Hall Ticket No								Que	estion Paper Code: AAEB49	
INSTITUTE OF AERONAUTICAL ENGINEERING										
EU CP.10. FOR LIBERT	(Autonomous) (Dundigal-500043, Hyderabad)									
B.Tech VII SEMESTER END EXAMINATIONS (REGULAR) - FEBRUARY 2022 Regulation: R18 AUTOMATIC CONTROL OF AIRCRAFT										
Time: 3 Hours						(AE)			Max Marks: 70	
(NOTE: P	rovi	sion i	is give All	n to an Questi	swer ions	r TWC Carry) que Equ	estions from a al Marks	each module any ONE module)	
All Questions Carry Equal Marks All parts of the question must be answered in one place only										

$\mathbf{MODULE}-\mathbf{I}$

1. (a) Discuss about drone radio control system with neat diagram and operation range. [7M]

(b) Explain the advance visual docking guidance system used for airplane and missiles. How these both differs from each other? [7M]

2. (a) Compare the merits and demerits of feedback control systems in comparison to open loop control.
[7M]

(b) Illustrate the aircraft homing system and discuss each element of the homing system with suitable operating principle. [7M]

$\mathbf{MODULE}-\mathbf{II}$

- 3. (a) Discuss application of feedback in stability augmentation system. Illustrate block diagram of Fuzzy control law for stability augmentation system. [7M]
 - (b) Identify the ten components related to flight control system and explain three of them with their functions and principles. [7M]
- 4. (a) How control augmentation system eliminates the problems in stability augmentation system? Discuss with suitable examples. [7M]
 - (b) Discuss wide area augmentation system (WAAS) for civilaviation navigation. What types of navigation this system does? [7M]

$\mathbf{MODULE}-\mathbf{III}$

- 5. (a) Explain about moment equation in an airplane. Write moment equations in all the three axes and explain each term and give some examples. [7M]
 - (b) Describe the pitch orientation control system and acceleration control system of auto pilot with block diagram. [7M]
- 6. (a) Discuss in detail about flight path stabilization and longitudinal control law design using back stepping algorithm. [7M]
 - (b) Develop the block diagram of the basic autopilot used for the analysis withrootlocus for inner loopsystem. [7M]

$\mathbf{MODULE}-\mathbf{IV}$

- 7. (a) Describe about yaw orientation control system with block diagram and explain each block element with its application and analyze its result. [7M]
 - (b) Discuss about auto pilot modes. Name two modes and explain each with suitable diagram.

[7M].

- 8. (a) Explain in detail about damping of the dutch roll of the aircraft during flight. How lateral autopilot is helpful to counter this effect? [7M]
 - (b) What are the controls managed by single axis autopilot? "Auto pilot is every where" discuss about this statement. [7M]

$\mathbf{MODULE}-\mathbf{V}$

- 9. (a) Describe in detail about fly-by-wire flight control features and advantages. [7M]
 - (b) Show with the block diagrams of the control laws and write its equation related to rudder, aileron and elevator deflection. [7M]
- 10. (a) Explain the methods for flight path angle rate command/ Hold algorithm. How this reduces the work load of the pilot? [7M]
 - (b) Demonstrate the self-adaptive autopilot and the philosophy behind the controlling of the airplane giving suitable sketch with all elements. [7M]

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