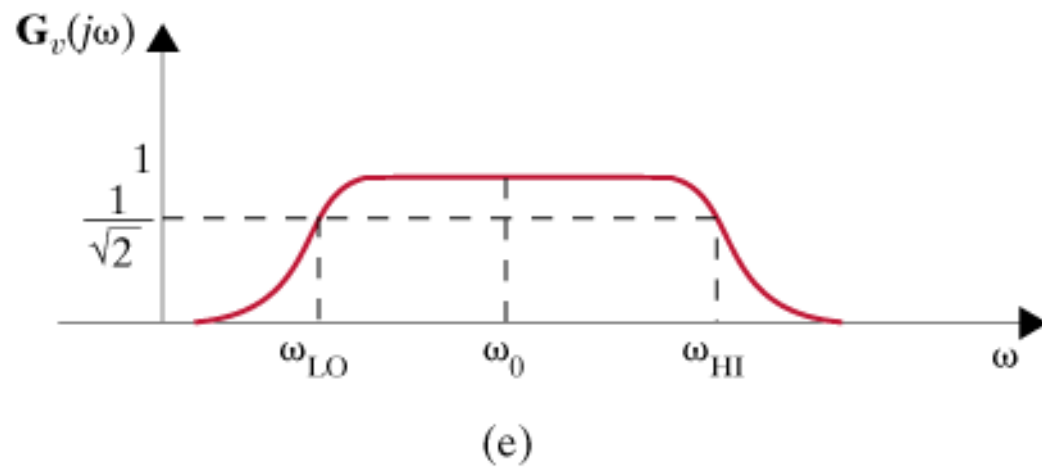
(c)

$$\omega_{LO} = \frac{1}{\tau}$$

# Simple band-pass filter



Band-pass



$$G_v = \frac{V_o}{V_1} = \frac{R}{R + j\left(\omega L - \frac{1}{\omega C}\right)}$$

$$M(\omega) = \frac{\omega RC}{\sqrt{(\omega RC)^2 + (\omega^2 LC - 1)^2}}$$

$$M\left(\omega = \frac{1}{\sqrt{LC}}\right) = 1 \quad M(\omega = 0) = M(\omega = \infty) = 0$$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

$$M(\omega_{LO}) = \frac{1}{\sqrt{2}} = M(\omega_{HI})$$

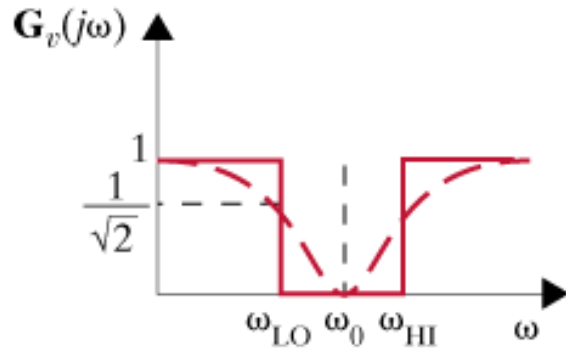
$$\omega_{LO} = \frac{-(R/L) + \sqrt{(R/L)^2 + 4\omega_0^2}}{2}$$

$$\omega_{HI} = \frac{(R/L) + \sqrt{(R/L)^2 + 4\omega_0^2}}{2}$$

$$BW = \omega_{HI} - \omega_{LO} = \frac{R}{L}$$



## Simple band-reject filter



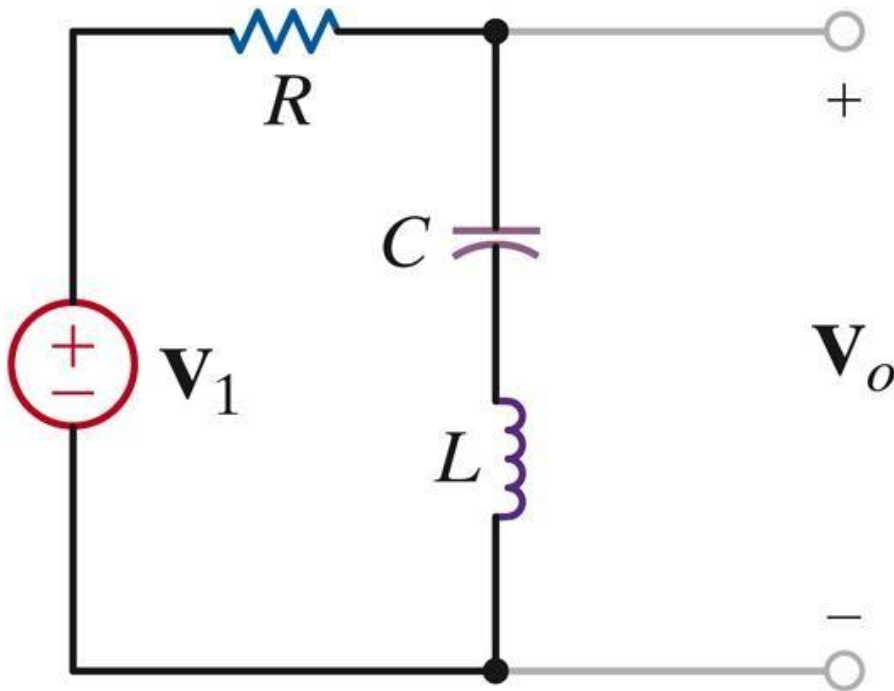
(b)

$$\omega_0 = \frac{1}{\sqrt{LC}} \Rightarrow j \left( \omega_0 L - \frac{1}{\omega_0 C} \right) = 0$$

at  $\omega = 0$  the capacitor acts as open circuit  $\Rightarrow V_0 = V_1$

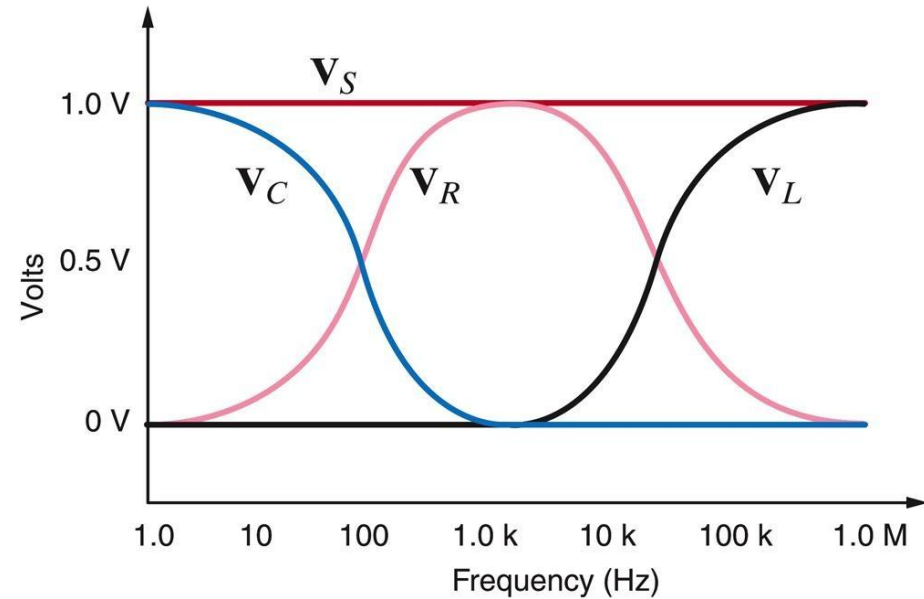
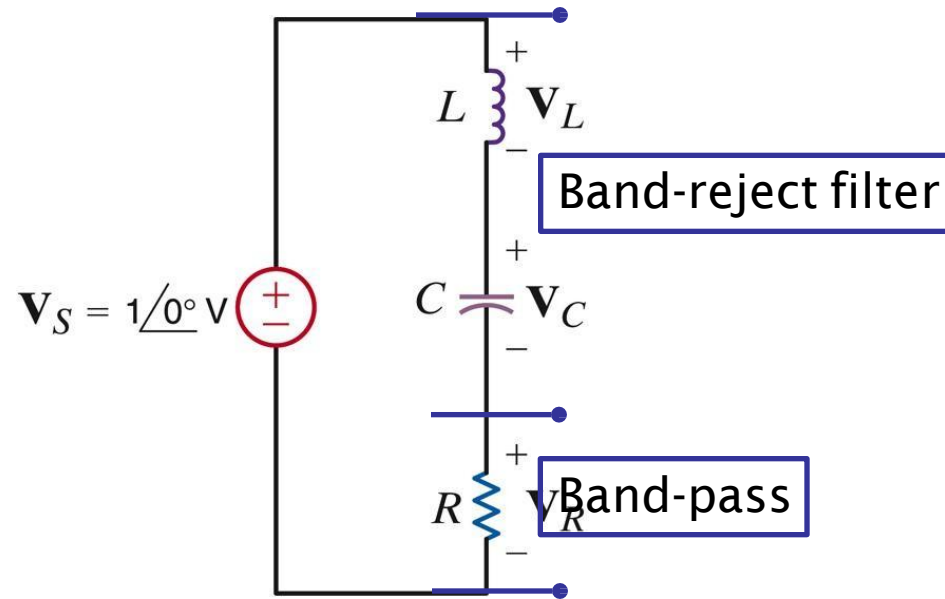
at  $\omega = \infty$  the inductor acts as open circuit  $\Rightarrow V_0 = V_1$

$\omega_{LO}$ ,  $\omega_{HI}$  are determined as in the band-pass filter



## LEARNING EXAMPLE

Depending on where the output is taken, this circuit can produce low-pass, high-pass or band-pass or band-reject filters



Bode plot for  $R = 10\Omega$ ,  $L = 159\mu\text{H}$ ,  $C = 159\mu\text{F}$

$$\frac{V_L}{V_S} = \frac{j\omega L}{R + j\left(\omega L - \frac{1}{\omega C}\right)}$$

$$\frac{V_L}{V_S}(\omega = 0) = 0, \quad \frac{V_L}{V_S}(\omega = \infty) = 1$$

High-pass

$$\frac{V_C}{V_S} = \frac{1}{R + j\left(\omega L - \frac{1}{\omega C}\right)}$$

$$\frac{V_C}{V_S}(\omega = 0) = 1, \quad \frac{V_C}{V_S}(\omega = \infty) = 0$$

Low-pass



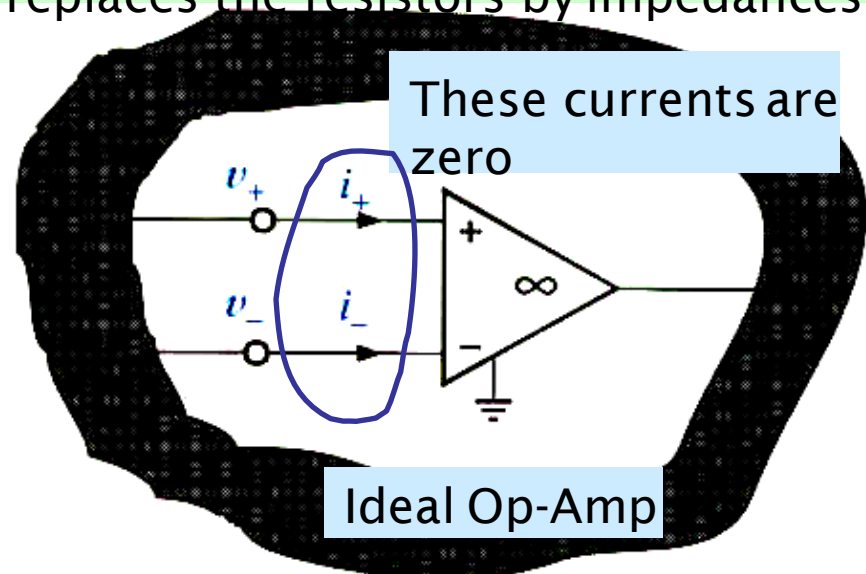
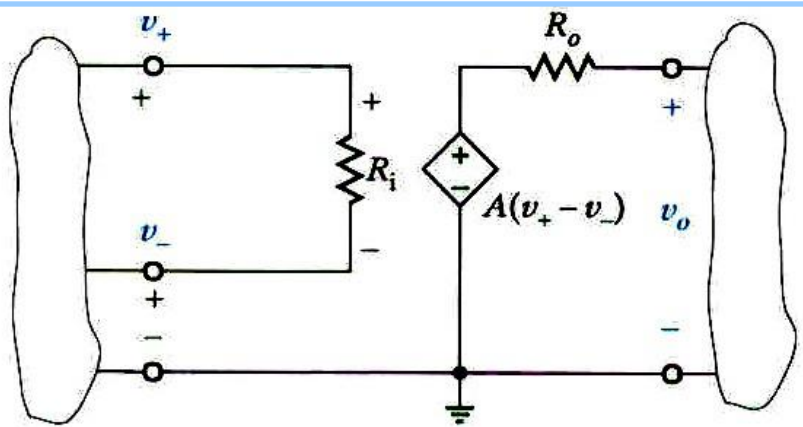
# ACTIVE FILTERS

Passive filters have several limitations

1. Cannot generate gains greater than one
2. Loading effect makes them difficult to interconnect
3. Use of inductance makes them difficult to handle

Using operational amplifiers one can design all basic filters, and more, with only resistors and capacitors

The linear models developed for operational amplifiers circuits are valid, in a more general framework, if one replaces the resistors by impedances



# DC TRANSIENT ANALYSIS

# SUB - TOPICS

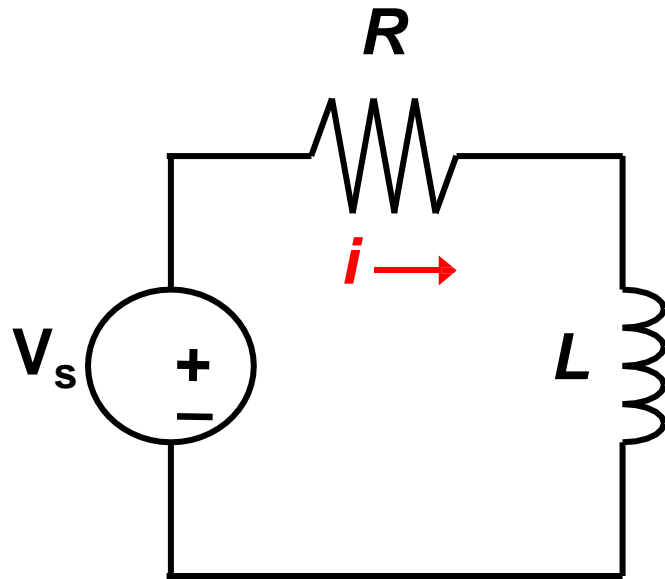
- NATURAL RESPONSE OF RLC CIRCUIT
- NATURAL RESPONSE OF RC CIRCUIT
- STEP RESPONSE OF RLC CIRCUIT
- STEP RESPONSE OF RC CIRCUIT

# OBJECTIVES

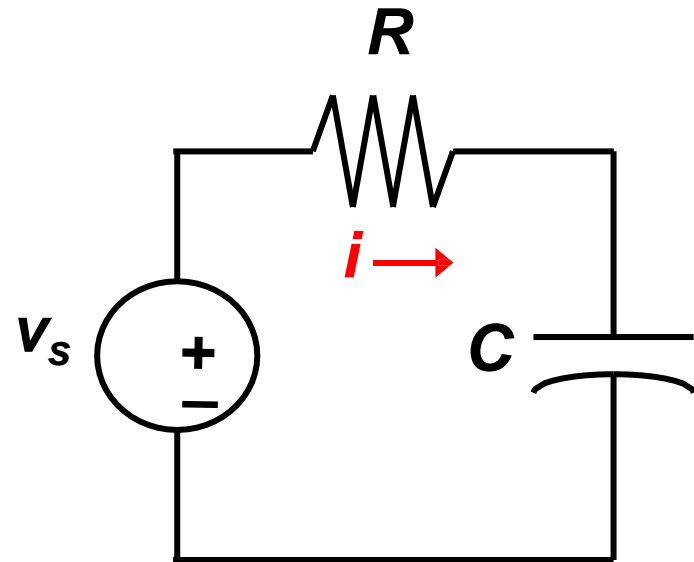
- To investigate the behavior of currents and voltages when energy is either released or acquired by inductors and capacitors when there is an abrupt change in dc current or voltage source.
- To do an analysis of natural response and step response of RL and RC circuit.

# FIRST – ORDER CIRCUITS

- A circuit that contains only sources, resistor and inductor is called an RL circuit.
- A circuit that contains only sources, resistor and capacitor is called an RC circuit.
- RL and RC circuits are called first – order circuits because their voltages and currents are described by first order differential equations.



An RL circuit

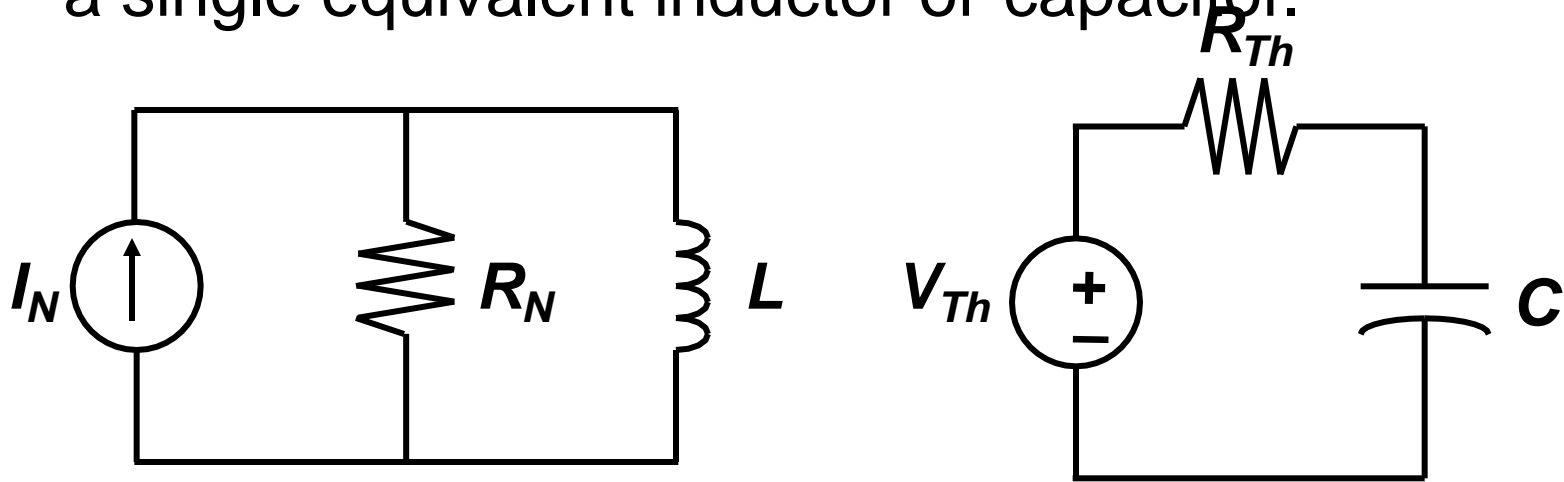


An RC circuit



# Review (conceptual)

- Any first – order circuit can be reduced to a Thévenin (or Norton) equivalent connected to either a single equivalent inductor or capacitor.

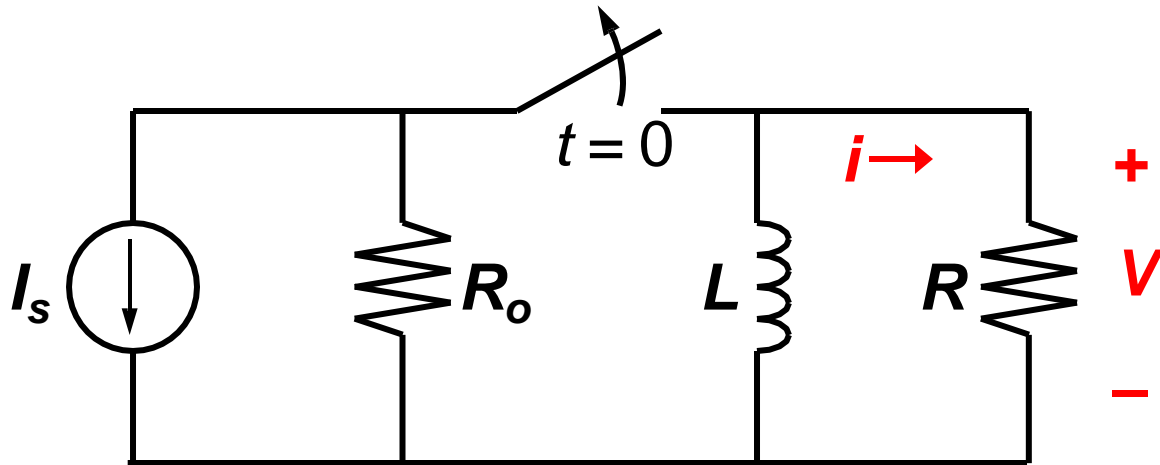


- In steady state, an inductor behave like a short circuit.
- In steady state, a capacitor behaves like an open circuit.

- The natural response of an RL and RC circuit is its behavior (i.e., current and voltage ) when stored energy in the inductor or capacitor is released to the resistive part of the network (containing no independent sources)
- The steps response of an RL and RC circuits is its behavior when a voltage or current source step is applied to the circuit, or immediately after a switch state is changed.

# NATURAL RESPONSE OF AN RL CIRCUIT

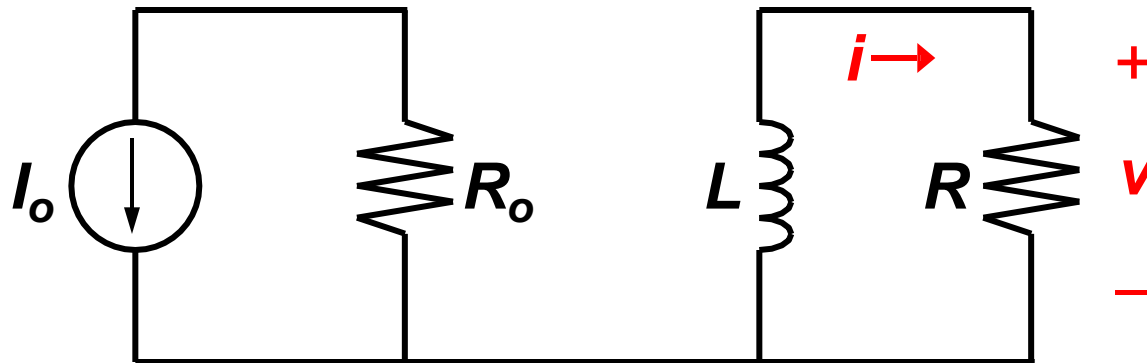
- Consider the following circuit, for which the switch is closed for  $t < 0$ , and then opened at  $t = 0$ :



- The dc voltage  $V$ , has been supplying the RL circuit with constant current for a long time

# Solving for the circuit

- For  $t \leq 0$ ,  $i(t) = I_o$
- For  $t \geq 0$ , the circuit reduce to



## Notation:

- $0^-$  is used to denote the time just prior to switching.
- $0^+$  is used to denote the time immediately after switching.

# Continue...

- Applying KVL to the circuit:

$$v(t) + Ri(t) = 0 \quad \text{_____} \quad \mathbf{(1)}$$

$$L \frac{di(t)}{dt} + Ri(t) = 0 \quad \text{_____} \quad \mathbf{(2)}$$

$$L \frac{di(t)}{dt} = -Ri(t) \quad \text{_____} \quad \mathbf{(3)}$$

$$\frac{di(t)}{i(t)} = -\frac{R}{L} dt \quad \text{_____} \quad \mathbf{(4)}$$

# Continue

- From equation (4), let say;

$$\frac{du}{u} = -\frac{R}{L}dv \quad \text{————— (5)}$$

- Integrate both sides of equation (5);

$$\int_{i(t_o)}^{i(t)} \frac{du}{u} = -\frac{R}{L} \int_{t_o}^t dv \quad \text{————— (6)}$$

- Where:

- ❖  $i(t_o)$  is the current corresponding to time  $t_o$
- ❖  $i(t)$  is the current corresponding to time  $t$

# Continue

■ Therefore,

$$\ln \frac{i(t)}{i(0)} = -\frac{R}{L}t \quad \text{—————} \quad (7)$$

■ hence, the current is

$$i(t) = i(0)e^{-(R/L)t} = I_0 e^{-(R/L)t}$$

# Continue

- From the Ohm's law, the voltage across the resistor  $R$  is:

$$v(t) = i(t)R = I_0 R e^{-(R/L)t}$$

- And the power dissipated in the resistor is:

$$p = v_L i_R(t) = I_0^2 R e^{-2(R/L)t}$$



# Continue

- Energy absorb by the resistor is:

$$w = \frac{1}{2} L I_0^2 (1 - e^{-2(R/L)t})$$

# Time Constant, $\tau$

- Time constant,  $\tau$  determines the rate at which the current or voltage approaches zero.

- Time constant,  $\tau = \frac{L}{R}$  (sec)

- The expressions for current, voltage, power and energy using time constant concept:

$$i(t) = I_0 e^{-t/\tau}$$

$$v(t) = I_0 R e^{-t/\tau}$$

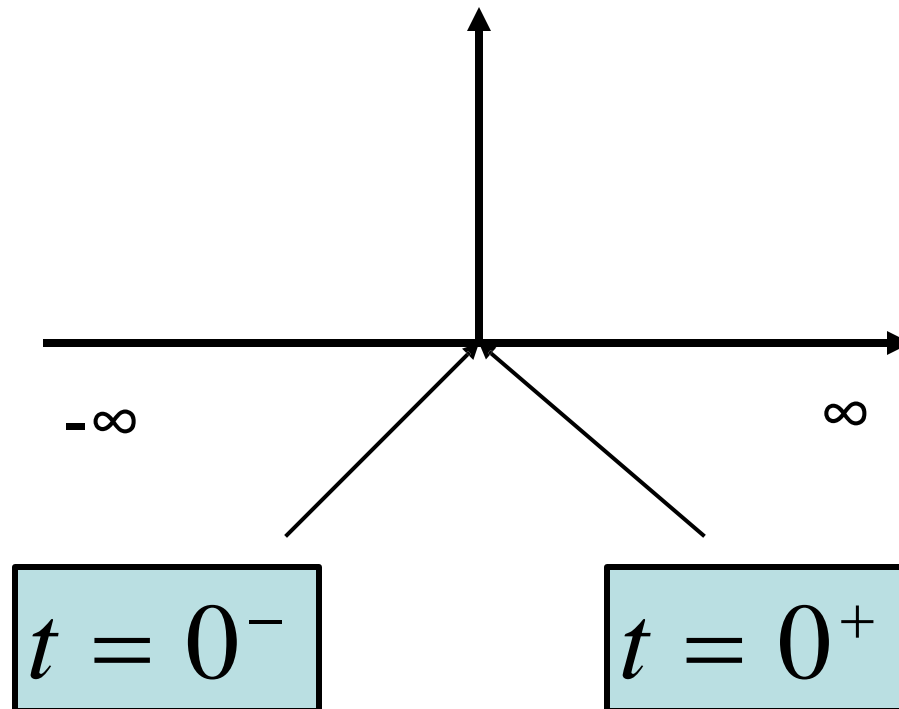
$$p = I_0^2 R e^{-2t/\tau}$$

$$w = \frac{1}{2} L I_0^2 (1 - e^{-2t/\tau})$$

# Switching time

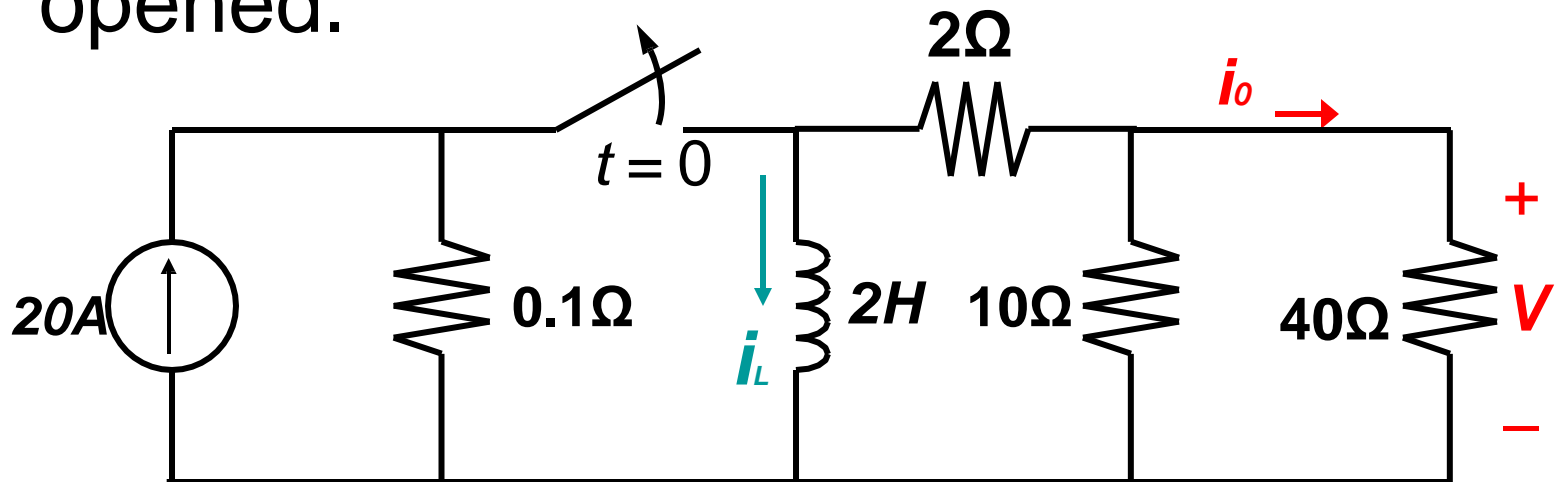
- For all transient cases, the following instants of switching times are considered.
- ✓  $t = 0^-$  , this is the time of switching between  $-\infty$  to 0 or time before.
- ✓  $t = 0^+$  , this is the time of switching at the instant just after time  $t = 0$ s (taken as initial value)
- ✓  $t = \infty$  , this is the time of switching between  $t = 0^+$  to  $\infty$  (taken as final value for step response)

- The illustration of the different instance of switching times is:



# Example

- For the circuit below, find the expression of  $i_o(t)$  and  $V_o(t)$ . The switch was closed for a long time, and at  $t = 0$ , the switch was opened.



# Solution :

Step 1:

Find  $\tau$  for  $t > 0$ . Draw the equivalent circuit. The switch is opened.

$$R_T = (2 + 10 // 40) = 10\Omega$$

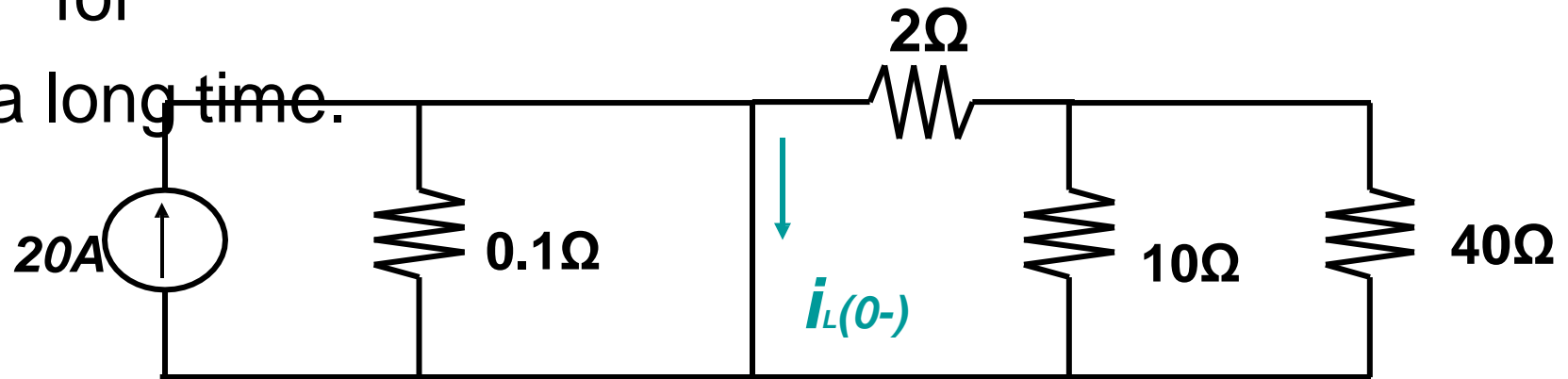
So;

$$\tau = \frac{L}{R_T} = \frac{2}{10} = 0.2 \quad \text{sec}$$

Step 2:

At  $t = 0^-$ , time from  $-\infty$  to  $0^-$ , the switch was closed for

a long time.



The inductor behave like a short circuit as it being supplied for a long time by a dc current source.

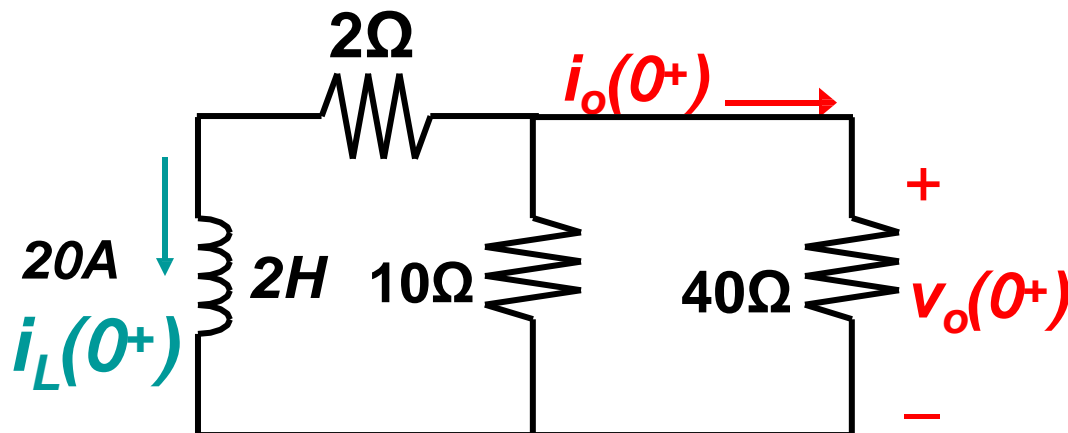
Current

20A thus flows through the short circuit until the switch



Step 3:

At the instant when the switch is opened, the time  $t = 0^+$ ,



The current through the inductor remains the same  
(continuous)

$$i_L(0^+) = i_L(0^-) = 20A$$

Thus,  
current.

which is the initial

Only at this particular instant the value of the current through  
the  
inductor is the same.

Since there is no other supply in the circuit after the switch is

By using current division, the current in the  $40\Omega$  resistor

is: 
$$i_o = -i_L \frac{10}{10 + 40} = -4A$$

So,

$$i_o(t) = -4e^{-5t} A$$

Using Ohm's Law, the  $V_o$  is:

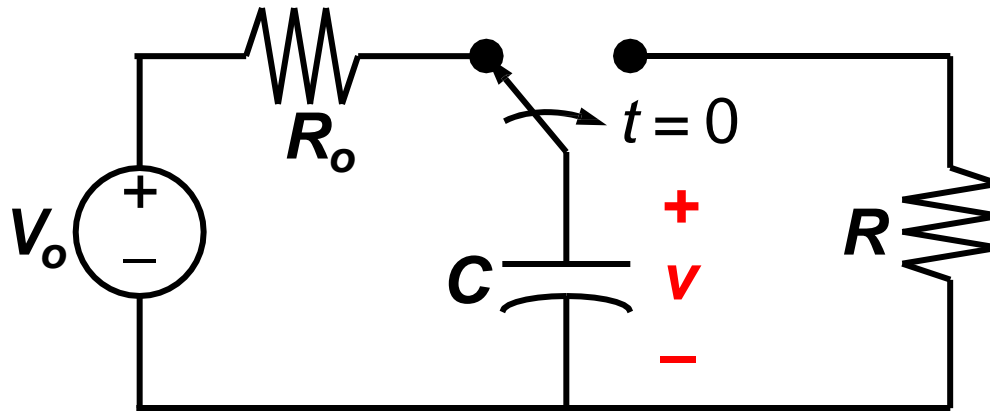
$$V_o(t) = -4 \times 40 = -160$$

So,

$$V_o(t) = -160e^{-5t}$$

# NATURAL RESPONSE OF AN RC CIRCUIT

- Consider the following circuit, for which the switch is closed for  $t < 0$ , and then opened at  $t = 0$ :

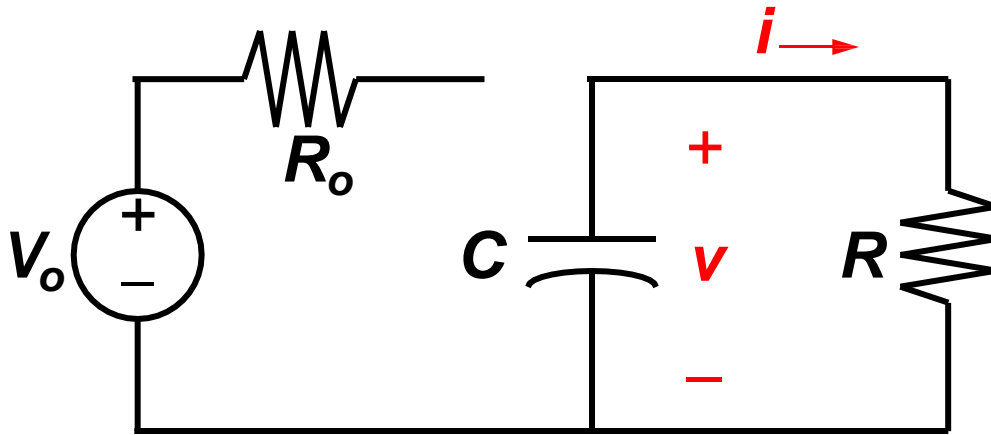


Notation:

- $0^-$  is used to denote the time just prior to switching
- $0^+$  is used to denote the time immediately after switching.

# Solving for the voltage ( $t \geq 0$ )

- For  $t \leq 0$ ,  $v(t) = V_o$
- For  $t > 0$ , the circuit reduces to



# Continue

■ Applying KCL to the RC circuit:

$$i_C + i_R = 0 \longrightarrow (1)$$

$$C \frac{dv(t)}{dt} + \frac{v(t)}{R} = 0 \longrightarrow (2)$$

$$\frac{dv(t)}{dt} + \frac{v(t)}{RC} = 0 \longrightarrow (3)$$

$$\frac{dv(t)}{dt} = - \frac{v(t)}{RC} \longrightarrow (4)$$

$$\frac{dv(t)}{v(t)} = - \frac{1}{RC} dt \longrightarrow (5)$$

)

# Continue

- From equation (5), let say:

$$\frac{dx}{x} = -\frac{1}{RC} dy \longrightarrow (6)$$

- Integrate both sides of equation (6):

$$\int_{V_o}^{v(t)} \frac{1}{x} du = -\frac{1}{RC} \int_0^t dy \longrightarrow (7)$$

- Therefore:

$$\ln \frac{v(t)}{V_o} = -\frac{t}{RC} \longrightarrow (8)$$

# Continue

- Hence, the voltage is:

$$v(t) = v(0)e^{-t/RC} = V_o e^{-t/RC}$$

- Using Ohm's law, the current is:

$$i(t) = \frac{v(t)}{R} = \frac{V_o}{R} e^{-t/RC}$$

# Continue

- The power dissipated in the resistor is:

$$p(t) = v i_R = \frac{V_o^2}{R} e^{-2t/RC}$$

- The energy absorb by the resistor is:

$$w = \frac{1}{2} C V_o^2 (1 - e^{-2t/RC})$$



# Continue

- The time constant for the RC circuit equal the product of the resistance and capacitance,

- Time constant,  $\tau = RC$  sec

- The expressions for voltage, current, power and energy using time constant concept:

$$v(t) = V_o e^{-t/\tau}$$

$$i(t) = \frac{V_o}{R} e^{-t/\tau}$$

$$p(t) = \frac{V_o^2}{R} e^{-2t/\tau}$$

$$w(t) = \frac{1}{2} C V_o^2 (1 - e^{-2t/\tau})$$

■ For the case of capacitor, two important observation can be made,

1) capacitor behaves like an open circuit when being supplied by dc source

(From,  $i_c = Cdv/dt$ , when  $v$  is constant,  $dv/dt = 0$ . When current in circuit is zero, the circuit is open circuit.)

2) in capacitor, the voltage is continuous / stays the same that is,  $V_c(0^+) = V_c(0^-)$

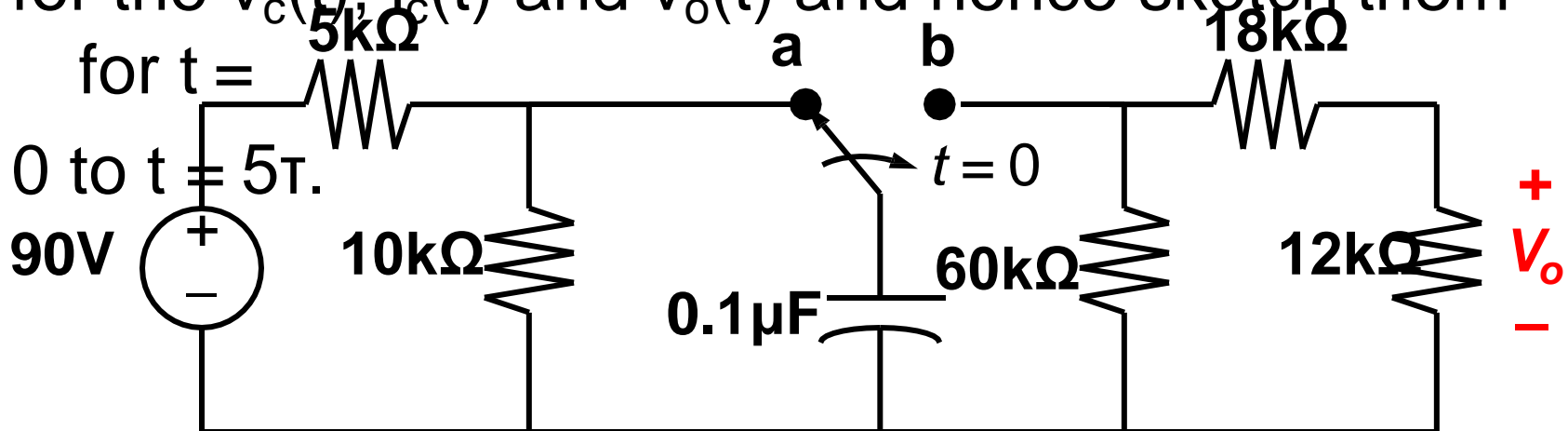
# Example

The switch has been in position *a* for a long time.

At

Time  $t = 0$ , the switch moves to *b*. Find the expressions

for the  $v_c(t)$ ,  $i_c(t)$  and  $v_o(t)$  and hence sketch them for  $t =$

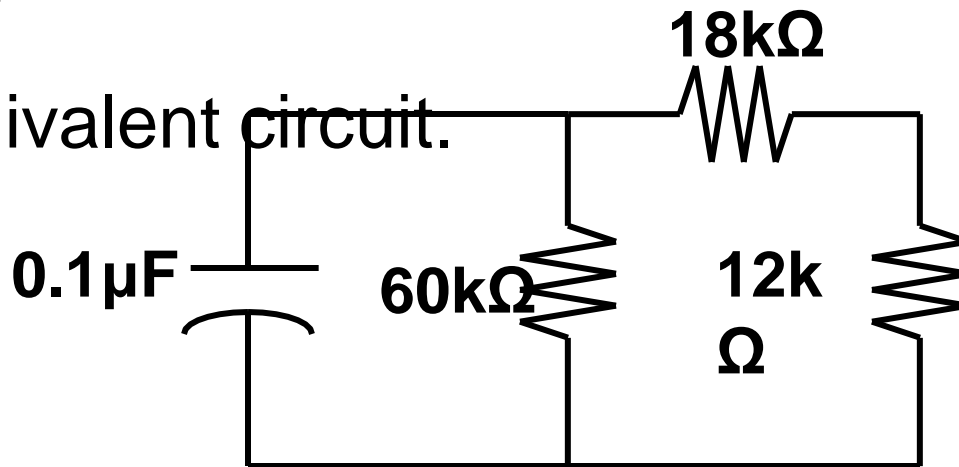


# Solution

Step 1:

Find  $t$  for  $t > 5\tau$  that is when the switch was at a.

Draw  
the equivalent circuit.



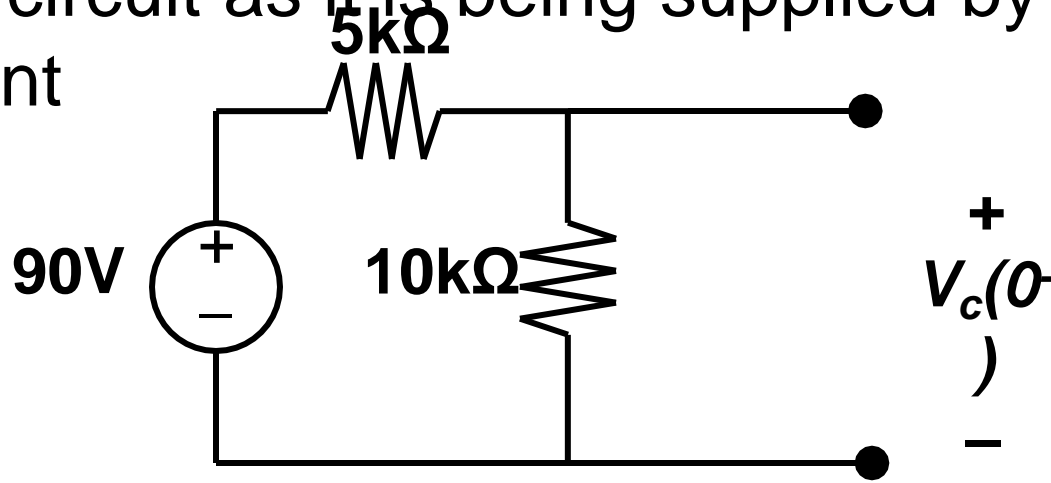
$$R_T = (18\text{k}\Omega + 12\text{k}\Omega) // 60\text{k}\Omega = 20\text{k}\Omega$$

$$\tau = R_T C = 20 \times 10^3 \times 0.1 \times 10^{-6} = 2\text{ms}$$

Step 2:

At  $t = 0$ , the switch was at  $a$ . the capacitor behaves like

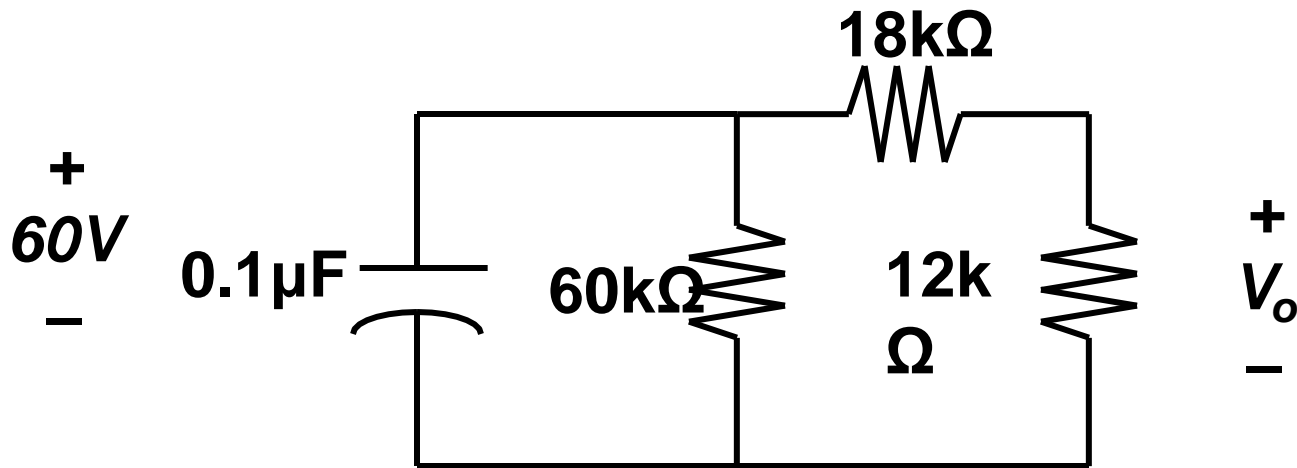
An open circuit as it is being supplied by a constant source.



$$v_c(0^-) = \frac{10}{15} \times 90 = 60V$$

Step 3:

At  $t = 0^+$ , the instant when the switch is at  $b$ .



The voltage across capacitor remains the same at this particular instant.

$$v_c(0^+) = v_c(0^-) = 60V$$

Using voltage divider rule,

$$V_o(0^+) = \frac{12}{30} \times 60 = 24V$$

Hence;

$$v_c(t) = 60e^{-500t} V$$

$$v_o(t) = 24e^{-500t} V$$

$$i_c(t) = -0.03e^{-500t} A$$

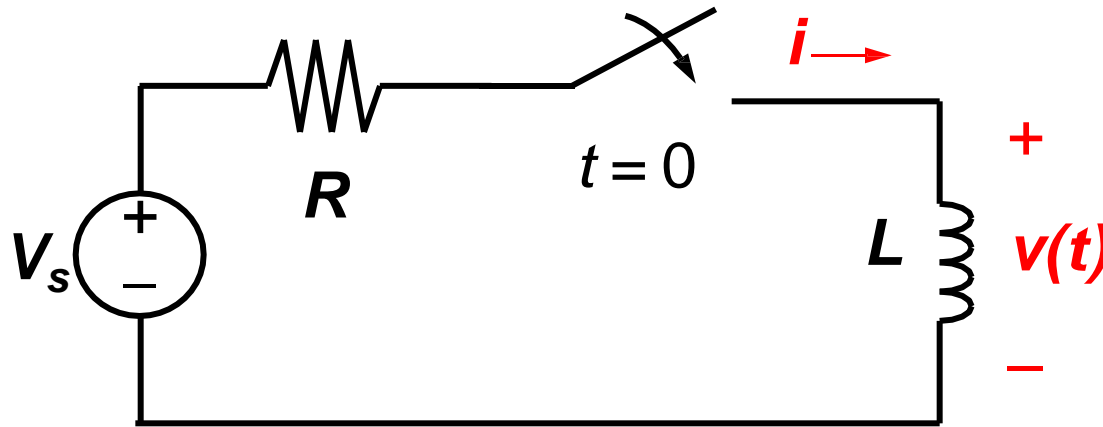


# Summary

No	RL circuit	RC circuit
1	$\tau = \frac{L}{R}$	$\tau = RC$
2	Inductor behaves like a short circuit when being supplied by dc source for a long time	Capacitor behaves like an open circuit when being supplied by dc source for a long time
3	Inductor current is continuous $i_L(0^+) = i_L(0^-)$	Voltage across capacitor is continuous $v_C(0^+) = v_C(0^-)$

# Step Response of RL Circuit

- The switch is closed at time  $t = 0$ .



- After switch is closed, using KVL

$$V_s = Ri(t) + L \frac{di}{dt} \longrightarrow (1)$$

# Continue

■ Rearrange the equation;

$$\frac{di(t)}{dt} = \frac{-Ri(t) + V_s}{L} = \frac{-R}{L} \left( i(t) - \frac{V_s}{R} \right) \longrightarrow (2)$$

$$di = \frac{-R}{L} \left( i - \frac{V_s}{R} \right) dt \longrightarrow (3)$$

$$\frac{R}{L} dt \frac{di}{i(t) - V_s/R} \longrightarrow (4)$$

$$-\frac{R}{L} \int_0^t dv = \int_0^{i(t)} \frac{du}{u - (V_s/R)} \longrightarrow (5)$$

# Continue

■ Therefore:

$$-\frac{R}{L}t = \ln \frac{i(t) - (V_s/R)}{I_0 - (V_s/R)} \longrightarrow (5)$$

■ Hence, the current is;

$$i(t) = \frac{V_s}{R} + \left( I_o - \frac{V_s}{R} \right) e^{-(R/L)t}$$

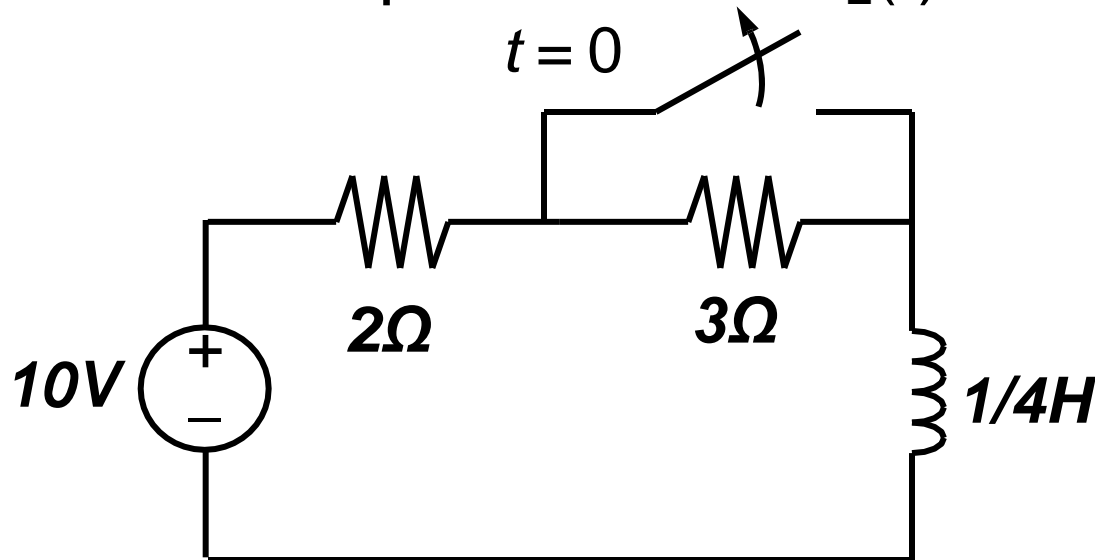
■ The voltage;

$$v(t) = (V_s - I_o R) e^{-(R/L)t}$$

# Example

The switch is closed for a long time at  $t = 0$ , the switch

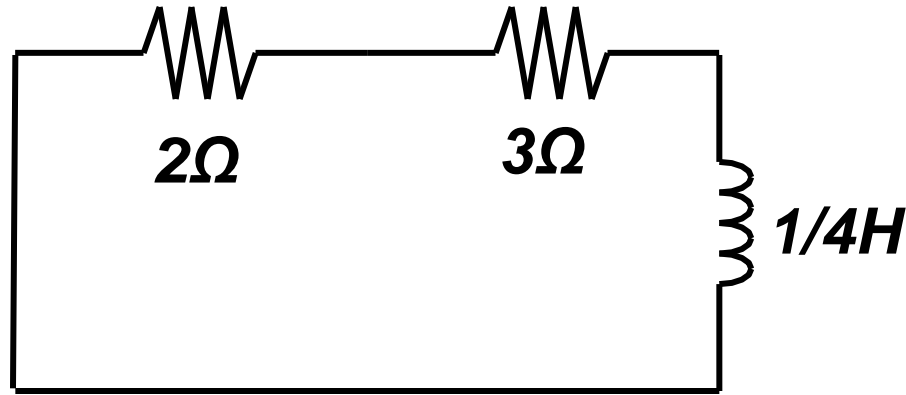
opens. Find the expressions for  $i_L(t)$  and  $v_L(t)$ .



# Solution

Step 1:

Find  $\tau$  for  $t > 0$ . The switch was opened. Draw the equivalent circuit. Short circuit the voltage source.



$$R_T = (2 + 3)\Omega = 5\Omega$$

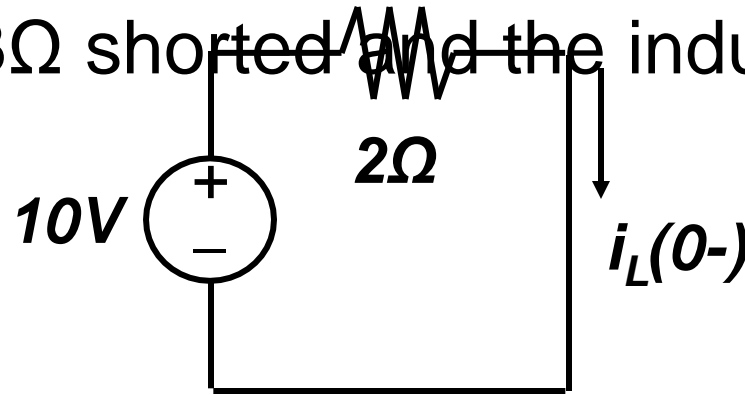
$$\tau = \frac{L}{R_T} = \frac{1}{20} s$$

# Continue

Step 2:

At  $t = 0^-$ , the switch was closed. Draw the equivalent

circuit with  $3\Omega$  shorted and the inductor behaves like a short circuit.



$$i_L(0^-) = 10 / 2 = 5A$$

# Continue

Step 3:

At  $t = 0^+$ , the instant switch was opened. The current in

inductor is continuous,  
$$I_0 = i_L(0^+) = i_L(0^-) = 5A$$

Step 4:

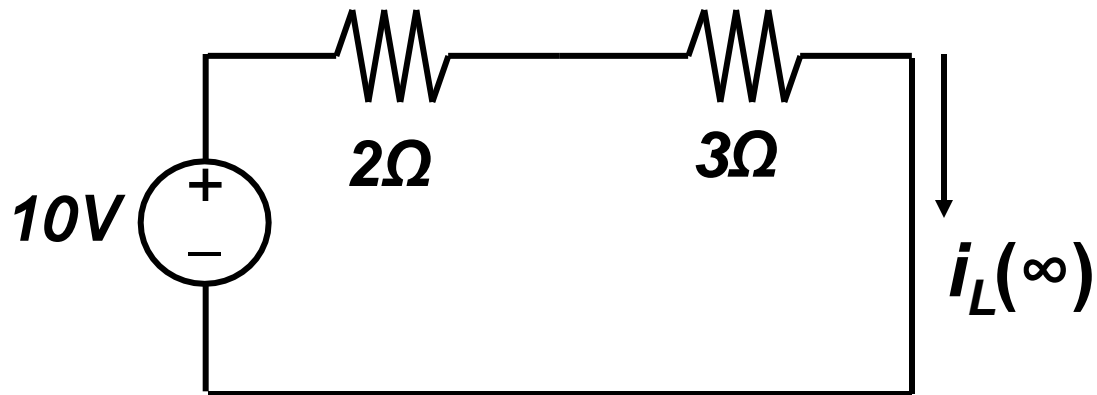
At  $t = \infty$ , that is after a long time the switch has been left

opened. The inductor will once again be behaving like a

short circuit.



# Continue



$$i_L(\infty) = V_s / R_T = 2A$$

Hence:

$$i_L(t) = \frac{V_s}{R} + \left( I_o - \frac{V_s}{R} \right) e^{-(R/L)t}$$

$$i_L(t) = 2 + 3e^{-20t} A$$

# Continue

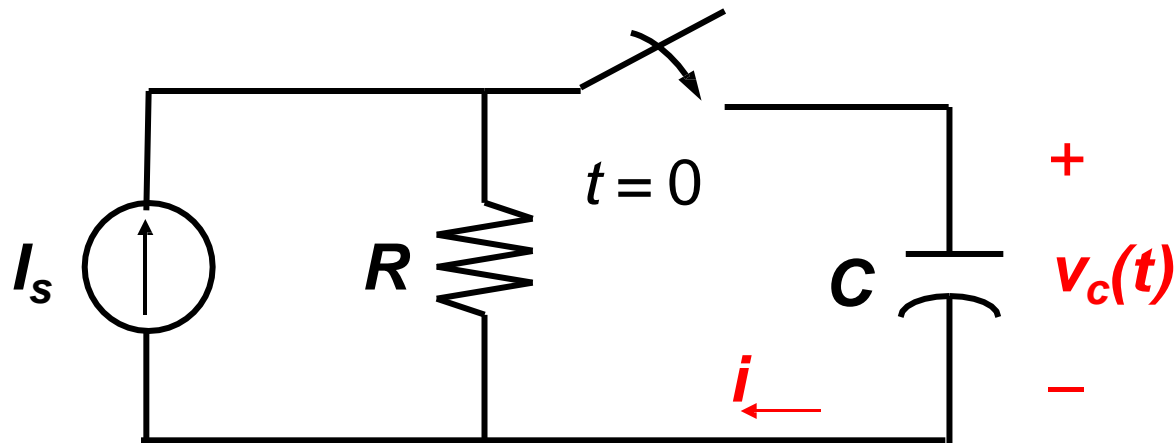
■ And the voltage is:

$$v_L(t) = (V_s - I_o R)e^{-(R/L)t}$$

$$v_L(t) = -15e^{-20t}V$$

# Step Response of RL Circuit

- The switch is closed at time  $t = 0$



- From the circuit;

$$\boxed{I_s = C \frac{dv_c}{dt} + \frac{v_c}{R}} \longrightarrow (1)$$

# Continue

- Division of Equation (1) by C gives;

$$\boxed{\frac{I_s}{C} = \frac{dv_c}{dt} + \frac{v_c}{RC}} \longrightarrow \textbf{(2)}$$

- Same mathematical techniques with RL, the voltage is:

$$v_c(t) = I_s R + (V_o - I_s R) e^{-t/RC}$$

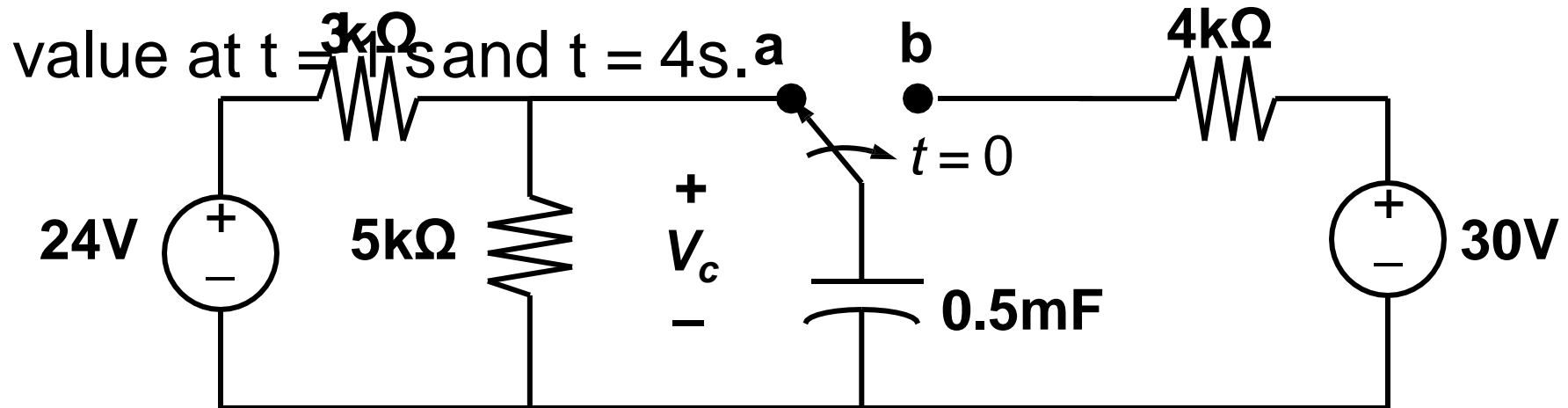
- And the current is:

$$i(t) = \left( I_s - \frac{V_o}{R} \right) e^{-t/RC}$$

# Example

The switch has been in position *a* for a long time. At  $t = 0$ ,

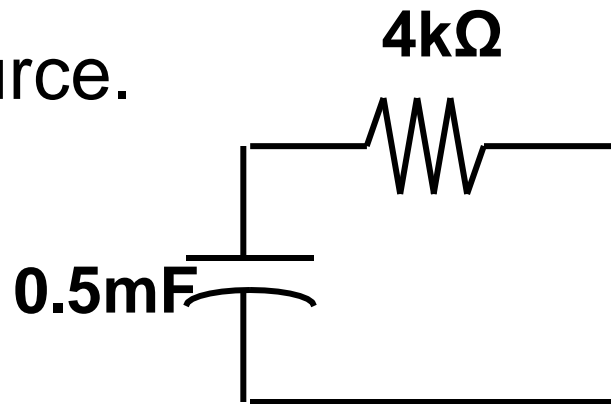
the switch moves to *b*. Find  $V_c(t)$  for  $t > 0$  and calculate its



# Solution

Step 1:

To find  $\tau$  for  $t > 0$ , the switch is at  $b$  and short circuit the voltage source.



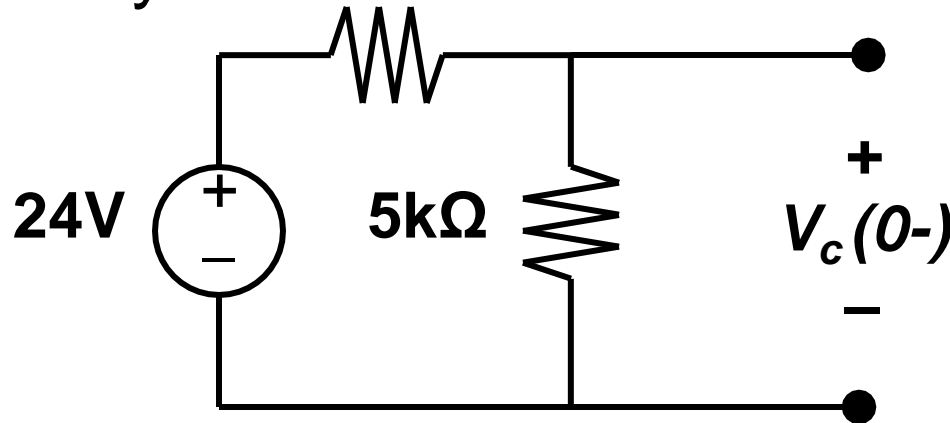
$$\tau = RC = 2s$$

# Continue

Step 2:

The capacitor behaves like an open circuit as it is being

supplied by a constant dc source.



From the circuit,  $V_c(0^-) = 24 \times \frac{5}{8} = 15V$

# Continue

Step 3:

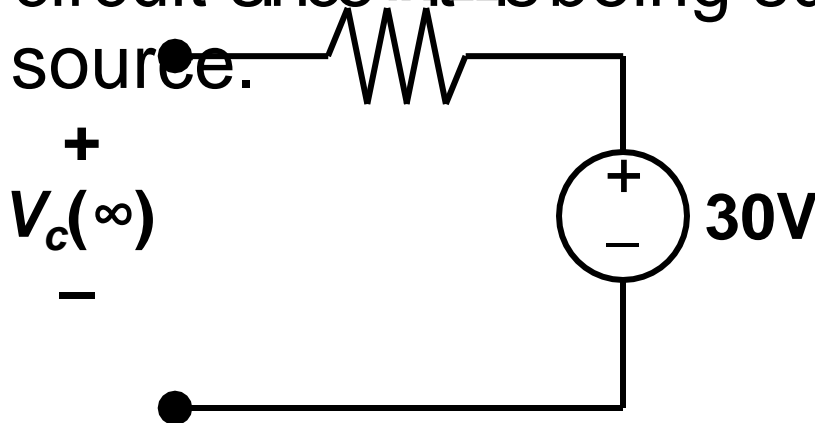
At  $t = 0^+$ , the instant when the switch is just moves to  $b$ .

Voltage across capacitor remains the same.

$$V_c(0^+) = V_c(0^-) = 15V$$

Step 4:

At  $t = \infty$ , the capacitor again behaves like an open circuit since  $4k\Omega$  is being supplied by a constant source.



$$V_c(\infty) = 30V$$



# Continue

Step 5:

Hence,

$$V_c(t) = 30 + (15 - 30)e^{-0.5t} = 30 - 15e^{-0.5t}V$$

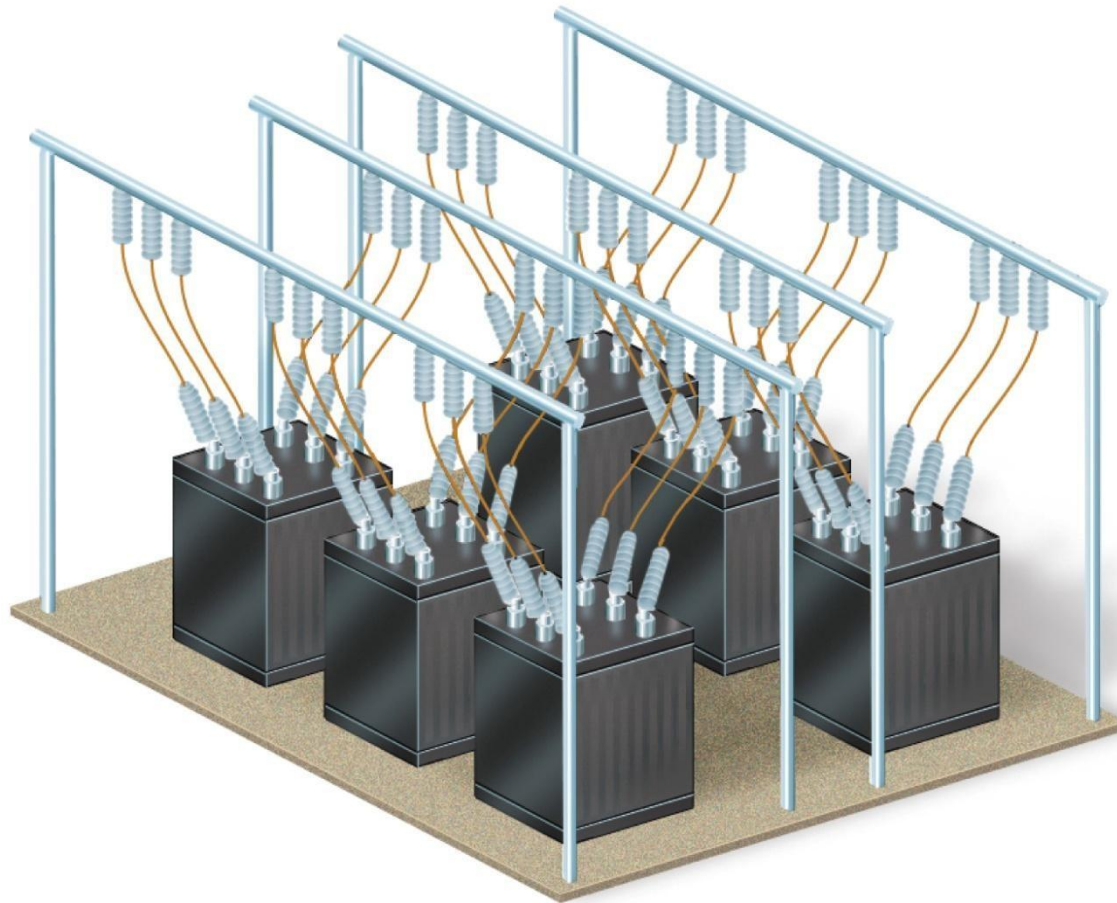
At  $t = 1s$ ,  $V_c(t) = 20.9V$

At  $t = 4s$ ,  $V_c(t) = 28V$

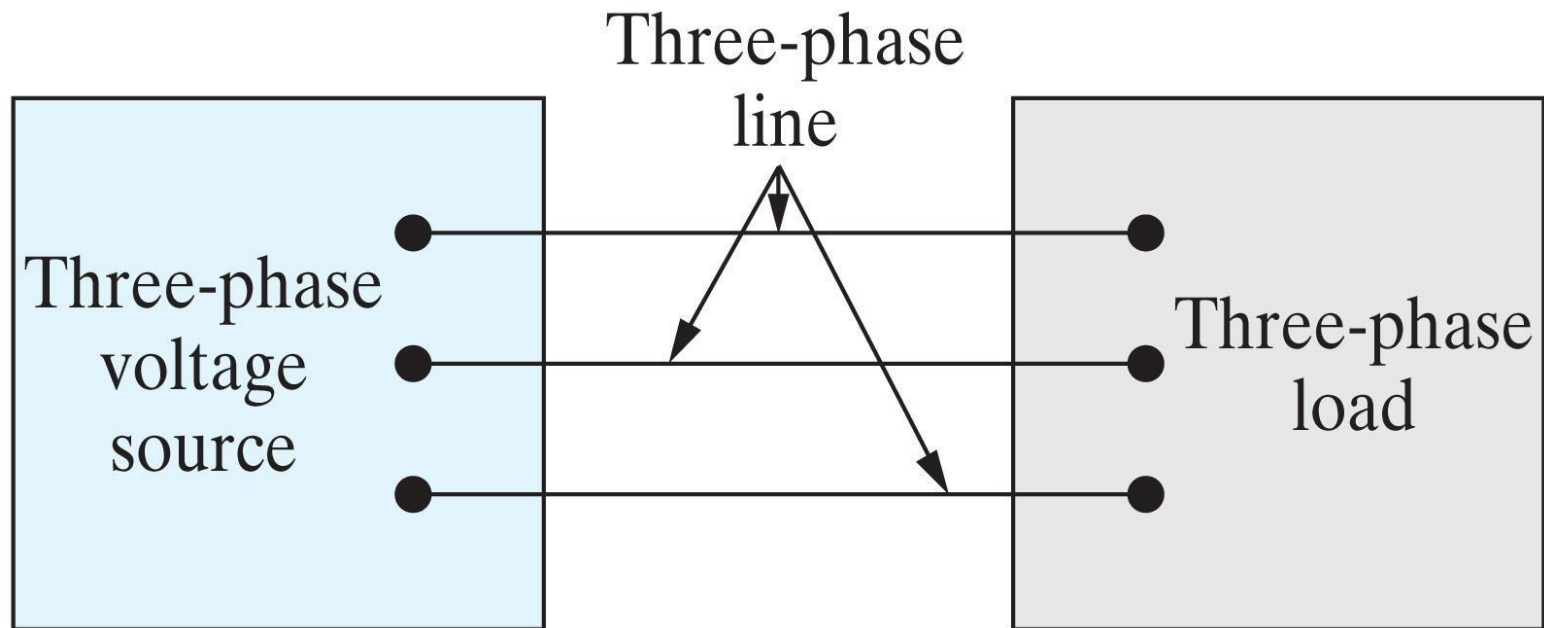
# Introduction to Three-Phase Power



# Typical Transformer Yard



# Basic Three-Phase Circuit

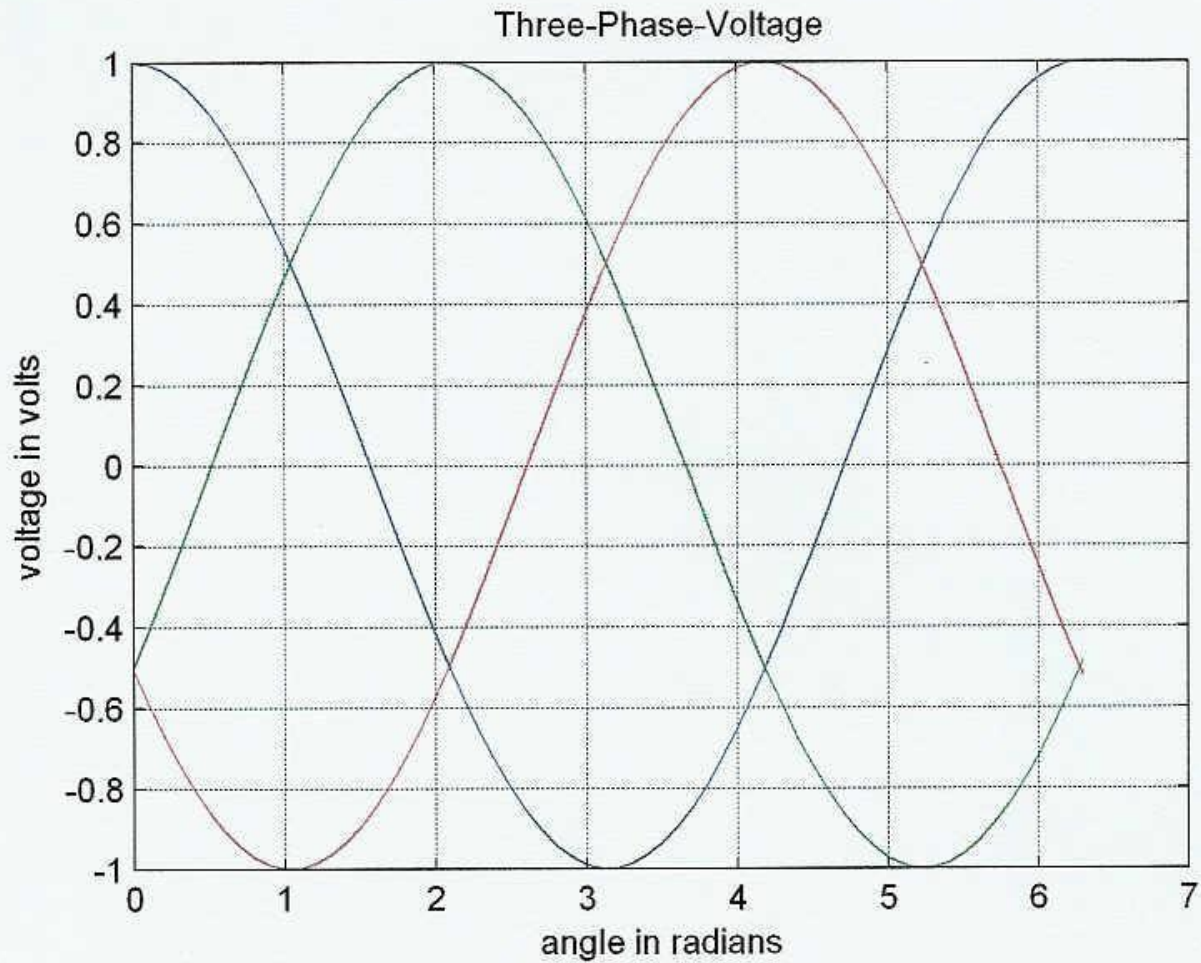


# What is Three-Phase Power?

- Three sinusoidal voltages of equal amplitude and frequency out of phase with each other by  $120^\circ$ . Known as “balanced”.
- Phases are labeled A, B, and C.
- Phases are sequenced as A, B, C (positive) or A, C, B (negative).



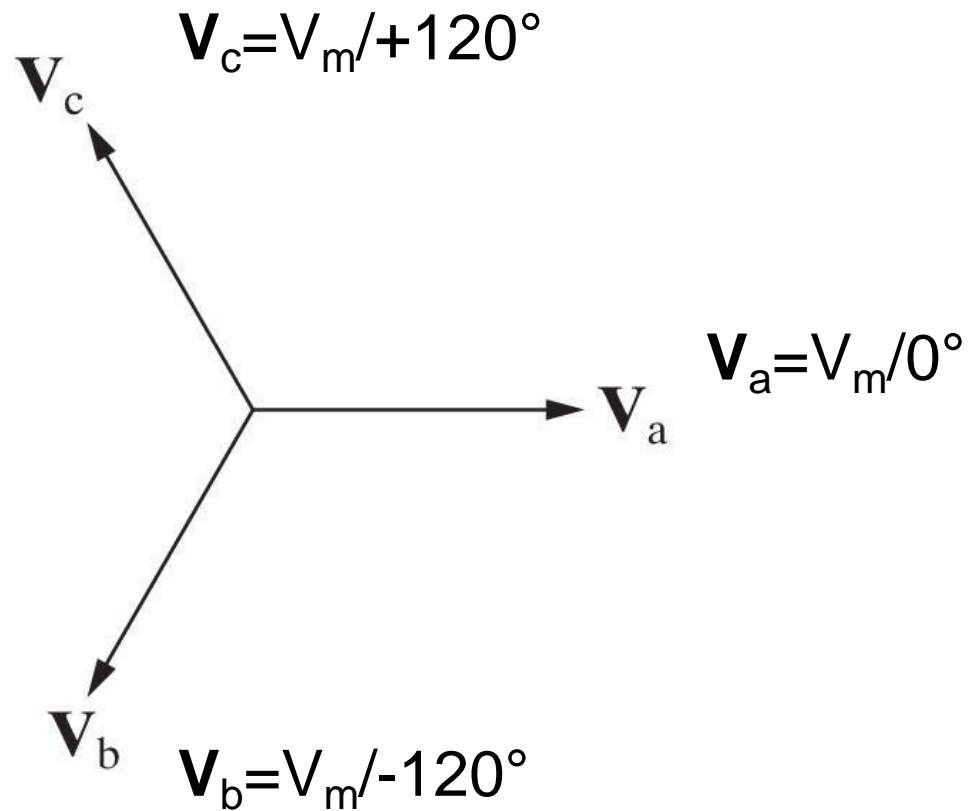
# Three-Phase Power



# Definitions

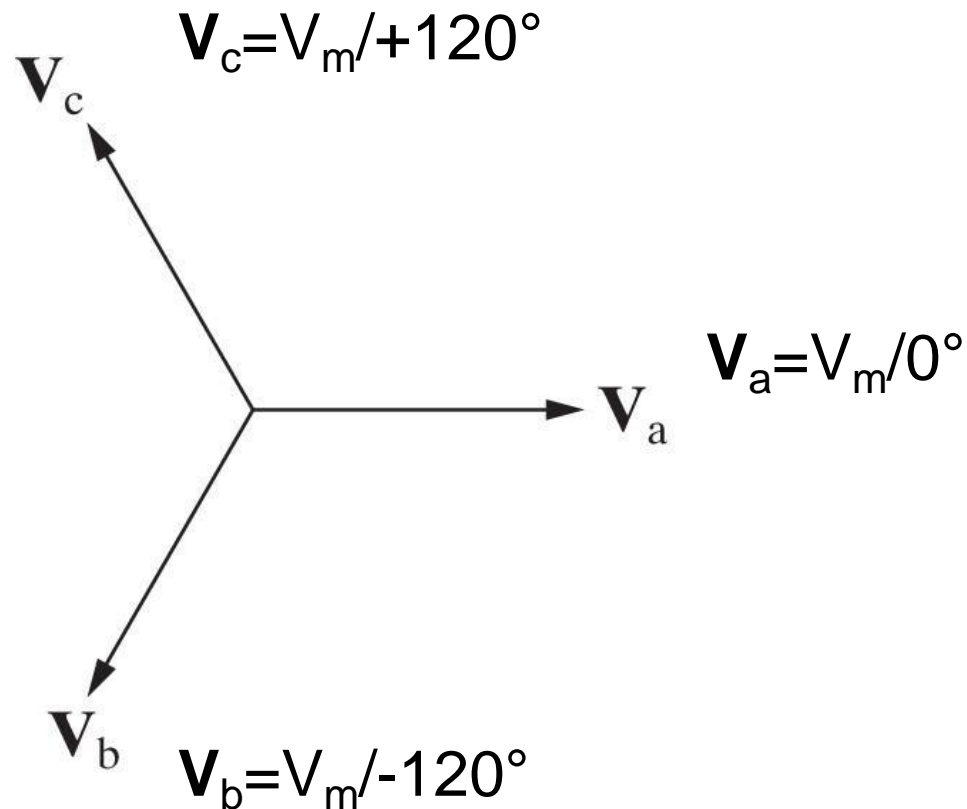
- 4 wires
  - 3 “active” phases, A, B, C
  - 1 “ground”, or “neutral”
- Color Code
  - Phase A      Red
  - Phase B      Black
  - Phase C      Blue
  - Neutral      White or Gray

# Phasor (Vector) Form for abc





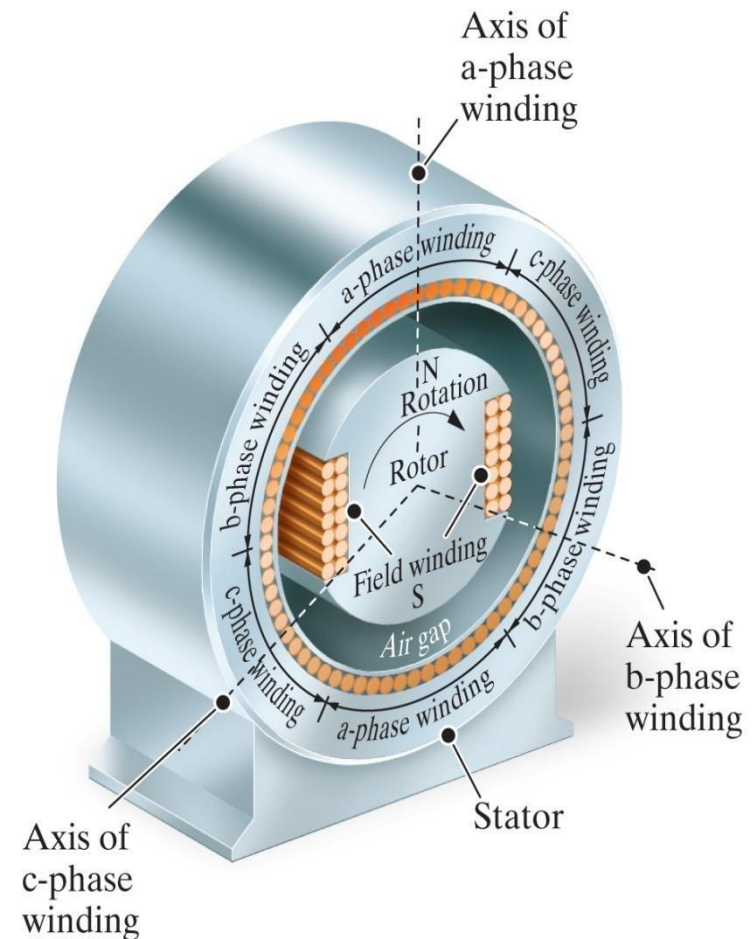
# Phasor (Vector) Form for abc

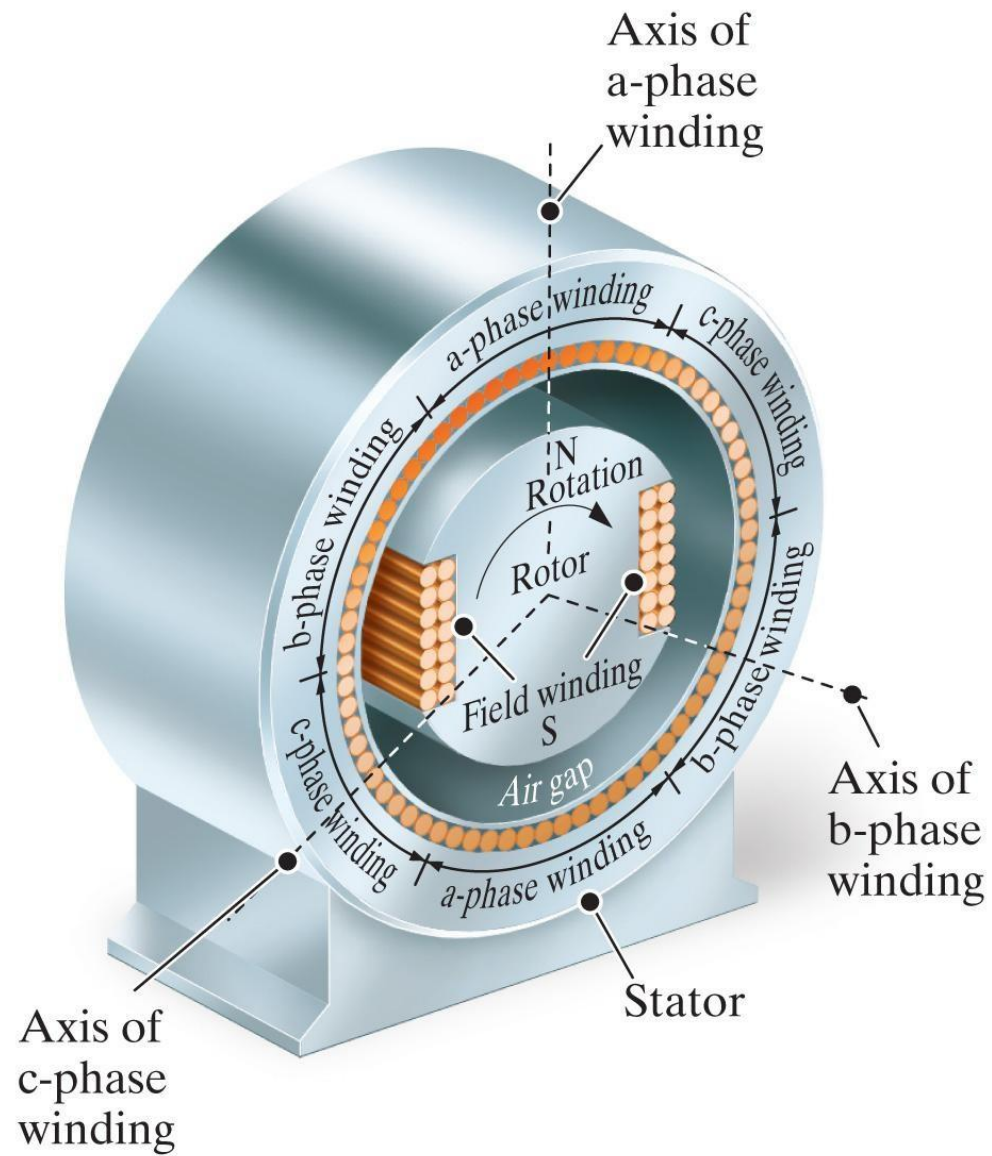


Note that KVL applies ....  $\mathbf{V}_a + \mathbf{V}_b + \mathbf{V}_c = 0$

# Three-Phase Generator

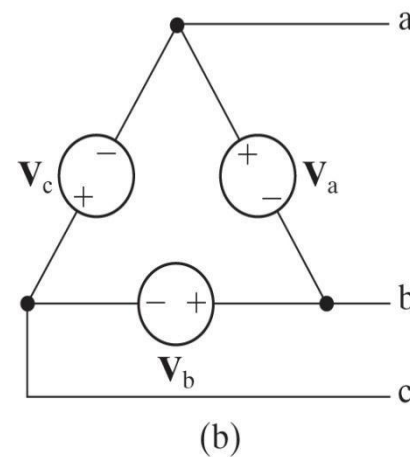
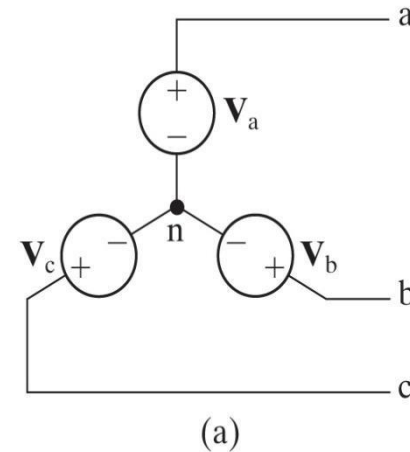
- 2-pole (North-South) rotor turned by a “prime mover”
- Sinusoidal voltages are induced in each stator winding



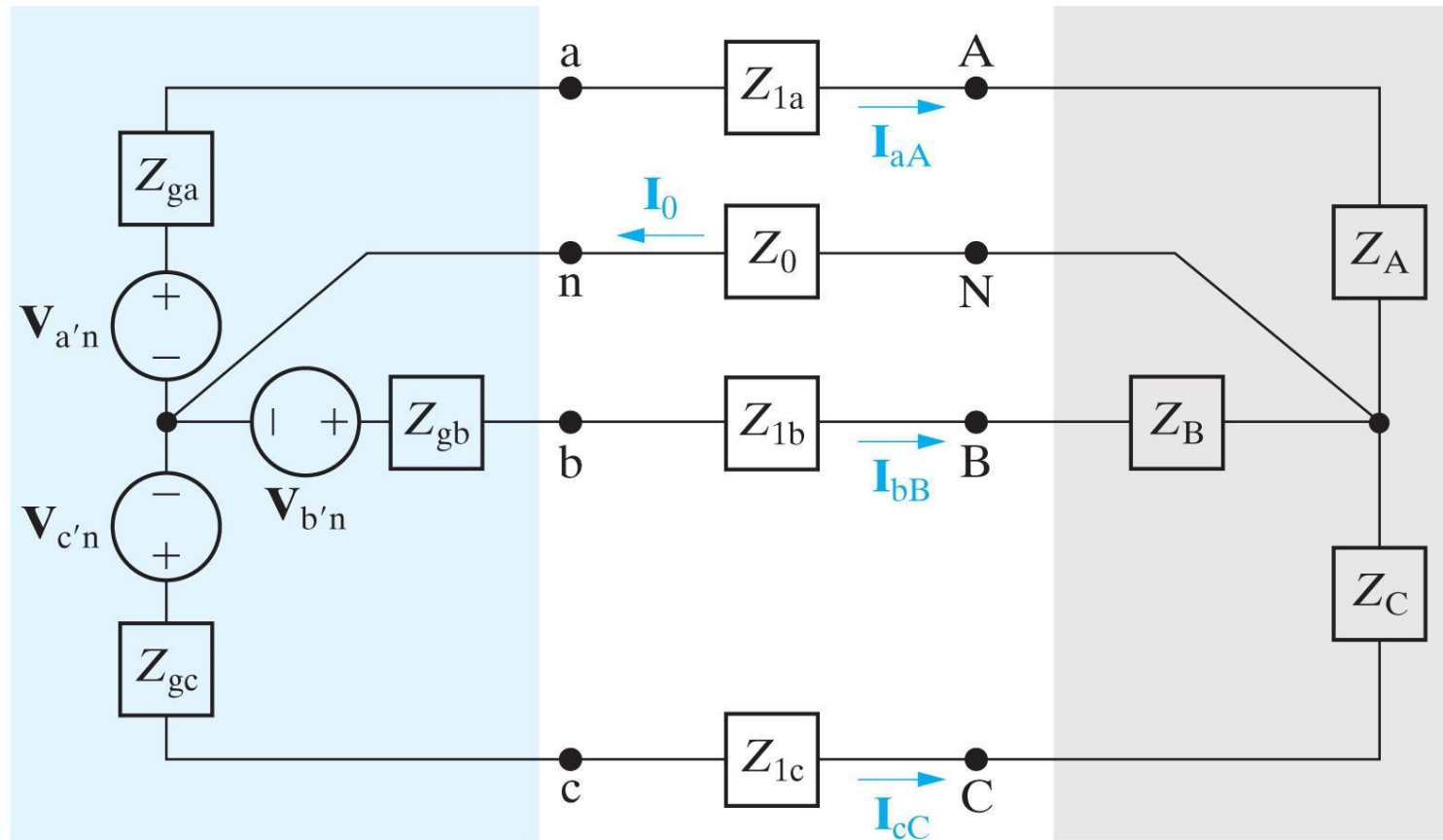


# How are the sources connected?

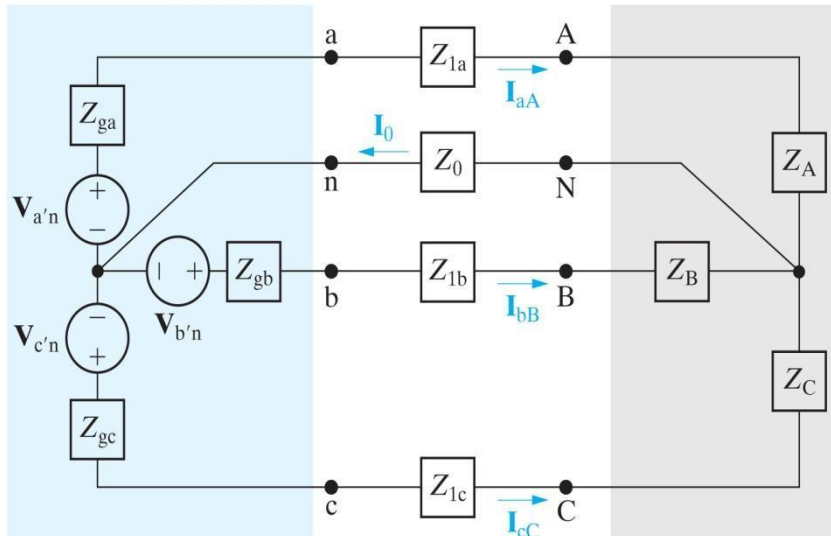
- (a) shows the sources (phases) connected in a wye (Y).
  - Notice the fourth terminal, known as Neutral.
- (b) shows the sources (phases) connected in a delta ( $\Delta$ ).
  - Three terminals



# Look at a Y-Y System

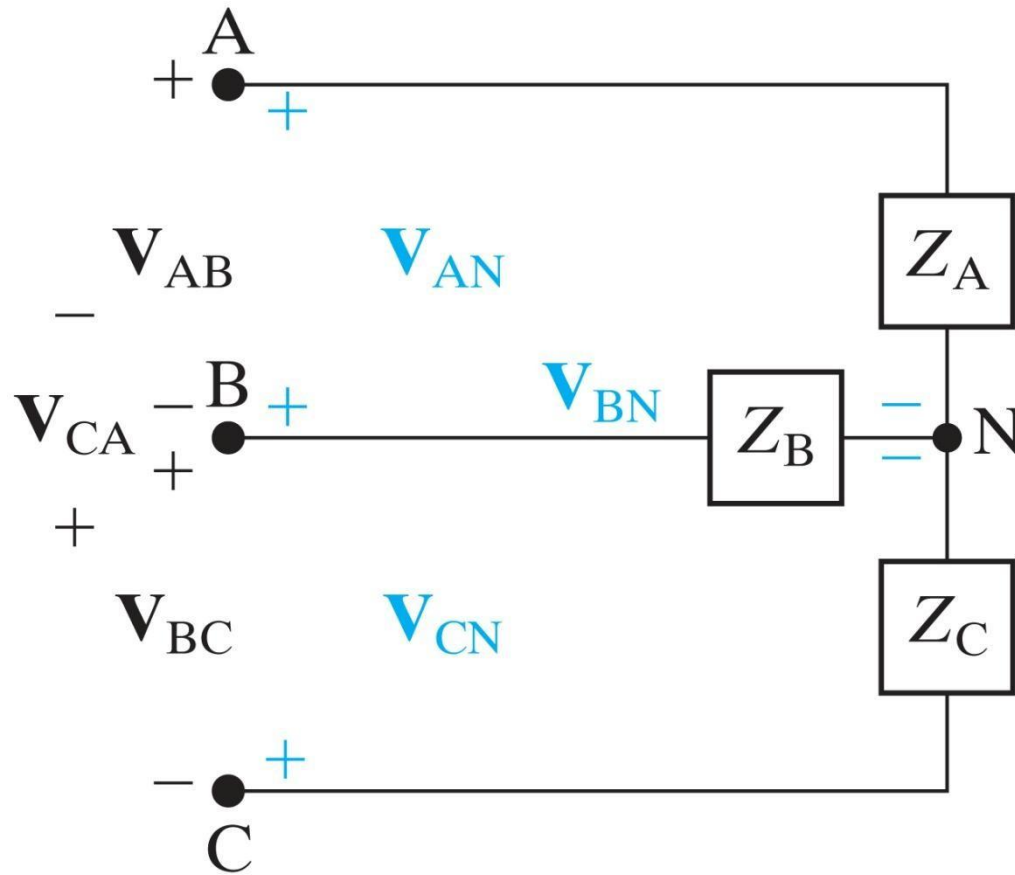


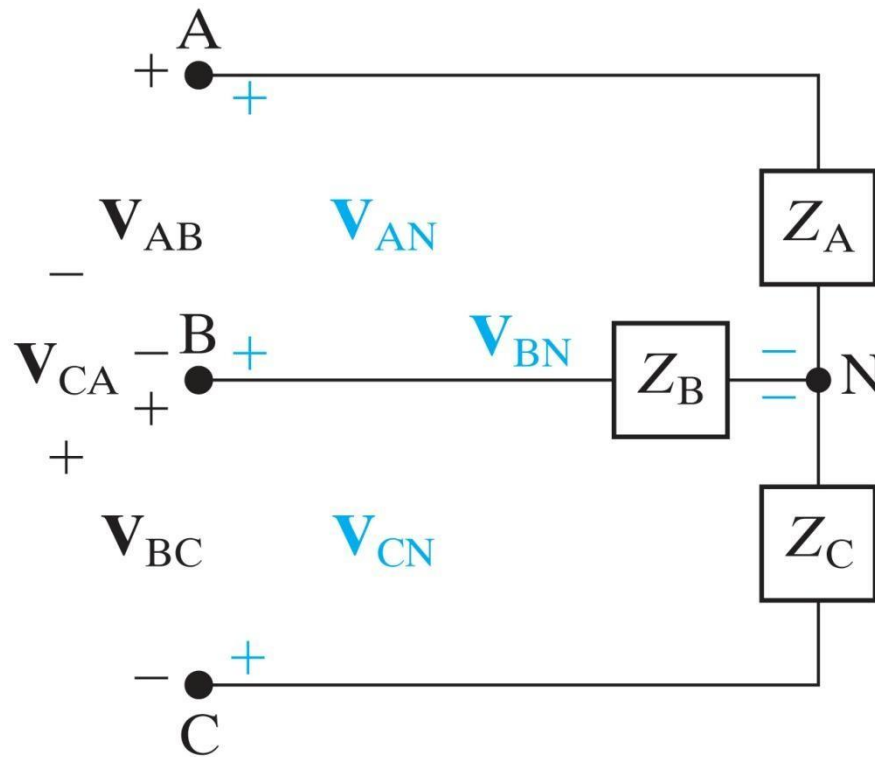
# Definitions



- $Z_g$  represents the internal generator impedance per phase
- $Z_l$  represents the impedance of the line connecting the generator to the load
- $Z_{A,B,C}$  represents the load impedance per phase
- $Z_0$  represents the impedance of the neutral conductor

# Look at the Line and Load Voltages





$$V_{AB} = V_{AN} - V_{BN}$$

$$V_{BC} = V_{BN} - V_{CN}$$

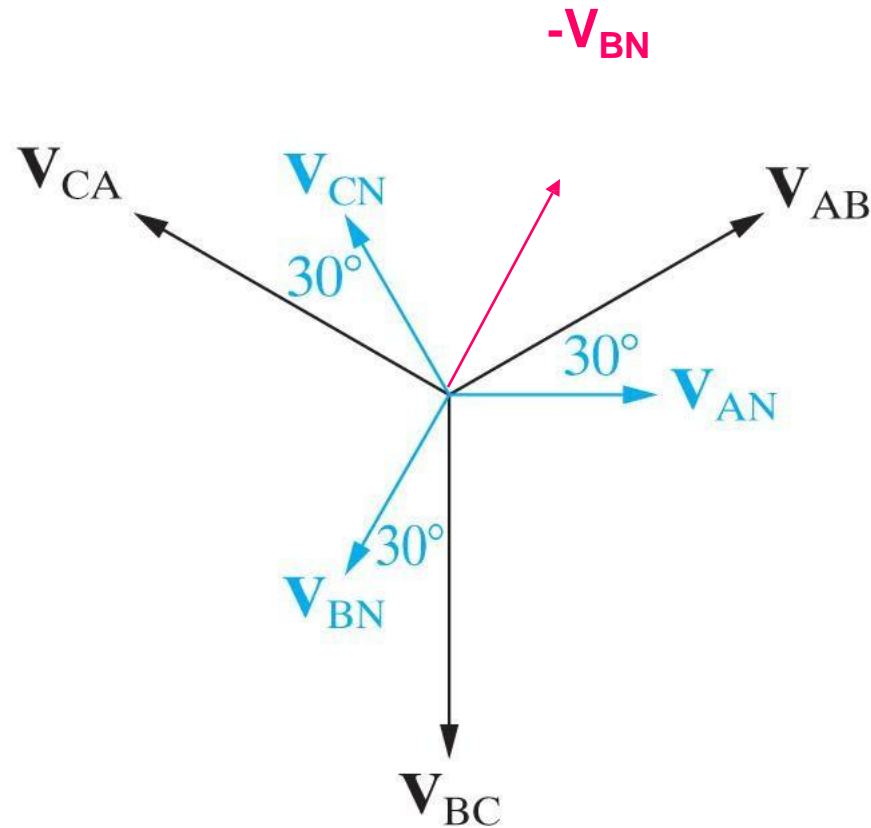
$$V_{CA} = V_{CN} - V_{AN}$$

Line Voltages

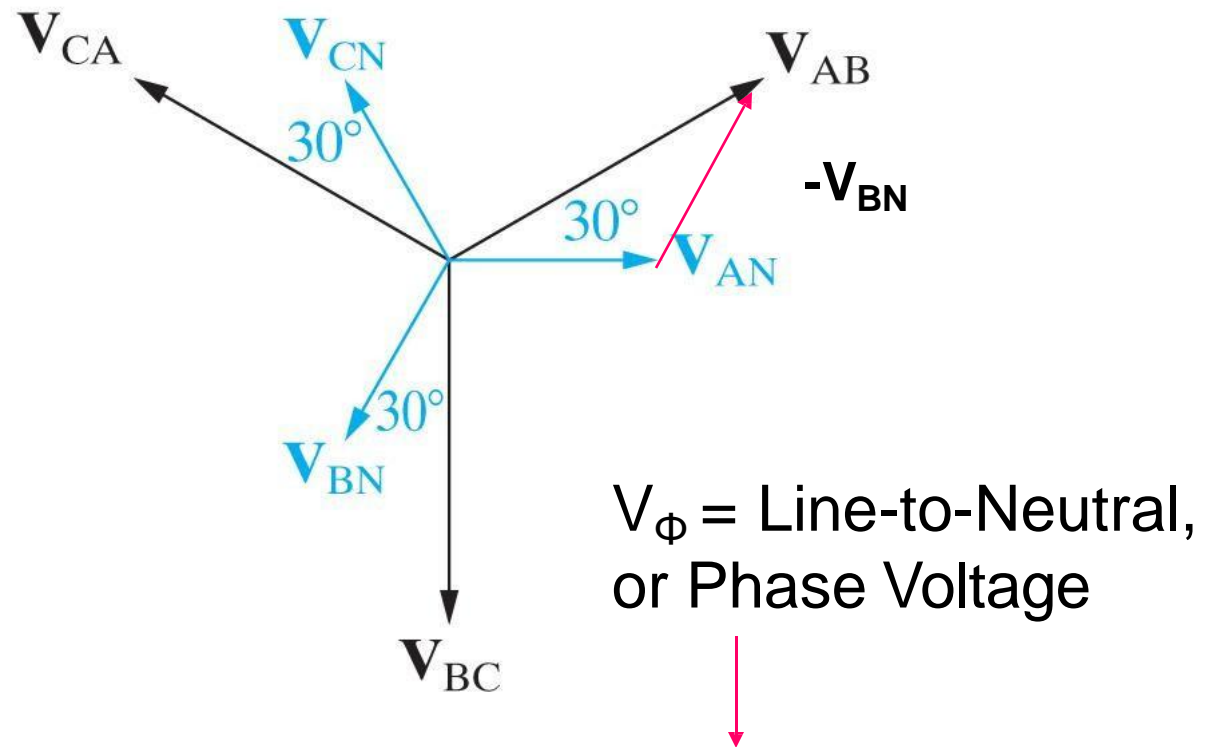
Phase Voltages



Vector addition to find  $V_{AB} = V_{AN} - V_{BN}$



# Using the Tip-to-Tail Method

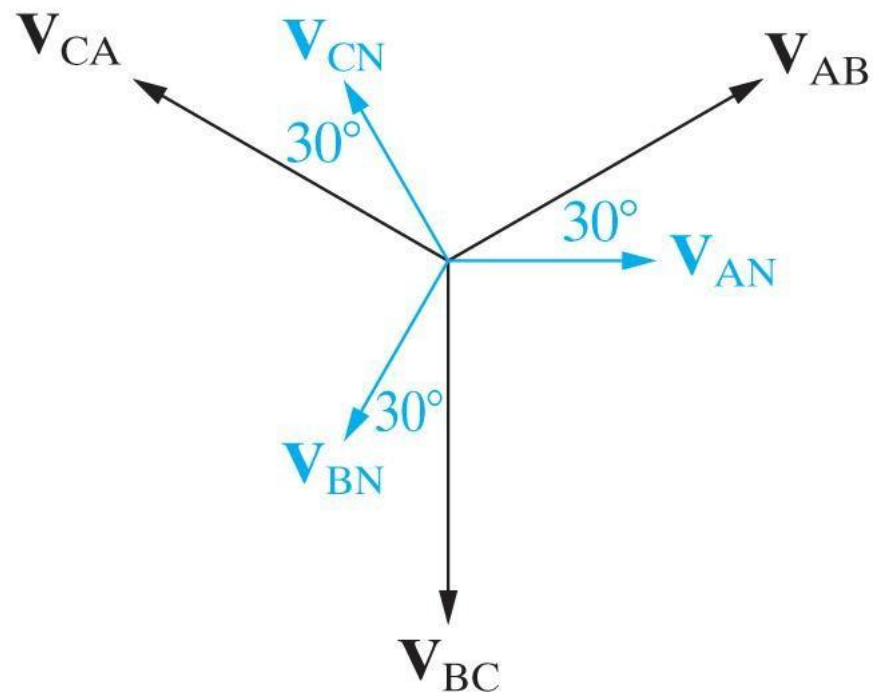


$$V_{AB} = V_{AN} - V_{BN} = \sqrt{3}V_\phi$$

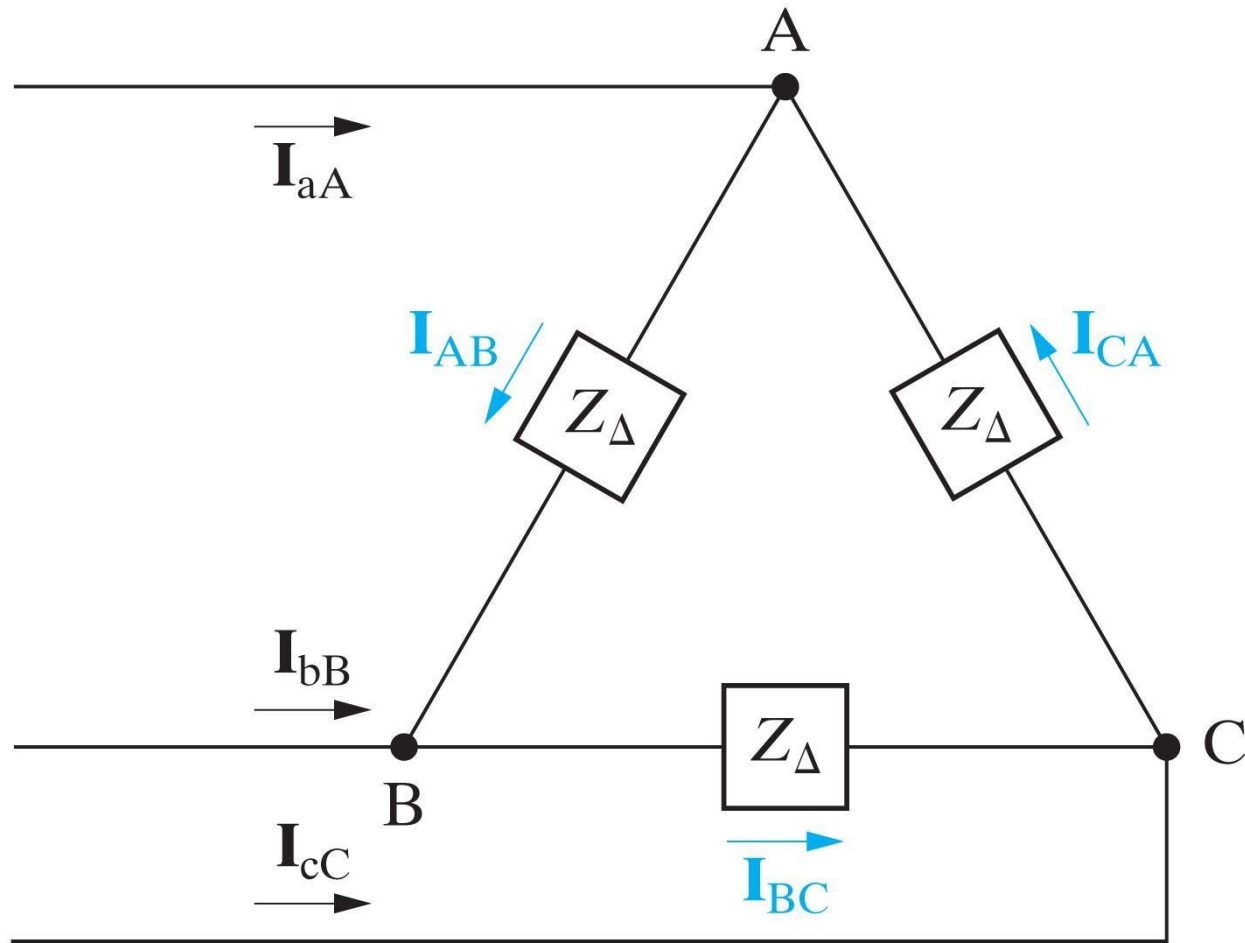
# Conclusions for the Y connection

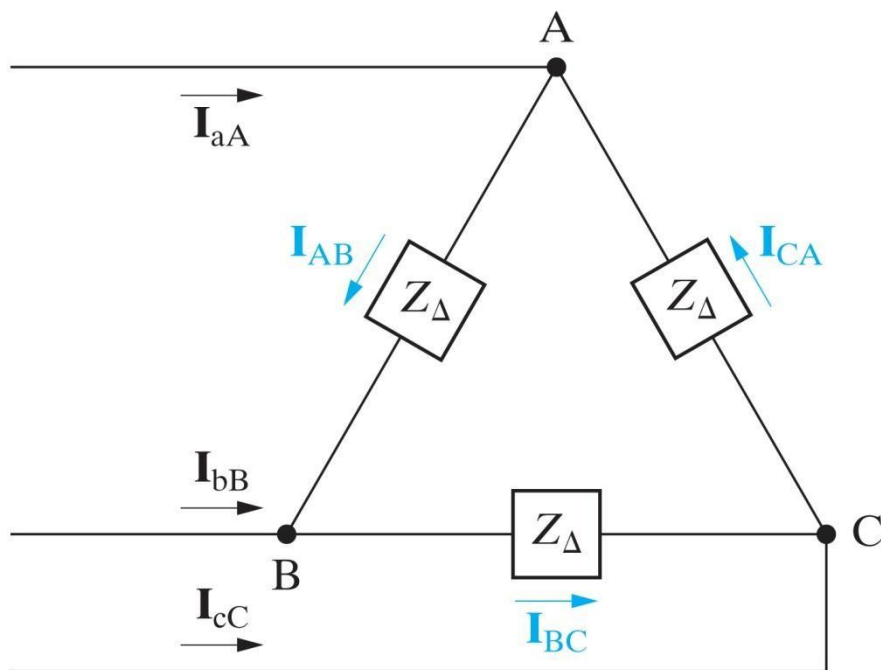
- The amplitude of the line-to-line voltage is equal to  $\sqrt{3}$  times the amplitude of the phase voltage.
- The line-to-line voltages form a balanced set of 3-phase voltages.
- The set of line-to-line voltages leads the set of line-to-neutral (phase) voltages by  $30^\circ$ .

# Summary



# Look at the Delta-Connected Load

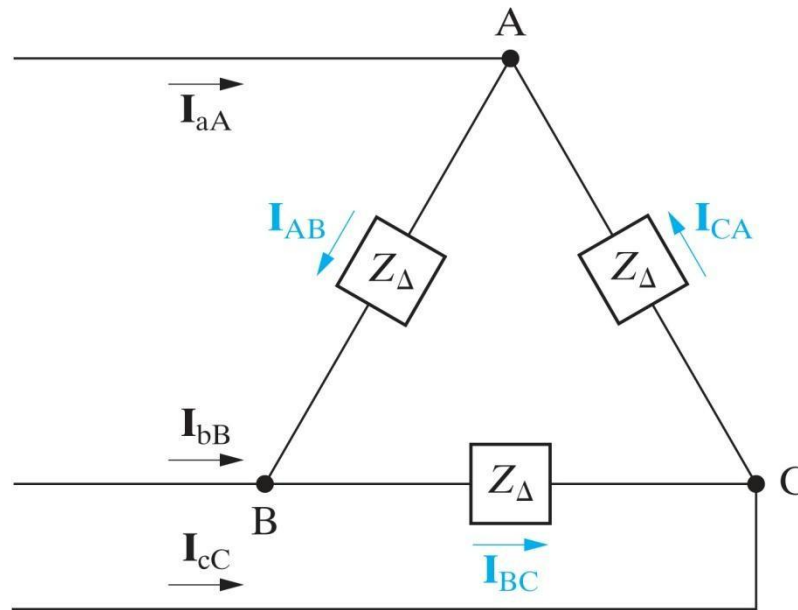




$$I_{AB} = I_{\phi} \angle 0^{\circ}$$

$$I_{BC} = I_{\phi} \angle -120^{\circ}$$

$$I_{CA} = I_{\phi} \angle 120^{\circ}$$



Line Currents

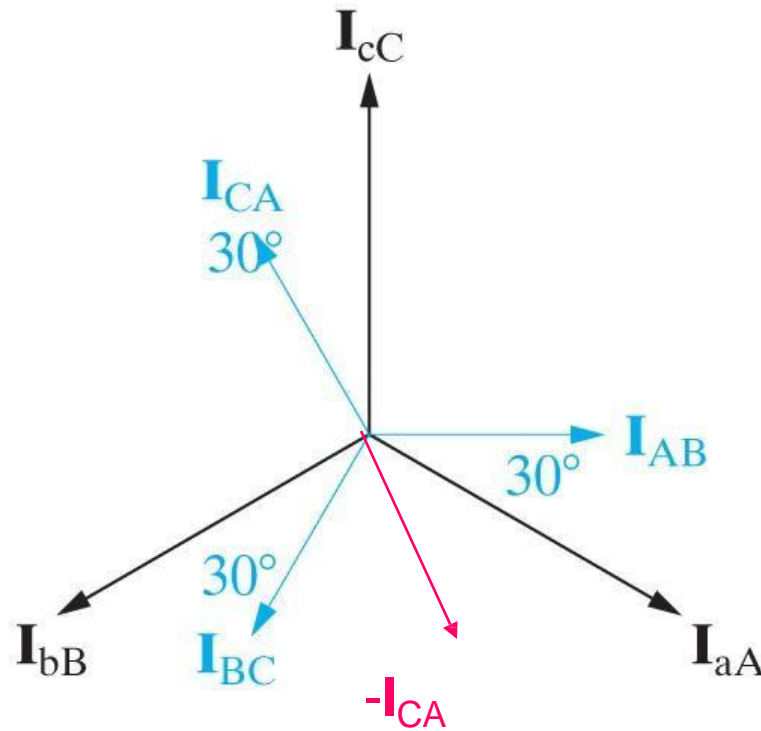
$$I_{aA} = I_{AB} - I_{CA}$$

$$I_{bB} = I_{BC} - I_{AB}$$

$$I_{cC} = I_{CA} - I_{BC}$$

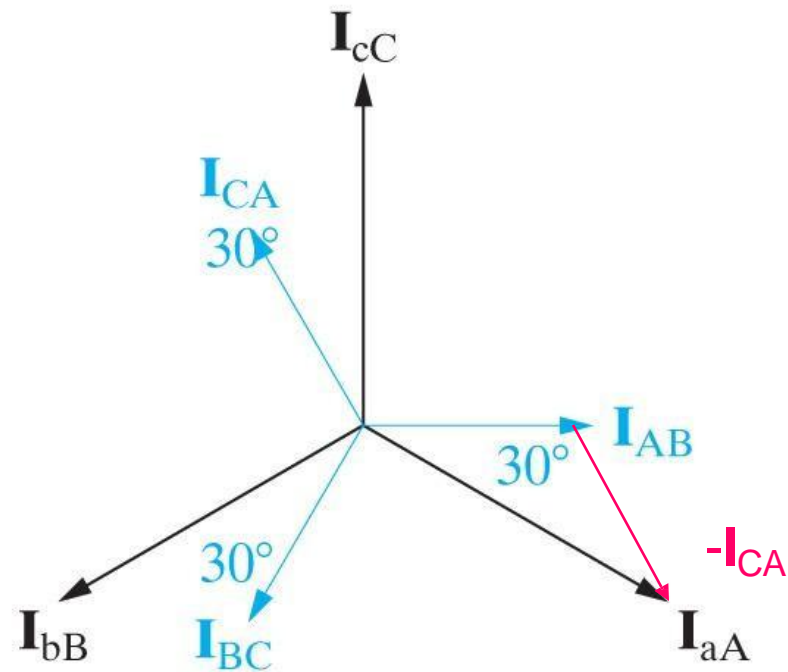
Phase Currents

Vector Addition to find  $I_{aA} = I_{AB} - I_{CA}$





# Using the Tip-to-Tail Method



$$I_{aA} = \sqrt{3}I_{\phi}/-30^\circ$$

# Conclusions for the Delta Connection

- The amplitude of the line current is equal to  $\sqrt{3}$  times the phase current.
- The set of line currents lags the phase currents by  $30^\circ$ .

Fourier analysis deals with the representation of signals by *sinewave* components. The simplest type of Fourier analysis is that of the *Fourier series* where a *periodic* signal  $x(t)$  is represented as a *sum* of sinewaves.

$$x(t) = \sum \text{ sine waves } .$$

The sine waves could be **sin ( )**, **cos ( )** or a *combination* thereof:

$$e^{j(\ )} = \cos(\ ) + j \sin(\ ).$$

The sine wave components in the summation will be a complex sine wave at various frequencies:

$$e^{jn\omega_0 t} \quad n = 0, \pm 1, \pm 2, \dots$$

The complex sinewave frequencies are *integral multiples* of

$$\omega_0 \equiv \frac{2\pi}{T}$$

Where *T* is the *period* of the signal to be represented.

$$x(t) = x(t+T).$$

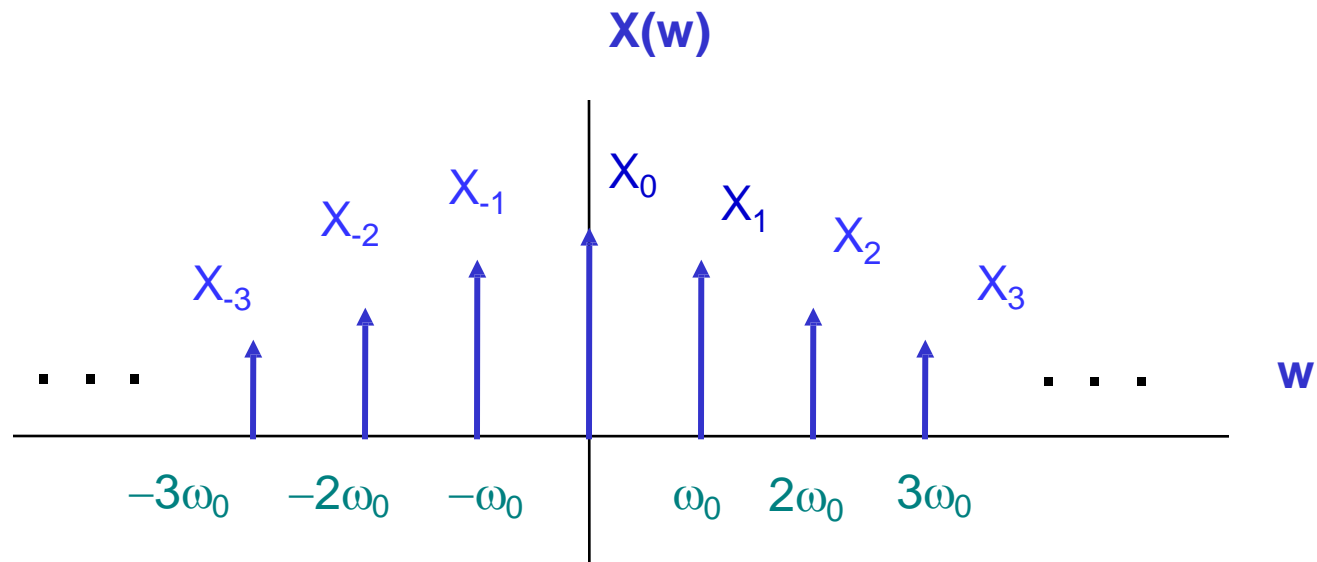
The resultant summation is a *weighted* sum of the complex sinewaves  $e^{jn\omega_0 t}$ :

$$x(t) = \sum_{n=-\infty}^{\infty} X_n e^{jn\omega_0 t},$$

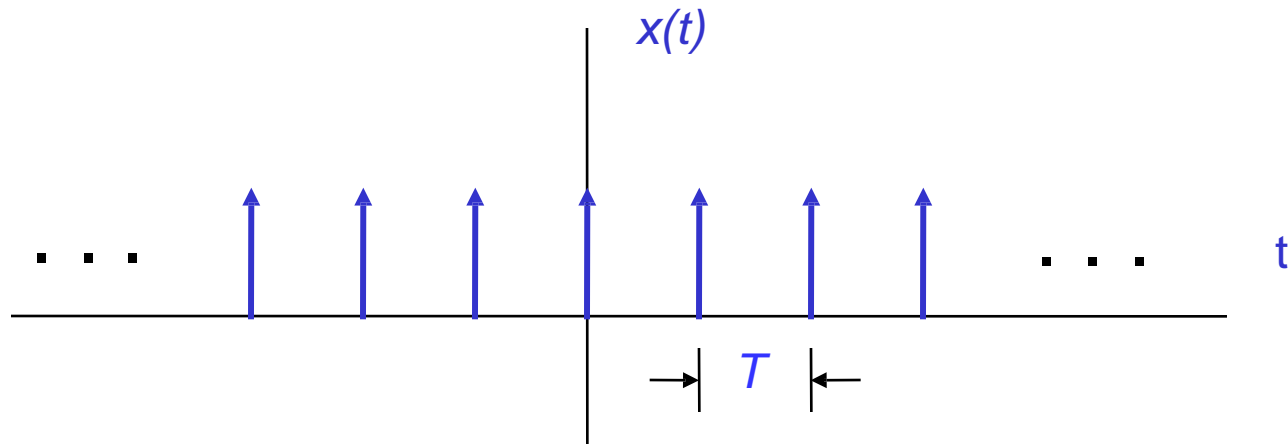
The *weights* or coefficients  $X_n$  are found from

$$X_n = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jn\omega_0 t} dt.$$

The weights  $X_n$  correspond to the *magnitudes* of the frequency components of the *spectrum* of  $x(t)$ .



**Example:** Find the Fourier series for the following function:



$$x(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT).$$



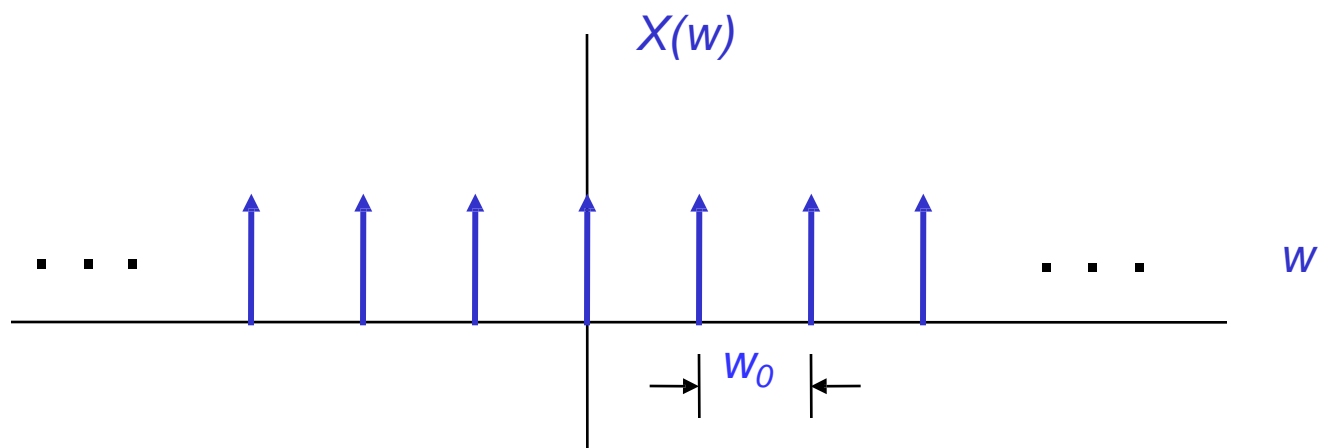
**Solution:** this function is clearly periodic. We calculate the coefficients as follows:

$$\begin{aligned} X_n &= \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jn\omega_0 t} dt \\ &= \frac{1}{T} \int_{-T/2}^{T/2} \delta(t) e^{-jn\omega_0 t} dt \\ &= \frac{1}{T} \int_{-T/2}^{T/2} \delta(t) e^{-jn\omega_0(0)} dt \end{aligned}$$

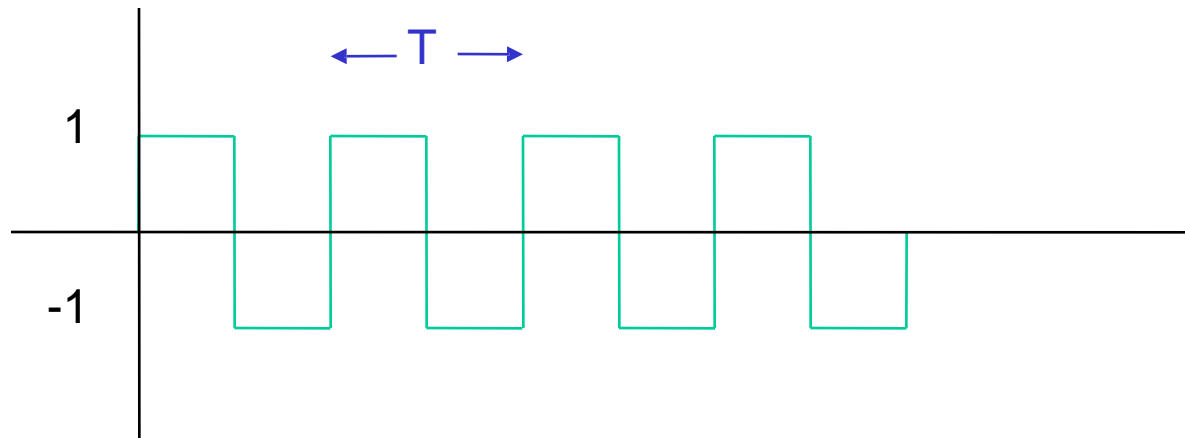
$$\begin{aligned}
&= \frac{1}{T} e^{-jn\omega_0(0)} \int_{-T/2}^{T/2} \delta(t) dt \\
&= \frac{1}{T} (1)(1) = \frac{1}{T}.
\end{aligned}$$

So,

$$x(t) = \sum_{n=-\infty}^{\infty} \frac{1}{T} e^{jn\omega_0 t} = \frac{1}{T} \sum_{n=-\infty}^{\infty} e^{jn\omega_0 t}.$$



**Example:** Find the Fourier series for the following function:



**Solution:** The coefficients are calculated in much the same way as before.

$$\begin{aligned}
X_n &= \frac{1}{T} \int_0^T x(t) e^{-jn\omega_0 t} dt \\
&= \frac{1}{T} \int_0^{T/2} (1) e^{-jn\omega_0 t} dt + \frac{1}{T} \int_{T/2}^T (-1) e^{-jn\omega_0 t} dt \\
&= \frac{1}{T} \frac{1}{(-jn\omega_0)} e^{-jn\omega_0 t} \Big|_0^{T/2} - \frac{1}{T} \frac{1}{(-jn\omega_0)} e^{-jn\omega_0 t} \Big|_{T/2}^T \\
&= \frac{1}{T} \frac{1}{(-jn\omega_0)} \left[ e^{-jn\omega_0 T/2} - e^{-j0} - e^{-jn\omega_0 T} + e^{-jn\omega_0 T/2} \right]
\end{aligned}$$

$$= \frac{1}{T} \frac{1}{(-jn\omega_0)} [e^{-jn\pi} - e^{-j0} - e^{-jn2\pi} + e^{-jn\pi}]$$

$$= \frac{1}{T} \frac{2}{(-jn\omega_0)} [e^{-jn\pi} - e^{-j0}]$$

$$= \frac{1}{T} \frac{2}{(jn\omega_0)} [e^{-j0} - e^{-jn\pi}]$$

$$= \frac{1}{(jn\pi)} [1 - e^{-jn\pi}]$$

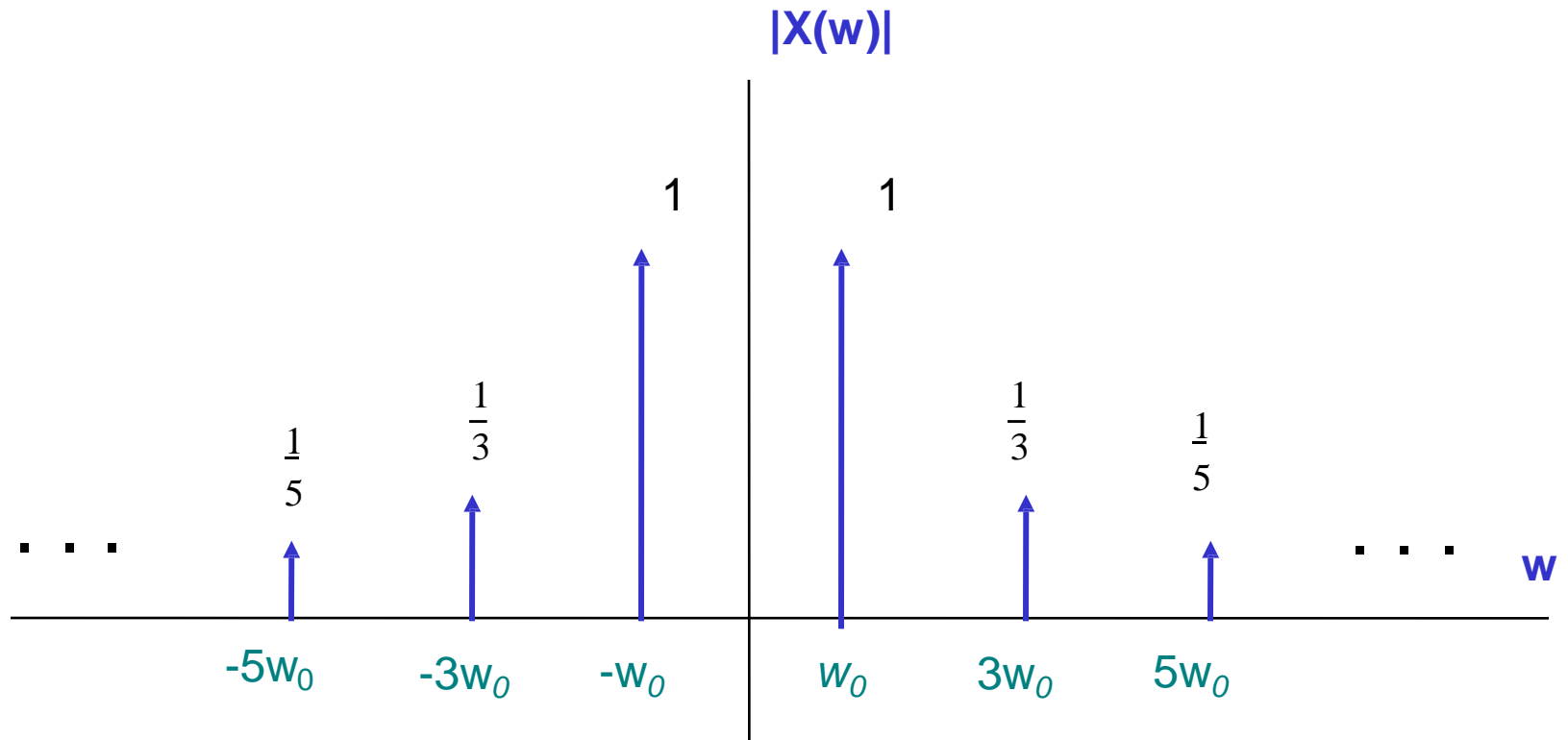
$$= \frac{1}{(jn\pi)} [1 - (-1)^n].$$

$$X_n = \begin{cases} 2 & (n \text{ odd}), \\ j n \pi & \\ 0 & (n \text{ even}). \end{cases}$$

Thus,

$$x(t) = \frac{2}{j \pi} \sum_{\substack{n=-\infty \\ n \text{ odd}}}^{\infty} \frac{1}{n} e^{jn \Omega_0 t}.$$

The spectrum of the square wave is shown below





# Fourier Transforms

Fourier transforms allow the frequency analysis of *non-periodic* as well as periodic functions. The Fourier transformation is derived from Fourier series.

To derive the Fourier transform, let us take the Fourier series, and take the **limit** as  $T \rightarrow \infty$ . As  $T \rightarrow \infty$ , we also have  $\omega_0 \rightarrow 0$  (since  $\omega_0 = 2\pi/T$ ).

If we let  $\omega_0 = \Delta\omega$ ,  $T=2p/w$  and  $c_n T = X(n\Delta\omega)$ , we have

$$X(n\Delta\omega) = \int_{-\infty}^{\infty} x(t) e^{-jn\Delta\omega t} dt.$$

and,

$$x(t) = \lim_{\Delta\omega \rightarrow 0} \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} X(n\Delta\omega) e^{jn\Delta\omega t} \Delta\omega.$$

This last expression is a Riemann sum which is a definite integral:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega,$$

where  $\omega = n\Delta\omega$ . Using this last piece of notation in  $X(n\Delta\omega)$ , we have

$$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt.$$

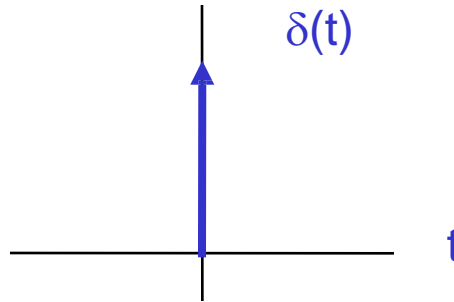
This last expression is the definition of the *Fourier transform* of  $x(t)$ :

$$F\{x(t)\} \equiv X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt.$$

In the process of deriving an expression for the Fourier transform, we have also derived an expression for the *inverse Fourier transformation*:

$$F^{-1}\{X(\omega)\} = x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega.$$

**Example:** find the Fourier transform of a delta function,  $x(t)=\delta(t)$ .



**Solution:** using the definition of the Fourier transform, we have

$$X(\omega) = F\{\delta(t)\} = \int_{-\infty}^{\infty} \delta(t) e^{-j\omega t} dt$$

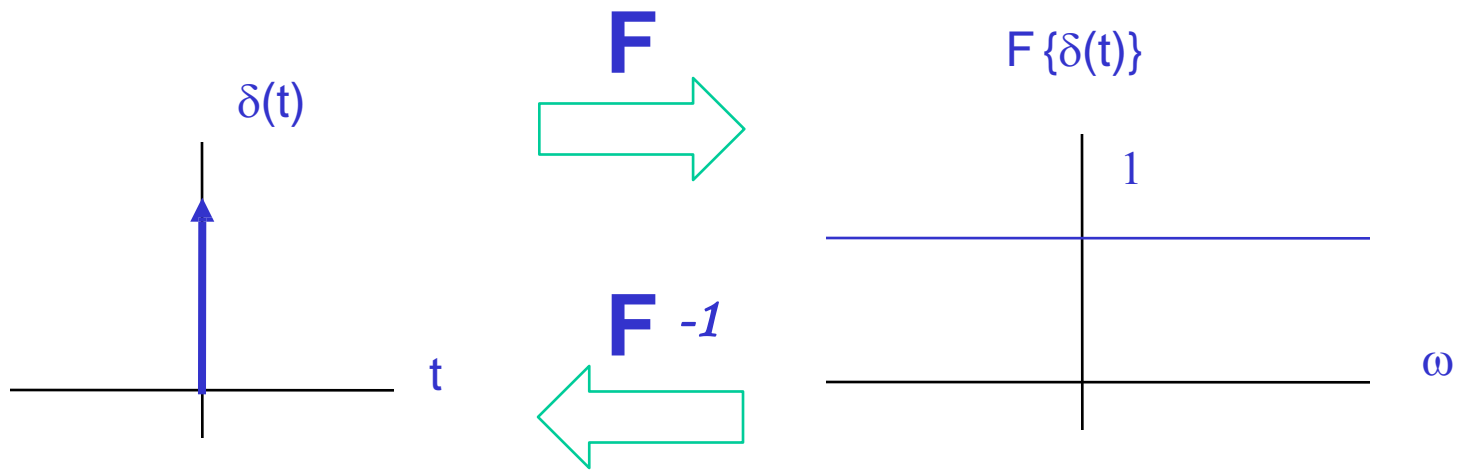
$$\begin{aligned}
&= \int_{-\infty}^{\infty} \delta(t) e^{-j\omega(0)} dt \\
&= e^{-j\omega(0)} \int_{-\infty}^{\infty} \delta(t) dt \\
&= (1)(1) = 1.
\end{aligned}$$

As corollary of this last problem, we have the following: the *inverse* Fourier transformation of one is a delta function:

$$F^{-1}\{1\} = \delta(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega t} d\omega .$$

This will be a *very useful fact* in other Fourier transform derivations.





We know that the Fourier transform of a delta function is one. What is the Fourier transform of one? The answer may be obtained by noticing the *similarities* between the forward transformation and the reverse transformation.

Let us do a few manipulations on the inverse Fourier transformation:

$$F^{-1}\{X(\omega)\} = x(t) = \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega .$$

$$F^{-1}\{X(t)\} = x(\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(t) e^{j\omega t} dt .$$

$$x(-\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(t) e^{-j\omega t} dt .$$

Thus we have the Fourier transform of a Fourier transform:

$$F\{X(t)\} = 2\pi x(-\omega).$$

If we know the forward Fourier transform, we can find the reverse Fourier transform. This property is called **duality**.

Applying this result to the Fourier transform of  $\delta(t)$ , we have

$$F\{1\} = 2\pi \delta(\omega) .$$

A *physical* interpretation can be given to the Fourier transforms of  $\delta(t)$  and  $1$ . The function  $1$  is a D.C. signal whose sole frequency component is 0 Hz. This component is represented by a spike at  $0$  rad/sec in the frequency domain. The function  $\delta(t)$  is like a lighting bolt whose spectrum covers the entire frequency band (from  $f = 0$  to  $\infty$ ).

Suppose we had a function  $x(t)$  whose Fourier transform we know,  $X(\omega)$ . We then wished to know the Fourier transform of a *shifted version* of  $x(t)$ ,  $x(t-a)$ :

$$\begin{aligned} F\{x(t-a)\} &= \int_{-\infty}^{\infty} x(t-a) e^{-j\omega t} dt \\ &= \int_{-\infty}^{\infty} x(t) e^{-j\omega(t+a)} dt \\ &= e^{-j\omega a} \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \\ &= e^{-j\omega a} X(\omega). \end{aligned}$$

Applying this principle to  $\mathcal{F}\{\delta(t)\}$ , we have

$$\mathcal{F}\{\delta(t-a)\} = e^{-j\omega a}.$$

Using duality, we also have

$$\begin{aligned}\mathcal{F}\{e^{jat}\} &= \delta(-\omega - a) \\ &= \delta(\omega + a).\end{aligned}$$

The previous two results could also have been had by *direct* application of the Fourier transform:

$$\begin{aligned} F\{\delta(t-a)\} &= \int_{-\infty}^{\infty} \delta(t-a) e^{-j\omega t} dt \\ &= \int_{-\infty}^{\infty} \delta(t-a) e^{-j\omega a} dt \\ &= e^{-j\omega a} \int_{-\infty}^{\infty} \delta(t-a) dt \\ &= e^{-j\omega a} . \end{aligned}$$

$$\begin{aligned}
 F\{e^{-jat}\} &= \int_{-\infty}^{\infty} e^{-jat} e^{-j\omega t} dt \\
 &= \int_{-\infty}^{\infty} e^{-j(a+\omega)t} dt \\
 &= \delta(\omega+a).
 \end{aligned}$$

The last step is true because of the “very useful fact”:

$$\delta(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega t} d\omega.$$



As a corollary of the previous Fourier transformations, we also have

$$F \{ \delta(t+a) \} = e^{+j\omega a}.$$

$$F \{ e^{+jat} \} = 2\pi \delta(\omega - a).$$

A summary of the Fourier transforms derived so far are shown in the table on the following slide.

$x(t)$	$X(\omega)$
$\delta(t)$	1
1	$2\pi\delta(\omega)$
$\delta(t-a)$	$e^{-j\omega a}$
$e^{jat}$	$2\pi\delta(\omega-a)$

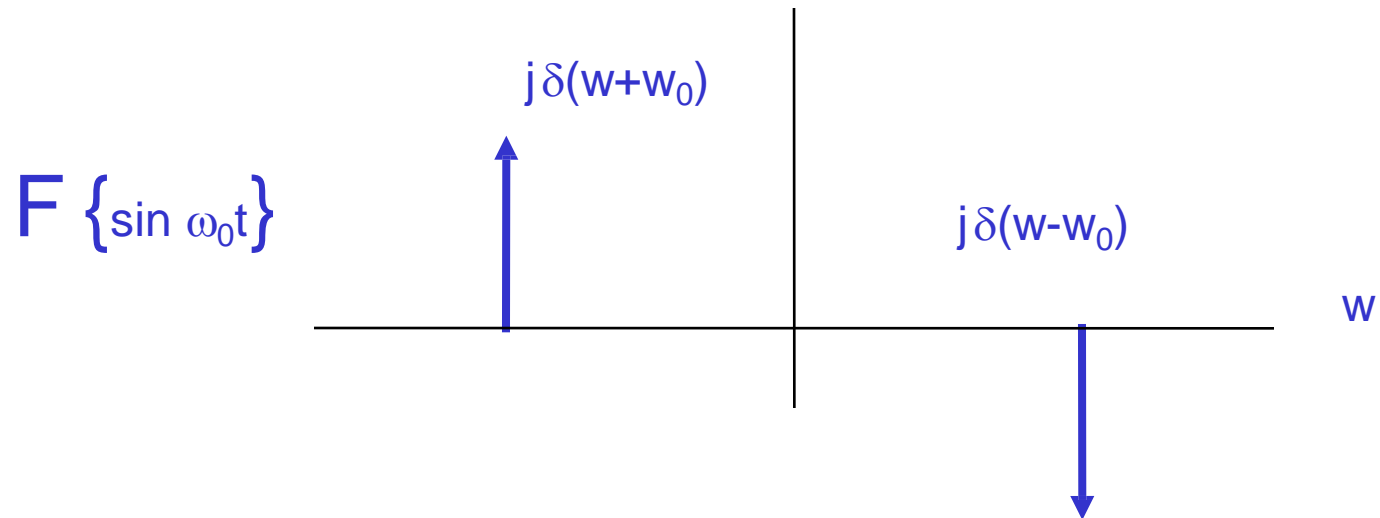
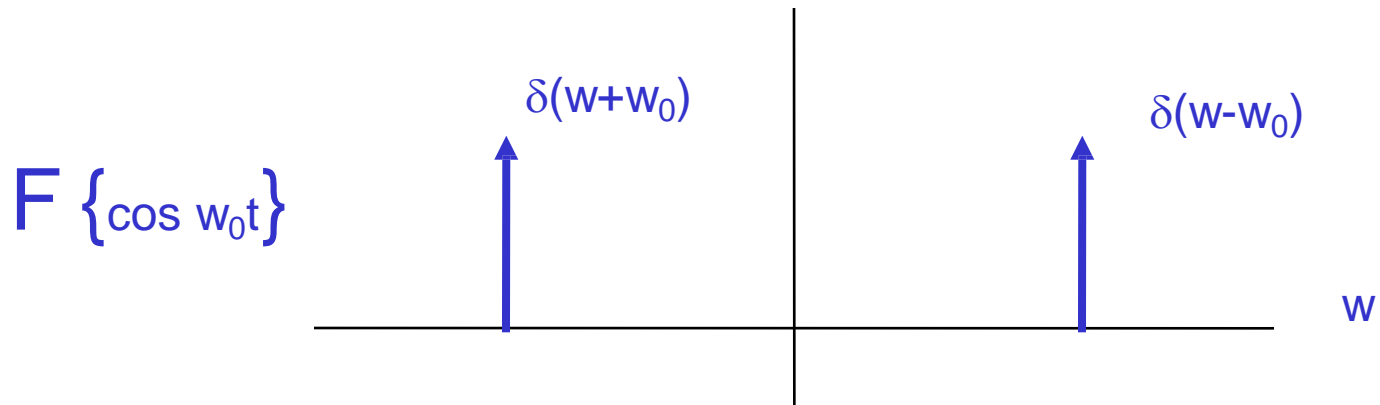
Let's find the Fourier transform of a sinewave:

$$\begin{aligned} F\{\cos \omega_o t\} &= F\left\{\frac{1}{2}\left[e^{j \omega_o t}+e^{-j \omega_o t}\right]\right\} \\ &= \frac{1}{2}\left[F\left\{e^{j \omega_o t}\right\}+F\left\{e^{-j \omega_o t}\right\}\right] \\ &= \frac{2 \pi}{2}\left[\delta\left(\omega-\omega_o\right)+\delta\left(\omega+\omega_o\right)\right] \\ &= \pi\left[\delta\left(\omega-\omega_o\right)+\delta\left(\omega+\omega_o\right)\right]. \end{aligned}$$

Similarly we have

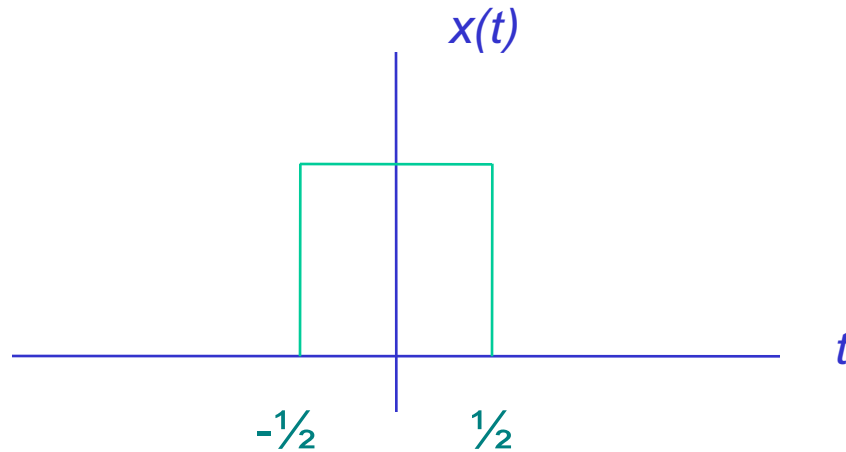
$$\begin{aligned}
 F\{\sin \omega_o t\} &= F\left\{\frac{1}{2j} [e^{j\omega_o t} + e^{-j\omega_o t}]\right\} \\
 &= \frac{2\pi}{2j} [\delta(\omega - \omega_o) - \delta(\omega + \omega_o)] \\
 &= j\pi [\delta(\omega + \omega_o) - \delta(\omega - \omega_o)].
 \end{aligned}$$

The plots of these Fourier transforms are shown below.



The physical interpretation of these transforms should be clear: the spectrum of a sinewave consists of spikes at the frequency of the sinewave along with a spike at the corresponding negative frequency. The (generally complex) coefficients of the spikes depend upon the *phase* of the sinewave.

Now, let's find the Fourier transform of a pulse:



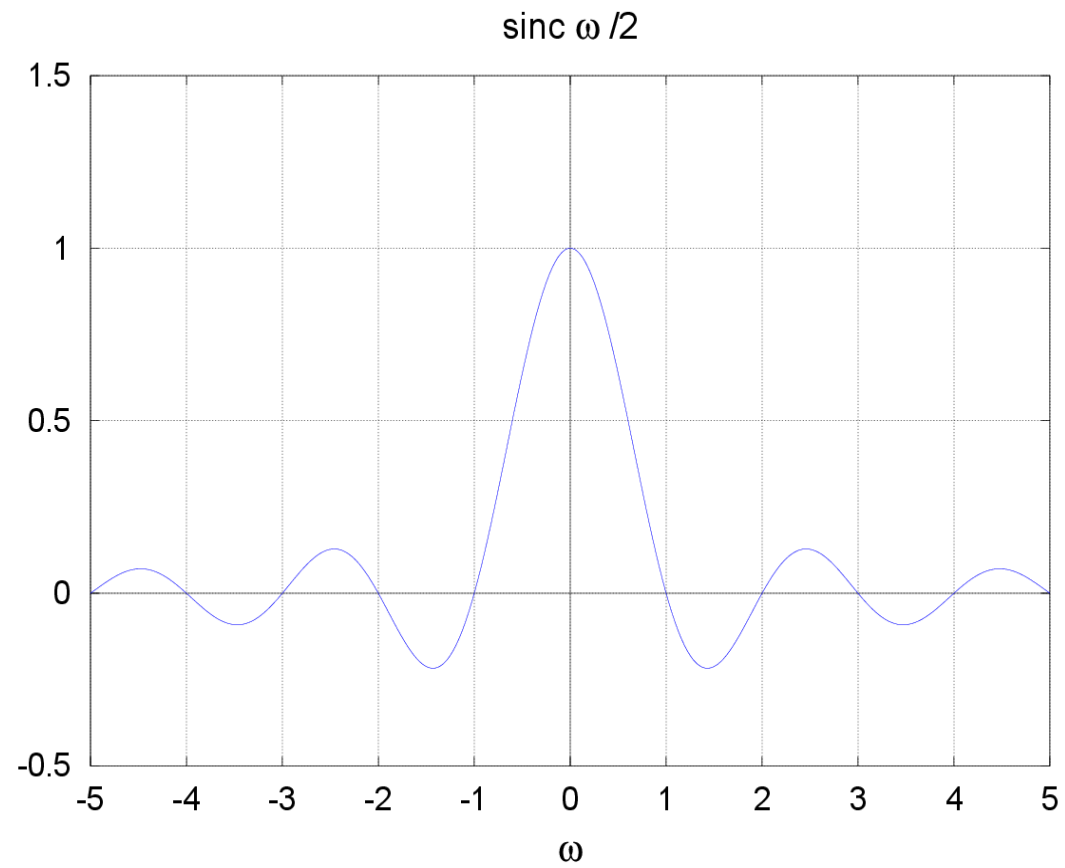
This function is sometimes referred to as  $\Pi(t)$ .

Applying the definition of the Fourier transform, we have

$$\begin{aligned}
F\{\Pi(t)\} &= \int_{-\frac{1}{2}}^{\frac{1}{2}} e^{-j\omega t} dt \\
&= \frac{1}{-j\omega} e^{-j\omega t} \Big|_{-\frac{1}{2}}^{\frac{1}{2}} \\
&= \frac{1}{j\omega} [e^{j\omega/2} - e^{-j\omega/2}] \\
&= \frac{1}{2j\frac{\omega}{2}} [e^{j\omega/2} - e^{-j\omega/2}] \\
&= \frac{\sin \frac{\omega}{2}}{\frac{\omega}{2}} \equiv \text{sinc} \frac{\omega}{2}.
\end{aligned}$$

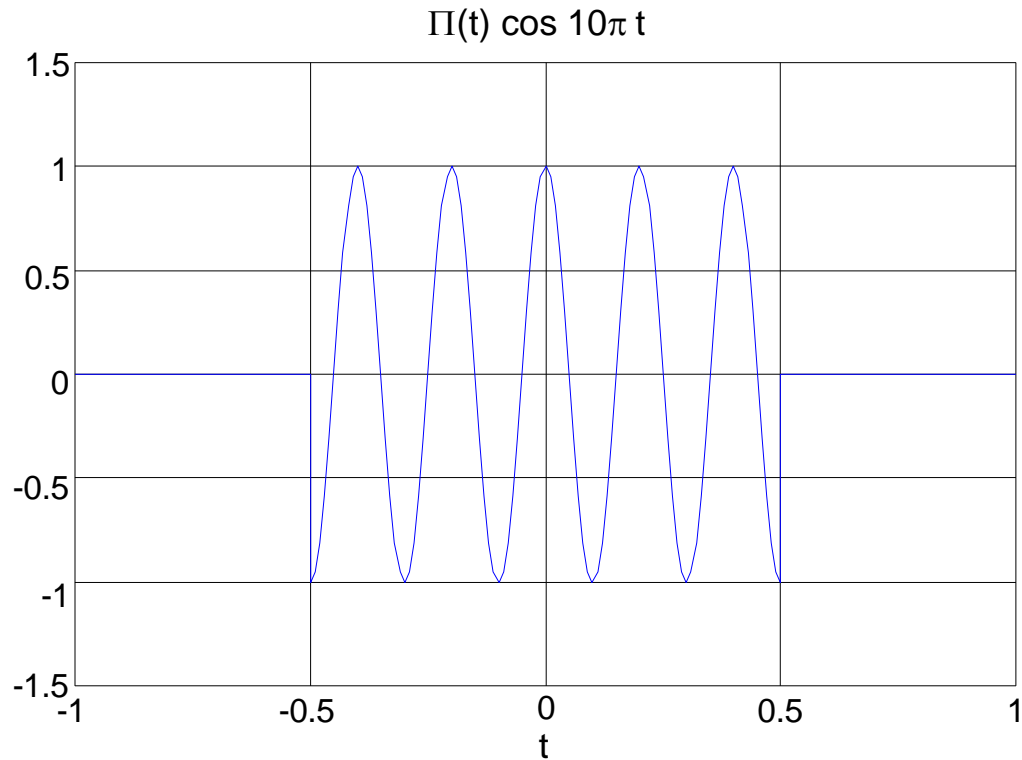


A plot of this function is shown below:



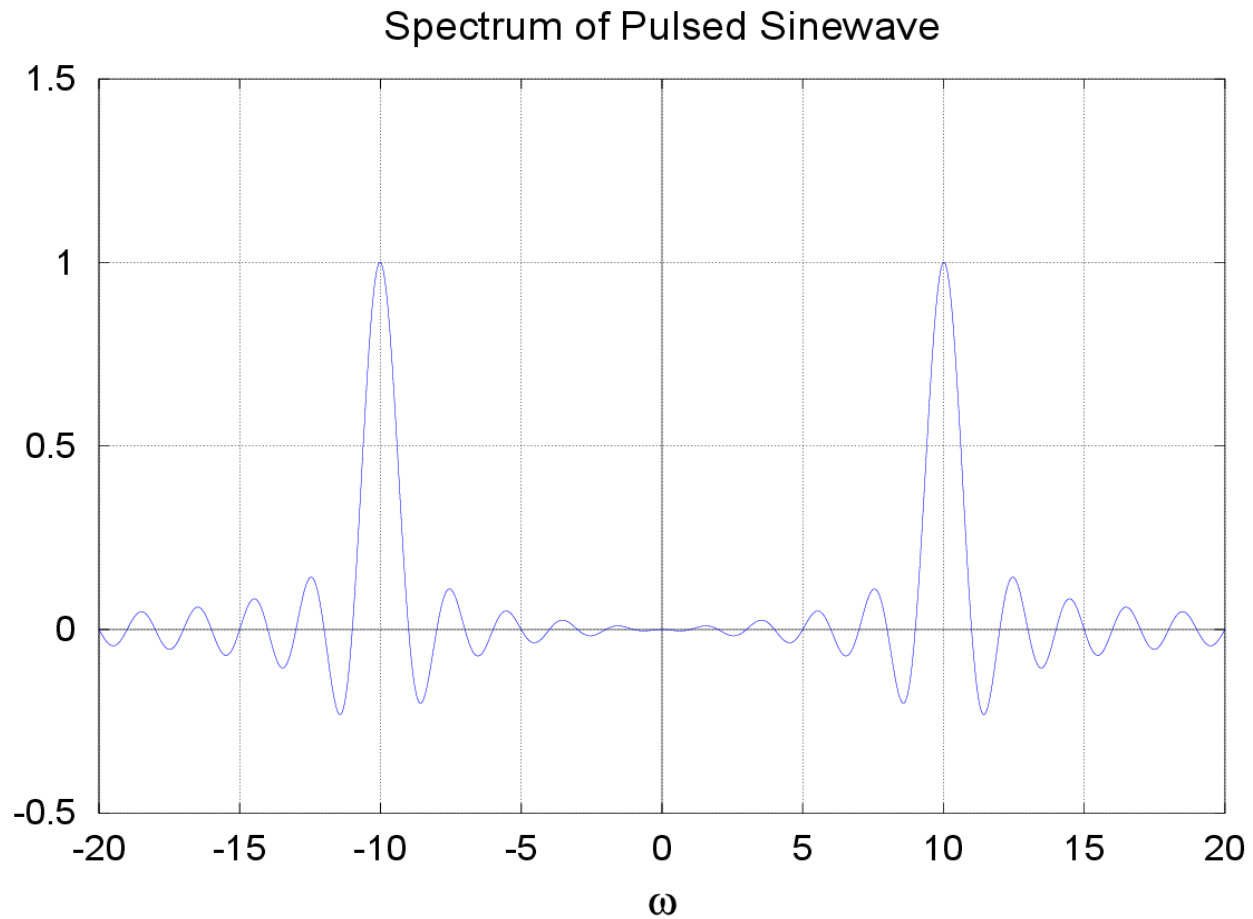
Now, let's find the Fourier transform of a *pulsed* sinewave:

$$x(t) = \Pi(t) \cos 10\pi t.$$



$$\begin{aligned}
F\{\Pi(t)\cos 10t\} &= \frac{1}{2} \int_{-\frac{1}{2}}^{\frac{1}{2}} (e^{j10\pi t} + e^{-j10\pi t}) e^{-j\omega t} dt \\
&= \frac{1}{2} \int_{-\frac{1}{2}}^{\frac{1}{2}} (e^{-j(\omega-10)t} + e^{-j(\omega+10)t}) dt \\
&= \frac{1}{2} \text{sinc}(\omega-10) + \frac{1}{2} \text{sinc}(\omega+10).
\end{aligned}$$

A plot of this function is shown below:



**Exercise:** find the Fourier transform of the following *pulsed* sine wave:

$$x(t) = \Pi\left(\frac{t}{20}\right) \sin 100\pi t.$$