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INSTITUTE OF AERONAUTICAL ENGINEERING

(Autonomous)

Dundigal-500043, Hyderabad

B.Tech VII SEMESTER END EXAMINATIONS (REGULAR) - DECEMBER 2023

Regulation: UG-20

INSTRUMENTATION AND CONTROL SYSTEMS

Time: 3 Hours

(MECHANICAL ENGINEERING)

Max Marks: 70

Answer ALL questions in Module I and II

Answer ONE out of two questions in Modules III, IV and V

All Questions Carry Equal Marks

All parts of the question must be answered in one place only

MODULE – I

- (a) Draw the block diagram representation of a generalised measurement system. Identify the various elements and point out the function performed by each element.
[BL: Understand| CO: 1|Marks: 7]
- (b) Distinguish between the following
 - Accuracy and Precision
 - Resolution and Threshold
 - Reproducibility and Repeatability
 - Dead zone and Hysteresis[BL: Understand| CO: 1|Marks: 7]

MODULE – II

- (a) Illustrate the construction, working and theory of Bourdon tube for measurement of pressures.
[BL: Understand| CO: 2|Marks: 7]
- (b) Discuss how displacement can be measured with the help of an inductive and capacitive transducer. Give the essential features of construction of these two types of electrical transducer.
[BL: Understand| CO: 2|Marks: 7]

MODULE – III

- (a) Give the constructional details and explain the working of a cryogenic fuel level indicator.
[BL: Understand| CO: 3|Marks: 7]
- (b) Enumerate the principle of operation, construction details, advantages and limitations of hotwire anemometer.
[BL: Understand| CO: 3|Marks: 7]
- (a) Explain the different methods adopted for the calibration of accelerometers. Differentiate between contact and non-contact type tachometer.
[BL: Understand| CO: 4|Marks: 7]
- (b) Illustrate with neat sketch the working of reed type vibrometer and indicate its applications, advantages and limitations.
[BL: Understand| CO: 4|Marks: 7]

MODULE – IV

5. (a) Discuss in detail the working of various types of dynamometers used for force measurement. [BL: Understand| CO: 5|Marks: 7]
- (b) Explain the method of usage of resistance strain gauge for bending compressive and tensile strains. [BL: Understand| CO: 5|Marks: 7]
6. (a) Summarize how a sling psychrometer is used to determine the dry and the wet bulb temperatures. [BL: Understand| CO: 5|Marks: 7]
- (b) A rectangular rosette is mounted on a steel plate having $E=200\text{Gn/m}^2$ and Poisson's ratio is 0.3. The three strains measured are $\epsilon_1 = 172 \times 10^{-6}$, $\epsilon_2 = 120 \times 10^{-6}$, $\epsilon_3 = 248 \times 10^{-6}$ calculate the principal strains and stresses, the maximum shear stress and orientation angle for principal axis. [BL: Apply| CO: 5|Marks: 7]

MODULE – V

7. (a) Illustrate the working of servomechanism and mention its applications. Compare pneumatic control systems with hydraulic control systems. [BL: Understand| CO: 6|Marks: 7]
- (b) With the help of a suitable example explain the use of block diagrams for analyzing the performance of a system. [BL: Understand| CO: 6|Marks: 7]
8. (a) Classify the elements in control system. Explain about position control systems with neat sketch. [BL: Understand| CO: 6|Marks: 7]
- (b) Distinguish between manual control system and automatic control systems. Outline the applications of control systems with respect to governing of speed. [BL: Apply| CO: 6|Marks: 7]

